Dynamic Inattention, the Phillips Curve and Forward Guidance

Hassan Afrouzi Columbia U. Choongryul Yang UT Austin

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Janet Yellen (Sept. 2017)

- Objective of forward guidance:
 - affect the economy today through news about future policy.
- Two natural questions:
 - Do price setters pay attention to the news about future policy?
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 - If so, do their prices respond to such news?
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- More generally, how are price setters' expectations formed and how do they affect inflation dynamics?

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• Two types of Phillips curves for inflation dynamics:

Sticky/Noisy information Phillips curves:

$$\pi_{\mathsf{t}} = \tilde{\mathbb{E}}_{\mathsf{t}-1}[\pi_{\mathsf{t}} + \alpha \Delta \mathsf{y}_{\mathsf{t}}] + \alpha \frac{\lambda}{1-\lambda} \mathsf{y}_{\mathsf{t}},$$

* criticized for not being forward looking.

Sticky price models:

$$\pi_{\mathsf{t}} = \beta \mathbb{E}_{\mathsf{t}}[\pi_{\mathsf{t}+1}] + \gamma \mathsf{y}_{\mathsf{t}},$$

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- A measure of firms $i \in [0, 1]$.
- Firms' flow nominal profit depends on their own price, aggregate price and output:

$$\begin{split} \Pi_{i,t} &= \Pi(\mathsf{P}_{i,t},\mathsf{P}_{t},\mathsf{Y}_{t}) \ &\approx -(\mathsf{p}_{i,t}-\mathsf{mc}_{t})^{2} + \mathsf{terms} \ \mathsf{independent} \ \mathsf{of} \ \mathsf{p}_{i,t} \end{split}$$

where small letters are log-deviations from steady state and

 $\mathbf{mc_t} = \mathbf{p_t} + \alpha \mathbf{y_t}.$

• Here:

► y_t is output gap.

• p_t is the aggregate price: $p_t = \int_0^1 p_{i,t} di$.

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• For any t, let S^t_i be i's information set at time t.

• i's pricing problem is

$$\mathsf{L}_{0}^{\mathsf{i}} \equiv \min_{\mathsf{p}_{\mathsf{i},\mathsf{t}}:\mathsf{S}_{\mathsf{i}}^{\mathsf{t}} \rightarrow \mathbb{R}} \mathbb{E} \left[\sum_{\mathsf{t}=0}^{\infty} \beta^{\mathsf{t}} (\mathsf{p}_{\mathsf{i},\mathsf{t}} - \mathsf{mc}_{\mathsf{t}})^{2} |\mathsf{S}_{\mathsf{i}}^{0} \right]$$

• Solution:

 $p_{i,t}(S_i^t) = \mathbb{E}[mc_t|S_i^t]$

and

$$\mathsf{L}_0^{\mathsf{i}} = \sum_{\mathsf{t}=0}^\infty \beta^{\mathsf{t}} \mathsf{var}(\mathsf{mc}_\mathsf{t}|\mathsf{S}_{\mathsf{i}}^{\mathsf{t}}).$$

• Kalman filtering:

$$\Delta \mathbf{p}_{i,t} = \mathbb{E}[\Delta \mathbf{m} \mathbf{c}_t | \mathbf{S}_i^{t-1}] + \mathbf{k}_t^i (\mathbf{s}_{i,t} - \mathbb{E}[\mathbf{s}_{i,t} | \mathbf{S}_i^{t-1}])$$

• Need to characterize what kind of signals firms choose to see.

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- Chooses $p_{i,t} : S_i^t \to \mathbb{R}$.

$$\begin{split} L_t(S_i^{t-1}) = \min_{S_{i,t} \subset \mathcal{S}_t} \{ \underbrace{var(mc_t | S_i^t)}_{\text{gain from information}} + \underbrace{C(S_{i,t} | S_i^{t-1})}_{\text{cost of information}} + \beta L_{t+1}(S_i^t) \} \\ \text{s.t. } S_i^t = S_i^{t-1} \cup S_{i,t} \end{split}$$

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- A forward looking firm cares about mc_t , mc_{t+1} , mc_{t+2} , ...
- These are subject to shocks that might not have been realized at time t.
- So if $\mathbb{E}_t^f[.]$ captures availability of infromation at t, firms can learn about $\mathsf{mc}_t, \mathbb{E}_t^f[\mathsf{mc}_{t+1}], \mathbb{E}_t^f[\mathsf{mc}_{t+2}], \ldots$
- It is optimal for firm to consider signals of the following form at time t:

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- Data Processing Inequality (DPI) in information theory:
 - \blacktriangleright for $\{s_1,s_2\}\subset \mathcal{S}_t$, seeing a combination of them is less costly than seeing both

$$\mathsf{C}(\mathsf{a}\mathsf{s}_1 + \mathsf{b}\mathsf{s}_2|\mathsf{S}^{\mathsf{t}-1}) \leq \mathsf{C}(\mathsf{s}_1, \mathsf{s}_2|\mathsf{S}^{\mathsf{t}-1})$$

Proposition

Every firm observes only one signal at any time.

• Intuition:

- Price is a linear combination of signals.
- So instead of seeing signals separately and paying a high cost, the firm would like to see the combination.

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 - Price is a linear combination of signals.
 - So instead of seeing signals separately and paying a high cost, the firm would like to see the combination.

 $\bullet\,$ The marginal cost of learning more about any $\mathbb{E}^f_t[\mathsf{mc}_{t+\tau}]$ is increasing.

Proposition

Optimal signals are forward looking $(b_{\tau>0} \neq 0)$

$$\mathbf{s}_{\mathsf{i},\mathsf{t}} = \sum_{\mathsf{j}=0}^{\infty} \beta^{\mathsf{j}} \mathsf{b}_{\mathsf{j}} \mathbb{E}^{\mathsf{f}}_{\mathsf{t}}[\mathsf{mc}_{\mathsf{t}+\mathsf{j}}] + \sigma^{\mathsf{i}}_{\mathsf{s}} \mathsf{e}_{\mathsf{i},\mathsf{t}}$$

• The agent is forward looking and wants to know about

 $\mathsf{mc}_{\mathsf{t}}, \mathbb{E}^{\mathsf{f}}_{\mathsf{t}}[\mathsf{mc}_{\mathsf{t}+1}], \mathbb{E}^{\mathsf{f}}_{\mathsf{t}}[\mathsf{mc}_{\mathsf{t}+2}], \dots$

Marginal benefit is decreasing with horizon while marginal cost is increasing with precision \Rightarrow Information smoothing.

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Dynamic Inattention, the Phillips Curve and Forward Guidance

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- Recall, $mc_t = p_t + \alpha y_t$.
- In sticky/noisy information models:

$$\pi_{\mathbf{t}} = \tilde{\mathbb{E}}_{\mathbf{t}-1}[\pi_{\mathbf{t}} + \alpha \Delta \mathbf{y}_{\mathbf{t}}] + \alpha \frac{\lambda}{1-\lambda} \mathbf{y}_{\mathbf{t}}$$

- sticky information: λ is the fraction that update their information.
- noisy information: λ is the Kalman gain.
- Under dynamic inattention:

$$\pi_{t} = \tilde{\mathbb{E}}_{t-1}[\pi_{t} + \alpha \Delta \mathbf{y}_{t}] + \alpha \delta_{0} \mathbf{y}_{t}$$
$$- \sum_{\tau=1}^{\infty} \beta^{\tau} \delta_{\tau} \tilde{\mathbb{FE}}_{t}[\pi_{t+\tau} + \alpha \Delta \mathbf{y}_{t+\tau}]$$

where $\tilde{\mathbb{FE}}[x] \equiv \tilde{\mathbb{E}}_t[x] - \mathbb{E}_t^f[x]$ is the forecast error of firms relative to a fully informed agent.

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Remarks:

- **①** This imbeds the noisy information Phillips curve when $\beta = 0$.
- Inflation is affected by expectations about future, but in a different way than sticky price models:
 - $\pi_t = \beta \mathbb{E}_t[\pi_{t+1}] + \kappa y_t$: inflation is increasing in expected inflation.
 - o dynamic inattention: inflation is decreasing in forecast errors.

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Estimate the Phillips curve using GMM

$$\begin{aligned} \pi_{\mathbf{t}} &= \tilde{\mathbb{E}}_{\mathbf{t}-1}[\pi_{\mathbf{t}} + \alpha \Delta \mathbf{y}_{\mathbf{t}}] + \alpha \delta_{0} \mathbf{y}_{\mathbf{t}} \\ &- \sum_{\tau=1}^{\mathsf{T}} \beta^{\tau} \delta_{\tau} \tilde{\mathbb{FE}}_{\mathbf{t}}[\pi_{\mathbf{t}+\tau} + \alpha \Delta \mathbf{y}_{\mathbf{t}+\tau}] + \xi_{\mathbf{t}} \end{aligned}$$

Use Survey of Professional Forecasters as proxy for firms' forecasts.

- Instrument forecast revisions for forecast errors. (Coibion Gorodnichenko (2015))
- 3 Null hypothesis: $\delta_{\tau} \neq 0$ for $\tau > 0$.

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	π_{t}	
	(1)	(2)
	GDP Deflator (72Q1-16Q4)	CPI (81Q3-16Q4)
$\tilde{\mathbb{E}}_{\mathbf{t}-1}[\pi_{\mathbf{t}} + \alpha \Delta \mathbf{y}_{\mathbf{t}}]$	1.00 ***	1.01 ***
	(0.01)	(0.14)
$\alpha \mathbf{y_t}$	1.28 **	0.67 ***
	(0.50)	(0.10)
$\tilde{\mathbb{FE}}_{\mathbf{t}}[\pi_{\mathbf{t}+1} + \alpha \Delta \mathbf{y}_{\mathbf{t}+1}]$	0.42 ***	0.16 ***
	(0.05)	(0.03)
$\tilde{\mathbb{FE}}_{\mathbf{t}}[\pi_{\mathbf{t}+2} + \alpha \Delta \mathbf{y}_{\mathbf{t}+2}]$	0.21 ***	-0.31 ***
	(0.05)	(0.03)
$\tilde{\mathbb{FE}}_{\mathbf{t}}[\pi_{\mathbf{t}+2} + \alpha \Delta \mathbf{y}_{\mathbf{t}+2}]$	0.11 ***	-0.17 ***
	(0.02)	(0.04)
Newey-West robust standard errors in parentheses		

*** p<0.01, ** p<0.05, * p<0.1

Example: One Period Ahead News

- Suppose $mc_t = mc_{t-1} + u_{t-1}$
- Shocks are announced one period ahead.
- How much do agents pay attention to this news and react?
- Under myopic inattention($\beta = 0$):

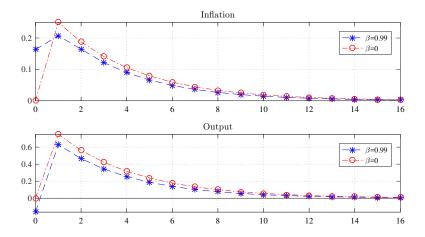
$$s_{i,t} = mc_t + e_{i,t}$$

- Notice that in this case $u_t \perp S_i^t$: myopic firms completely ignore news about future.
- Under dynamic inattention $(\beta > 0)$:

$$\mathbf{s}_{\mathbf{i},\mathbf{t}} = \mathbf{m}\mathbf{c}_{\mathbf{t}} + \gamma\mathbf{m}\mathbf{c}_{\mathbf{t}+1} + \mathbf{e}_{\mathbf{i},\mathbf{t}}$$

Example: One Period Ahead News

- Under dynamic inattention inflation responds to the news shock.
- Output falls on impact because marginal cost is fixed by assumption, which is relaxed in GE.



A Three Equation Model

• Dynamic Phillips curve:

$$\pi_{\mathbf{t}} = \tilde{\mathbb{E}}_{\mathbf{t}-1}[\pi_{\mathbf{t}} + \alpha \Delta \mathbf{y}_{\mathbf{t}}] + \alpha \delta_{0} \mathbf{y}_{\mathbf{t}} \\ - \sum_{\tau=1}^{\infty} \beta^{\tau} \delta_{\tau} \mathbb{F} \tilde{\mathbb{E}}_{\mathbf{t}}[\pi_{\mathbf{t}+\tau} + \alpha \Delta \mathbf{y}_{\mathbf{t}+\tau}]$$

Oynamic IS curve:

$$\mathbf{y}_{\mathsf{t}} = \mathbb{E}_{\mathsf{t}}^{\mathsf{f}}[\mathbf{y}_{\mathsf{t}+1}] - \sigma^{-1}(\mathbf{i}_{\mathsf{t}} - \mathbb{E}_{\mathsf{t}}^{\mathsf{f}}[\pi_{\mathsf{t}+1}])$$

• Taylor rule:

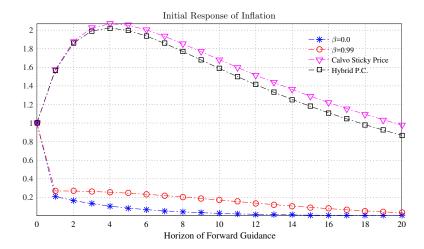
$$\mathbf{\dot{i}_{t}} = \rho \mathbf{\dot{i}_{t-1}} + (1 - \rho) \left(\phi_{\pi} \pi_{\mathbf{t}} + \phi_{\mathbf{y}} \mathbf{y}_{\mathbf{t}} \right) + \mathbf{u}_{\mathbf{t}-\mathbf{k}}$$

where k is the horizon of forward guidance.

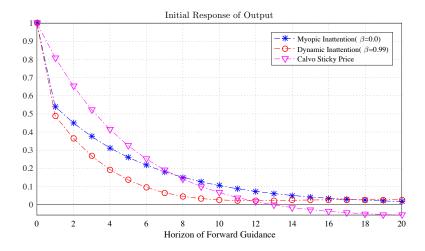
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Forward Guidance Puzzle

• Impact response of inflation is decreasing in horizon of forward guidance



4-period ahead Forward Guidance Shock



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Conclusion

• Showed that firms have information smoothing incentives:

- they pay attention to news about future,
- and incorporate such news in their current prices.
- Derived and estimated a new micro founded Phillips curve:
 - inflation is forward looking in contrast to other models of information rigidity.
 - no forward guidance puzzle despite inflation being forward looking.

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- Showed that firms have information smoothing incentives:
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4-period ahead Forward Guidance Shock

