Mechanism Design with Limited Commitment

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Mechanism Design with Limited Commitment

- Full commitment is the standard assumption in dynamic mechanism design
 - Useful: upper bound on the designer's payoff.
 - Convenient: revelation principle turns the mechanism selection game into a constrained optimization program.
- This *tractability* is lost when the designer has **limited commitment**.
- Limited commitment looms large in many applications of interest:
 - Bargaining, principal agent (ratchet effect), fiscal policy, social insurance, international relations.
- Trade off:
 - Optimal mechanism w/finite horizon (Hart & Tirole (1988), Laffont & Tirole (1990), Skreta (2006,2015), Deb and Said (2015)).
 - Infinite horizon with restrictions (Maestri (2015), Gerardi & Maestri (2017), Strulovici (2017), Acharya and Ortner (2017)).

This paper

Revelation principle for mechanism design with limited commitment.

- We study a game between an uninformed designer and an informed agent with persistent private information.
- The designer can commit to today's contract, but not to the continuation ones.

Result

- 1. Characterize the minimal class of mechanisms that is sufficient to replicate *all* equilibrium payoffs of the mechanism selection game.
- 2. Transform the designer's problem into a constrained optimization one
 - Usual truthtelling and participation constraints,
 - + designer's sequential rationality constraint.

$$M \xrightarrow{\beta(\cdot|m)} S \xrightarrow{\alpha(\cdot|s)} A$$

Mechanisms (Myerson '82, Forges '85)

- *M* is a set of input messages,
- S is a set of output messages,
- β is a communication device,
- α is a (randomized) allocation rule.



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Full Commitment

Without loss of generality,

- M = V,
- |S| = |M|,
- β is "invertible",
- Truth-telling.



Limited Commitment 1: Bester & Strausz (ECMA, 2001) Assume:

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Then, for outcomes in the Pareto frontier, it is without loss of generality

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However, Truthtelling.



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- XM//#/X\$/V
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Limited Commitment 1: Bester & Strausz (JET, 2007) Assume:

- MM/#/S ask: when is it without loss of generality to have |M| = |S|?
- $\beta/is//invertible//,$
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Then, without loss of generality

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Revelation principle:

- $S \approx \Delta(V)$.
- In a general class of games, this language allows us to replicate any equilibrium payoff of the interaction between the designer and the agent.
 - No need to assume transfers/time separability/history independence.
- Mechanism serves dual role: allocation today & information tomorrow.
- Mechanisms with M = V and $S = \Delta(V)$ are denoted canonical.

Parsimonious representation:

- In finite horizon, we can write the designer's problem as a sequence of constrained maximization problems.
- Truthtelling + participation + designer's sequential rationality.
- Constrained Information Design.

Revelation Principle

Mechanism Selection Game: Model

- Two players, the principal and the agent, interact over T periods.
 - T can be infinity.
- The principal holds the bargaining power.
- The agent has private information: type $v \in V$, $|V| < \infty$.
- Each period an allocation a ∈ A is determined, where A is a compact space.
- Given a sequence of allocations a^t = (a₀,..., a_{t-1}), the principal can only choose a_t ∈ A(a^t).
- Payoffs: W(a, v) for the principal and U(a, v) for the agent for a ∈ A^T, v ∈ V.

The action set for the principal at time t is given by:

$$\mathcal{M}_t = \{\mathbf{M}_t = (\langle M^{\mathbf{M}_t}, \beta^{\mathbf{M}_t}, S^{\mathbf{M}_t} \rangle, \alpha^{\mathbf{M}_t})\}$$

where:

- M^{M_t} is a finite set of input messages, $|V| \leq |M^{M_t}|$,
- S^{M_t} is a set of output messages, S^{M_t} contains an image of $\Delta(V)$,
- $\beta^{\mathsf{M}_t} : M^{\mathsf{M}_t} \mapsto \Delta^*(S^{\mathsf{M}_t})$ is the communication device,
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- A mechanism is canonical if (V, Δ(V)) are its sets of input and output messages.
- Let \mathcal{M}^{C} denote the set of canonical mechanisms.
- Assume that $\mathcal{M}^{\mathsf{C}} \subseteq \mathcal{M}_t$.

In each period t,

- Both players observe a draw from a correlating device $\omega \sim U[0,1]$.
- The principal offers the agent a mechanism M_t.
- The agent observes the mechanism and accepts/rejects:
 - If she rejects, an allocation a^{*} ∈ A gets implemented. Move to next period. (Assume a^{*} ∈ A(a^t) for all t, a^t ∈ A^t).
- If she accepts, sends report $m \in M^{M_t}$, unobserved to the principal.
- $s \in S^{M_t}$ is drawn according to $\beta^{M_t}(\cdot|m)$, observed by the principal.
- $a \in A$ is drawn according to $\alpha^{M_t}(\cdot|s)$, observed by the principal.

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Equilibrium

A Perfect Bayesian Equilibrium is a tuple $\langle \Gamma^*, (\pi_v^*, r_v^*)_{v \in V}, \mu^* \rangle$ such that:

- 1. Strategies are sequentially rational,
- 2. Beliefs are obtained via Bayes' rule whenever possible.

Alternatively, consider the following canonical game where, for all t, $\mathcal{M}_t \equiv \mathcal{M}^C$, i.e.,

- $M^{\mathsf{M}_t} = V$,
- $S^{\mathsf{M}_t} = \Delta(V).$

That is, the principal only chooses β and α .

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Then there exists a payoff-equivalent PBE of the canonical game, $\langle \Gamma', (\pi'_{\nu}, r'_{\nu})_{\nu \in V}, \mu' \rangle$, such that

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$$\frac{\mu'(\mathbf{v})\beta^{\mathsf{M}_{t}^{\mathsf{C}}}(\mu|\mathbf{v})}{\sum_{\mathbf{v}'\in \mathbf{V}}\mu'(\mathbf{v}')\beta^{\mathsf{M}_{t}^{\mathsf{C}}}(\mu|\mathbf{v}')}$$

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$$\mu'(\mathsf{M}_t^{\mathsf{C}}, 1, \mu)(\mathsf{v}) = \frac{\mu'(\mathsf{v})\beta^{\mathsf{M}_t^{\mathsf{C}}}(\mu|\mathsf{v})}{\sum_{\mathsf{v}' \in \mathsf{V}} \mu'(\mathsf{v}')\beta^{\mathsf{M}_t^{\mathsf{C}}}(\mu|\mathsf{v}')}$$

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Canonical input messages: M = V

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- The agent has two pieces of private information:
 - her payoff relevant type, $v \in V$,
 - her past interactions with the mechanism.
- It implies that the principal cannot peak into his past devices.
- It follows from:
 - If the agent conditions on past input messages, then she is indifferent.
 - It is possible to construct a strategy for the agent that gives the principal the same payoff.

Canonical output messages: $\overline{S = \Delta(V)}$

 $S = \Delta(V)$

- Let \mathbf{M}_t be a mechanism on the support of Γ^* and $s \in S^{\mathbf{M}_t}$
- Upon observing *s*, two things happen:
 - The allocation is drawn from $\alpha^{\mathsf{M}_t}(\cdot|s)$.
 - Principal updates his beliefs about V and past inputs using β^{M_t} and r_v^* : $\mu_s^*(v, \cdot)$.
- Lemma 1 implies that $\mu_s^*(\mathbf{v}, \cdot)$ is constant.

 \Rightarrow relevant part of beliefs are about the agent's type!

• Natural conjecture: relabel $s \simeq \mu_s^*$.

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• Coordinate continuation play

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Lemma 2

There is a one-to-one mapping between output messages and equilibrium beliefs.

Truthtelling and participation with probability $\boldsymbol{1}$

Truthtelling and participation with probability 1

Fix a history and a $\mathbf{M}_t \in \text{supp } \Gamma^*$. Let

$$\sigma(\mathsf{M}_t): S^{\mathsf{M}_t} \mapsto \Delta(V)$$

$$\sigma(\mathsf{M}_t)(s) = \sum_{\substack{h_A^t, m \in M^{\mathsf{M}_t}}} \mu^*(h^t, \mathsf{M}_t, 1, s)(\cdot, m),$$

we can define for each $\mu \in \Delta(V)$,

$$\alpha^{\mathsf{M}_{t}^{\mathsf{C}}}(\boldsymbol{a}|\boldsymbol{\mu}) = \alpha^{\mathsf{M}_{t}}(\boldsymbol{a}|\boldsymbol{\sigma}^{-1}(\mathsf{M}_{t})(\boldsymbol{\mu}))$$
$$\beta^{\mathsf{M}_{t}^{\mathsf{C}}}(\boldsymbol{\mu}|\boldsymbol{\nu}) = \sum_{\boldsymbol{m}\in\mathcal{M}^{\mathsf{M}_{t}}} \beta^{\mathsf{M}_{t}}(\boldsymbol{\sigma}^{-1}(\mathsf{M}_{t})(\boldsymbol{\mu})|\boldsymbol{m})r_{\boldsymbol{\nu}}^{*}(\mathsf{M}_{t},1)(\boldsymbol{m}),$$

Participation with probability 1:

- As usual, we can have the agent participate, but
 - not only need to guarantee she receives the same allocation, but also,
 - make sure that this can be done without altering the continuation mechanism for the agent.

- The theorem says that all equilibrium payoffs of the mechanism selection game are also equilibrium payoffs of the canonical game.
- However, canonical game has a smaller set of deviations.
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Proposition

Any equilibrium payoff of the canonical game can be attained in an equilibrium of the mechanism selection game.

- In the canonical game, not all deviations are to mechanisms that induce truthtelling and participation.
- It follows from the proof of the proposition that these are all the deviations that matter.
- Hence, in finite horizon, can write the principal's problem as selecting between mechanisms such that
 - Agent participates with probability 1.
 - Agent tells the truth.
 - Recommended beliefs are *realized* beliefs.
 - Continuation mechanisms satisfy sequential rationality.

Indeed, once $S \simeq \Delta(V)$, we can think of

- Principal in period t: Sender,
- Principal in period t + 1: Receiver.

with some special features:

- Sender also takes actions: designs allocation,
- Not all information structures are available: only those that satisfy the PC and IC constraints ⇒ Constrained Information Design.

We exploit the connection to ID to provide a program in the finite horizon case that solves for the principal's optimal mechanism:

- Extend the one-inequality constraint result in Le Trest and Tomala (2017) to allow for any number of equality and inequality constraints.
- Characterize the number of posteriors the principal induces.
- Available in a short paper.

Conclusions

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- Revelation principle for mechanism design with limited commitment:
 - Canonical outputs: beliefs.
 - Single agent.
 - Finite types. (continuum in Appendix)
- Separate allocation from information revelation.
- Beliefs: non self-referential language.
- Parsimonious representation of the equilibrium payoffs of the mechanism selection game.

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- Parsimonious representation of the equilibrium payoffs of the mechanism selection game.

Not in the talk:

- Application to infinite horizon sale of a durable good:
 - Foundation for dynamic bargaining with one-sided offers and one-sided incomplete information.

Thank you!

We endow the principal with a collection $(M_i, S_i)_{i \in \mathcal{I}}$ such that

- M_i is finite and $|V| \leq |M_i|$ for all $i \in \mathcal{I}$,
- S_i contains an image of $\Delta(V)$ for all $i \in \mathcal{I}$,
- $(V, \Delta(V))$ is an element of the collection.

Denote by \mathcal{M} the set of all mechanisms with message sets $(M_i, S_i)_{i \in \mathcal{I}}$.

Hence, the action set for the principal at time t is given by:

$$\mathcal{M} = \{ \mathbf{M}_t = (\langle M^{\mathbf{M}_t}, \beta^{\mathbf{M}_t}, S^{\mathbf{M}_t} \rangle, \alpha^{\mathbf{M}_t}) \}$$

where:

- $(M^{\mathsf{M}_t}, S^{\mathsf{M}_t}) = (M_i, S_i)$ for some $i \in \mathcal{I}$,
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Back

Participation

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- We can guarantee all types of the agent participate with probability 1,
- This may require using messages m^*, s^* that are only sent by the 0-probability types, v^* .
- PBE (and SE) do not impose any restrictions on the principal's belief at s^*

in the original equilibrium when v^* did not participate, the principal could have believed it was $v' \neq v^*$!

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 \Rightarrow This endangers the one-to-one map between used outputs and beliefs

How do we deal with this?

- We "remove" input messages *m*^{*} that lead to output messages that are used only by 0-probability types.
- This removes deviations for the positive probability types, but may violate participation for the 0-probability types.
- Consequently, the only output messages that have positive probability under some device are those that have positive probability under the agent's reporting strategy and the principal's beliefs.

Back