# Wiener-Hopf Parametrization of Possibly Non-Invertible SVARMA Models

Bernd Funovits

University of Helsinki and TU Wien

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#### Non-Invertible SVARMA

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Impulse Response Functions and Productivity Example 1

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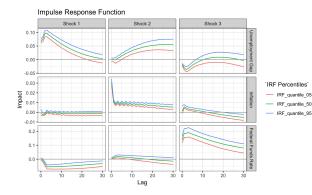
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# Impulse Response Function (IRF)

- Trace out the response of an economic variable of interest with respect to true underlying economic shocks
  - Important part of macroeconomic analysis since "Sims (1980): Macroeconomics and Reality"



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# Reconstructing Shocks from IRF

## Example: Productivity $y_t = \varepsilon_t + b\varepsilon_{t-1}$

- $\varepsilon_t$  = Shock on productivity (i.i.d.)
  - Underlying true economic shock
- ▶ b > 1: Maximal impact occurs with lag
- 1. Can we **reconstruct** the shocks from present and past observables? No!

$$\varepsilon_t = y_t - b\varepsilon_{t-1} = y_t - by_{t-1} + b^2\varepsilon_{t-2} = \cdots$$

2. Reconstruct true underlying shock from future observables? Yes!  $\varepsilon_t = \frac{1}{b} \sum_{j=1}^{\infty} \left(-\frac{1}{b}\right)^j y_{t+j}$ 

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# Structural Vector Autoregressive Moving Average Models

$$\underbrace{\left(I_n - a_1 z - \dots - a_p z^p\right)}_{=a(z)} y_t = \underbrace{\left(b_0 + b_1 z + \dots + b_q z^q\right)}_{=b(z)} B\varepsilon_t,$$
(1)

- ▶ Stable AR polynonmial: det  $(a(z)) \neq 0$  for all  $|z| \leq 1$
- Possibly non-invertible MA polynomial: det (b(z)) ≠ 0 for all |z| = 1
  - ▶ b<sub>0</sub> may be singular, identifiability conditions on factorised b(z)
- $(\varepsilon_t)$  independent across time, non-Gaussian, independent in cross-section with  $\mathbb{E}(\varepsilon_t) = 0$  and  $\mathbb{E}(\varepsilon_t \varepsilon'_s) = \delta_{ts} \text{diag}(\sigma_1, \dots, \sigma_n) = \delta_{ts} \Sigma$
- $(B, \Sigma)$  jointly identified (signed permutations)

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# Parametrization for Possibly Non-Invertible SVARMA

"Past" p(z): All zeros outside the unit circle

$$b(z) = \left[p(z)\underbrace{\operatorname{diag}\left(z^{\kappa+1},\ldots,z^{\kappa+1},z^{\kappa},\ldots,z^{\kappa}\right)}_{=s(z)}f(z)\right]B\varepsilon_{t}$$

- stable polynomial in z, i.e. det (p(z)) ≠ 0 for all |z| ≤ 1; all zeros outside the unit circle
- Zero and one restrictions to obtain uniqueness

$$p(z) = \begin{pmatrix} I_k & 0_{k \times (n-k)} \\ p_{0,21} & I_{n-k} \end{pmatrix} + \begin{pmatrix} p_{1,11} & 0_{k \times (n-k)} \\ p_{1,21} & p_{1,22} \end{pmatrix} z + \cdots$$
$$\cdots + p_{q-\kappa-1} z^{q-\kappa-1} + \begin{pmatrix} 0_{k \times k} & p_{q-\kappa,12} \\ 0_{(n-k) \times k} & p_{q-\kappa,22} \end{pmatrix} z^{q-\kappa}$$

►  $(a_{\rho}, [p_{[q-\kappa-1,\bullet1]} \quad p_{[q-\kappa,\bullet2]}])$  of full rank

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# Parametrization for Possibly Non-Invertible SVARMA

"Future" f(z): All zeros inside the unit circle

$$f(z) = f_0 + f_1 z^{-1} + \dots + \begin{pmatrix} f_{\kappa, [1:k,\bullet]} \\ f_{\kappa, [k+1:n,\bullet]} \end{pmatrix} z^{-\kappa} + \begin{pmatrix} f_{\kappa+1, [1:k,\bullet]} \\ 0_{(n-k)\times n} \end{pmatrix} z^{-\kappa-1}$$

- stable polynomial in <sup>1</sup>/<sub>z</sub>: det (f (<sup>1</sup>/<sub>z</sub>)) ≠ 0 for all |z| ≤ 1; all zeros inside the unit circle
- ▶ f<sub>0</sub> of full rank
  - Natural normalization:  $f_0 = I_n$
  - Unnatural normalization:  $b_0 = I_n$ , implying

$$p_0^{-1} = \begin{pmatrix} f_{\kappa+1,[1:k,\bullet]} \\ f_{\kappa,[k+1:n,\bullet]} \end{pmatrix} = \begin{pmatrix} I_k & 0_{k\times(n-k)} \\ -p_{0,21} & I_{n-k} \end{pmatrix}$$

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# Parametrization for Possibly Non-Invertible SVARMA

"Shifts" s(z) with partial indices  $(\kappa, k)$ 

$$a(z) = \left[ p(z) \underbrace{\operatorname{diag} \left( z^{\kappa+1}, \dots, z^{\kappa+1}, z^{\kappa}, \dots, z^{\kappa} \right)}_{=s(z)} f(z) \right] B\varepsilon_t$$

### Unique

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# Identifiability

# Connect External Characteristics Uniquely to Internal Characteristics

- Is there an injective function from the (deep) parameters to the observed aspects of the stochastic process?
- Is it possible to deduce the internal characteristics from the external ones?

### Here

- Second moment information (spectral density) does not allow for identification of root location and the static shock transmision matrix.
- Higher order spectral densities do (under assumptions)!

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# Assumptions on Input Shocks

## (a) Non-zero cumulants

Components of  $\varepsilon_t$  are **mutually independent** (not necessarily i.i.d.), have a **non-zero cumulant** of order  $r \ge 3$  and **finite moments up to order**  $\tau$ , where  $\tau > r$  is even.

## (b) Non-Gaussian i.i.d.

Components of  $\varepsilon_t$  are i., identically, d., and non-Gaussian.

## Theorem (Chan, Ho, Tong (2004, 2006))

Under (a) or (b), the deep parameters in  $(a(z), p(z)s(z)f(z), B, \Sigma)$  are identifiable up to signed permutations of B.

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## Literature: Univariate

- Deconvolution using entropy methods: Wiggins (1978), Donoho (1981), Gassiat (1993)
- Andrews, Breidt, Davis, Lii, Rosenblatt (1982-2007+): Deconvolution, MLE for non-Gaussian, non-invertible ARMA, MLE for non-causal AR, rank-based estimation of all-pass models etc
  - Rosenblatt's 2000 book "Gaussian and Non-Gaussian Linear Time Series and Random Fields"
- Gouriéroux, Zakoian (2015, JTSA): On uniqueness of MA representations of heavy-tailed stationary processes
- Velasco, Lobato (2019, Annals): Non-causal and non-invertible ARMA using polyspectra

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## Literature: Multivariate

- Chan, Ho, Tong (2004, 2006, Biometrika): Uniqueness of two-sided multivariate non-Gaussian moving average processes
- Lanne, Saikkonen (2013, ET): Non-causal VAR
- GMR = Gouriéroux, Monfort, Renne (2019, ReStud): Identification and Estimation in Non-Fundamental SVARMA Models
- Velasco (2020): Non-invertible SVARMA Polyspectra approach
  - Similar problems as GMR but still a working paper
  - Multivariate version of the univariate objective function in VL19

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# Funovits (2020, arxiv): Comment on GMR

- Bivariate VARMA(p,1)
- $b_0 = I_2$  excludes zeros at zero (corresponding to delays)
- Estimates 2<sup>n·q</sup> models via root flipping, similar to the approach presented at TU Dortmund in Jan 2017
  - WHF approach estimates  $n \cdot q$  models
- Ignores deliberately complex-conjugated roots
  - Leaves real-valued parameter space
  - Non-trivial problem, see Scherrer, Funovits (2020, arxiv)

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Identifiability Problem and Solution From Spectral Density to Spectral Factor From MA Polynomial to (Unique) WHF

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# External Characteristics: Second Moment Information

## Autocovariance Function $\gamma(s)$ of $(y_t)$

$$\gamma(s) = Cov\left(y_{t+s}y_t'
ight)$$

## Spectral density of $(y_t)$

$$F(z) = \frac{1}{2\pi} \sum_{s=-\infty}^{\infty} \gamma(s) z^s, \quad z = e^{-i\lambda}$$
$$= \frac{1}{2\pi} a(z)^{-1} b(z) b'\left(\frac{1}{z}\right) a^{-1'}\left(\frac{1}{z}\right), \quad z = e^{-i\lambda}$$

Same information as autocovariances  $\gamma(s) = \mathbb{E}(y_{t+s}y'_t)$ , but sometimes easier to manipulate

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# Overview: From External to Internal Characteristics

- 1. From (full rank) rational spectral density f(z) to true spectral factor l(z) such that  $f(z) = l(z)l'(\frac{1}{z})$  holds.
- From (normalized) spectral factor k(z) to polynomial matrix fraction description (a(z), b(z)) such that l(z) = a(z)<sup>-1</sup>b(z)BΣ with
- From MA polynomial matrix (b(z), B, Σ) to
   Wiener-Hopf factorization ((p(z), s(z), f(z)), B, Σ)

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# Observationally Equivalent Spectral Factors

For a given (observed) rational spectral density, there are many spectral factors:

MA(1): 
$$y_t = \varepsilon_t + 3\varepsilon_{t-1}$$
 or  $y_t = \tilde{\varepsilon}_t + \frac{1}{3}\tilde{\varepsilon}_{t-1}$ ?

$$\begin{aligned} \sigma(z) &= (1+3z)\sigma^2 \left(1+\frac{3}{z}\right) = \\ &= \left(\frac{1}{3z}+1\right)3z\sigma^2\frac{3}{z}\left(\frac{z}{3}+1\right) \\ &= \left(1+\frac{z}{3}\right)\left[9\sigma^2\right]\left(1+\frac{1}{3z}\right) \end{aligned}$$

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Solution of Dynamic Identifiability Problem "Time-equivalent" of Orthogonal Matrices: All-Pass Filters

In the same way as  $QQ' = I_n$  for orthogonal matrices Q it holds for all-pass filters that

$$T(z)T'\left(\frac{1}{z}\right) = I_{r}$$

► 
$$t(z)t\left(\frac{1}{z}\right) = \left[\frac{1-3z}{z-3}\right]\frac{1-3\frac{1}{z}}{\frac{1}{z}-3} = \left[\frac{1-3z}{z-3}\right]\frac{\frac{1}{z}(z-3)}{\frac{1}{z}(1-3z)} = 1$$

All-pass filters are "dynamic rotations"

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# Solution of Dynamic Identifiability Problem Third Order Cumulants

## Cumulant Function

$$\gamma^{(3)}(r,s) = Cumu\left(y_{t+r}y_{t+s}y_t
ight)$$

## Cumulant based bispectral density

$$f^{(3)}\left(e^{-i\lambda_1}, e^{-i\lambda_2}\right) = \left(\frac{1}{2\pi}\right)^2 \sum_{r,s=-\infty}^{\infty} \gamma^{(3)}(r,s) e^{-i(r\lambda_1+s\lambda_2)}$$

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Solution of Dynamic Identifiability Problem Example: Blaschke factor  $t(z) = \frac{1-3z}{z-3}$ 

Spectral density of  $y_t = t(z)\varepsilon_t$  is constant!

$$f\left(e^{-i\lambda}\right) = rac{1-3e^{-i\lambda}}{e^{-i\lambda}-3}rac{1-3e^{i\lambda}}{e^{i\lambda}-3} \equiv 1$$

## Bispectral density of $y_t = t(z)\varepsilon_t$

$$f^{(3)}\left(e^{-i\lambda_{1}}, e^{-i\lambda_{2}}\right) = \frac{1 - 3e^{-i\lambda_{1}}}{e^{-i\lambda_{1}} - 3} \frac{1 - 3e^{-i\lambda_{2}}}{e^{-i\lambda_{2}} - 3} \frac{1 - 3e^{i(\lambda_{1} + \lambda_{2})}}{e^{i(\lambda_{1} + \lambda_{2})} - 3}$$

• Cumulant of  $\varepsilon_t$ :  $\kappa_3 = 1 \neq 0$ 

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# Generic Partial Indices

## Theorem (Gohberg, Krein (1960))

In an open and dense (aka. generic) set in the parameter space, the difference between the largest and the smallest partial index is smaller than two.

• 
$$\kappa_1 = \cdots = \kappa_k = \kappa + 1$$
 and  $\kappa_{k+1} = \cdots = \kappa_n = \kappa$ 

- Weaker assumption than Velasco's root separation.
- Not mentioned in GMR.

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# (Non-) Uniqueness of WHF

## Theorem (Clancey, Gohberg (1981))

The partial indices of b(z) are unique.

- In the case (κ, 0), the WHF can be made unique by requiring that p(0) = I<sub>n</sub>.
- In the case (κ, k), k ≠ 0, the equivalence class of WHFs is described by unimodular matrices of the form

$$u(z)=u_0+\begin{pmatrix}0&\tilde{u}_1\\0&0\end{pmatrix}z.$$

• 
$$\mathring{p}(z) = p(z)u(z), \ \mathring{f}(z) = s(z)^{-1}u(z)^{-1}s(z)f(z).$$

 transformation does not change the row degrees of f(z) or s(z)f(z).

## Theorem (Funovits 2020)

A unique representative among all tuples (p(z), s(z), f(z))such that b(z) = p(z)s(z)f(z) can be chosen and is of the described form.

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# Remarks

- Asymptotics are standard, similar to Rosenblatt (2000, Chapter 8)
- Main difficulty is identifiability
  - From identifiability it follows that information matrix is non-singular (main difficulty in "Lii, Rosenblatt 1996: MLE for non-Gaussian non-minimum phase ARMA sequences")
- Invertibility of  $f_0$  is essential
  - $f_0 = I_n$  simplifies Jacobian
- Formulas are complicated in the multivariate case
  - Equality restrictions in the case  $(\kappa, k)$

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# **R-Packages**

- Building on two packages written by Wolfgang Scherrer and myself
  - rationalmatrices
    - Implements matrix polynomials, left- and right-matrix fraction description of rational matrices, state space representations of rational matrices, Hankel matrices as representations
    - Conversions between these (S3-) classes, Kronecker normal forms, etc
    - Matrix factorizations: Smith-form, Wiener-Hopf factorization, column reduction

### RLDM (Rational Linear Dynamic Models)

- Mainly estimation algorithms, optimization of different (structural) models
- Simulations, visualization of IRF, FEVD, prediction
- Templates for different realizations (Kronecker form for VARMA, state space system, etc)

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# Feasibility

- Seems that the WHF parametrisation is the only feasible approach
  - Easy to check location of roots of p(z) and f(z)
  - Easy to provide useful initial values
  - No root flipping required
  - Very costly to evaluate cumulant spectra (sample size  $200 \Rightarrow 200^3$  frequency to integrate over)

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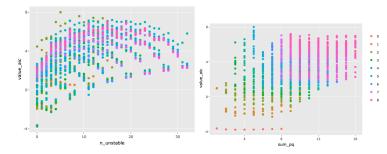
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# Monetary Model + RER

- unemployment, FFR, CPI inflation, real exchange rate
- AR models clearly best, no unstable roots



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# **Summary and Conclusion**

- New feasible parametrisation for estimating and analyzing non-invertible SVARMA
  - Exists on a topologically large set in the parameter space
  - Parametrises the number of MA zeros inside the unit circle
- Allows data-driven evaluation of DSGE models
- Makes "incredible restrictions" testable (and unnecessary to impose them apriori)

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