# Technology Polarization* 

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#### Abstract

We construct a new method to describe firm distributions within technology fields and investigate the relationship between those distributions and aggregate innovation. To locate firms on a technology space, we apply multidimensional scaling for the inter-firm technological dissimilarity matrices that are computed from patent citation overlaps among firms using the NBER US patent dataset. Our estimated firm distributions show increasing trends in technological distance and polarization on average, where we follow Duclos et al. (2004) to measure polarization. We construct a model of inter-group competition in which polarization stimulates R\&D incentives. The model fits data before 1990 but the impact of polarization is reversed after that. We attribute the structural change to the major patent reform in the United States in 1980s.


[^0]Keywords: Patent citation overlaps; polarization; inter-group competition; multi-dimensional scaling
JEL classification: O31, O32, L25

## 1 Introduction

Since Jaffe (1986) introduced technological distance (or proximity) between firms with using patent data to capture knowledge spillovers, researchers in economics and innovation management have used it to estimate technological relations among firms (Jaffe (1989), Rosenkopf and Almeida (2003), Benner and Waldfogel (2008), Bloom et al. (2013), and so on). They mainly consider how firms' positions in technology spaces and resulting accecible knowledge affect innovation, stock value, productivity, M\&A and alliance at the firm level.

This paper investigates the distribution of firm positions in technological spaces and its relation to innovation output at the aggregate level rather than the firm level. Our main question is: Under what type of distributions are innovations stimulated? To see the key factors to answer this question, imagine the following three extreme distributions in a technological space. First, if most firms concentrate on a technological position, they unintentionally help each other through knowledge spillovers because a firm can know and facilitate a new technology developed by another firm relatively easily when they are closely related. ${ }^{1}$ Second, if we have a wide-spread firm distribution in a technology space, the spillover effect is relatively small. This is the opposite case to concentrated distributions. ${ }^{2}$ Lastly but the most importantly in this paper, consider the middle. Suppose that we have a firm distribution in a technology space such that there are two poles, i.e., concentration points, distant from each other. There are two scenarios to explain this type of distribution. One is segmentation of technology. Even in the same technology space, poles are not technologically related. In this scenario, it is better to consider that the current technological classification should be subdivided. The other scenario is inter-group competition. Firms

[^1]around each pole use distinct fundamental technologies and they compete a race for becoming a (de facto) standard in the technology field. ${ }^{3}$ In this scenario, they have more incentive to innovate because the winning pole will grab all demands. The level of market competition does not decay in technological distance because the products from the two poles are close in the market.

Several instances of competition for the de factor standard, such as the videotape format war between betamax and VHS, and between producers of operating systems for computers, indicate the historical existence of technology groups and inter-group competition. Open innovation strategies may also induce technology groups. A typical example is that IBM released its software patents in 2005 and induce other firms to develop Linux. Recently, the largest automobile company in Japan made its fuel cell vehicle patents free for use to facilitate entry by other firms, which is an example that a firm tries to generate a technology group (TOYOTA Motor Corporation (2015)). Our theoretical model shows how distributional statistics (average distance, concentration, and polarization) relate to the average R\&D in each technology field.

The degree of polarization, developed by the series of papers by Esteban and Ray (Esteban and Ray (1994), Esteban and Ray (2011), and so on), responds such inter-group competition. Intuitively, high polarization results when there are two distinct density masses (poles) with large distance between them, while low polarization is attained when a distribution has only one mass point or if the distribution is equally dispersed like a uniform distribution. We apply the continuous version of the polarization defined in Duclos et al. (2004) (referred to as DER below) to firm distribution in a technology space. This paper is the first work that applies their formalization of polarization to R\&D activities.

Our main findings are as follows. First, we find that the average technological distance and the average polarization have displayed upward trends in the last three decades in the United States. Second, we estimate the impacts of polarization on the number of citation-weighted patent applications. Our model of inter-group competition implies that polarization raises innovation. But the model fits data only before 1990 and the impact is completely reversed afterwards. This reversion can be explained by the negative impact on patent quality from polarization, which is only observed in the later periods. Thus, we attribute

[^2]the structural change to the major patent reform in the United States in 1980s that changes institutions from anti-patent to pro-patent because the reform may have caused degradation of patent quality (Jaffe and Lerner (2004)). This suggest that the desired distribution on a technology space depends on institutions.

To obtain the distribution of firms in technology spaces, we use two methods of Stuart and Podolny (1996) with modifications: patent citation overlaps and multi-dimensional scaling. We choose citation overlaps to examine the technological similarity; this allows us to look at the distribution of firms within technological categories. Other standard methods utilize patent portfolios, within-firm distributions of patents across categories (Jaffe (1986), Jaffe (1989), Benner and Waldfogel (2008), Bar and Leiponen (2012), Bloom et al. (2013), etc.), are not suitable to consider changes inside of the categories. ${ }^{4}$ Since the original definition of citation overlap between two firms in Stuart and Podolny (1996) is not independent of a third firm, we modify it to satisfy independence of pair-wise similarity from third firms as illustrated in the next section. ${ }^{5}$

Multidimensional scaling (MDS, hereafter) is a statistical tool to estimate the location of entities by minimizing the sum of squared gaps between dissimilarity and the resulting distance, when dissimilarities among entities are given. Dissimilarity does not have to be a mathematical distance in MDS. MDS is not popular in economics but is one of the typical ways to analyze relational data in behavioral sciences (cf. Cox and Cox (2001)).

Data We used the NBER US patent dataset ${ }^{6}$. The dataset provides information on patents granted by the USPTO up to 2006. For patents granted after 1975, the dataset supplies the citation list of each patent (only for those registered in the US patent office, though). The dataset also provides information about changes in patent ownership. Thus, we can specify the original inventors of technologies. In this paper, we basically consider the 2 -digit classification defined in Hall et al. (2001), which they call subcategories. We omit 6 "miscellaneous"

[^3]categories out of 37 subcategories because they are not suitable for our purpose. The list of subcategories is summarized in Table 7 in Appendix B. The NBER US patent dataset contains firm identification numbers defined by Compustat for private firms, with which we link the patent data to firm data. The technological distributions are computed for 215 -year moving windows such as 1976-1980, 1977-1981, ..., 1996-2000. ${ }^{7}$

The rest of the paper is organized as follows. Section 2 is devoted to the description of the measurement methodologies including citation overlaps, multidimensional scaling, and 2-dimensional kernel density estimation. Section 3 presents a simple model to connect polarization and $R \& D$ incentives, and defines the degree of polarization. In Section 4, we investigate the impact of polarization on innovation. Section 5 discusses our results.

## 2 Technological Distance among Firms in each Technological Category

As mentioned in the introduction, the traditional measures of technological distance are based on the patent portfolio vector of each firm, which contains information about the within-firm distribution of patent holdings over technological categories. For investigating firm distributions within categories, another type of technological distance is needed. In this section, we construct a new measure of technological (dis-)similarity among firms based on patent citation overlaps.

### 2.1 Citation Overlaps

The first-order citation overlaps between firm $i$ and $j$ are from patent citation lists of the two firms within a period, say $P_{i}$ and $P_{j}$. Since some patents are frequently cited by the same firm, the elements in each list is not unique in general. We consider such a frequently cited patent as important for the firm. When a citation overlap occurs at such an important patent, the overlap contributes to technological closeness more than an overlap that occurred among one-time

[^4]

Figure 1: Citation overlaps.
cited patents. ${ }^{8}$ To incorporate this idea, we keep repetition in each citation list. Define $O\left(P_{i}, P_{j}\right)$ as the patents in $P_{i}$ that overlap those in $P_{j}$ with repetition (we do not say "intersection" because the elements are not unique in general). The first-order citation overlap, $\omega_{i j}^{1}$, is defined as

$$
\begin{equation*}
\omega_{i j}^{1} \equiv\left|O\left(P_{i}, P_{j}\right)\right|+\left|O\left(P_{j}, P_{i}\right)\right|, \tag{1}
\end{equation*}
$$

where $|P|$ is the number of patents in a list, $P$. Figure 1 illustrates an exapmle with $P_{i}=\{1,1,2,3,4\}$ and $P_{j}=\{1,3,5\}$, where each number indicates a patent. $\omega_{i j}^{1}$ counts the patents in the shaded area.

Even though a citation does not directly overlap, it could be technologically related indirectly. In the current example, patent 2 cited by firm $i$ cites patent 5, which is cited by firm $j$. Moreover, patent 4 in firm $i$ 's citation list and patent 5 in firm $j$ 's list cite the same patent 6 . To capture these indirect overlaps, we define the second-order overlaps.

Let $\tilde{P}_{i j}$ be the items of $P_{i}$ that do not overlap $P_{j}$. Let $C_{i}(p)$ be patent $p$ 's citations but not included in $P_{i} .{ }^{9}$ The idea of the second-order overlap is that we put a positive weight on $p_{k} \in \tilde{P}_{i j}$ if $p_{k}$ cites a patent in $\tilde{P}_{j i}$ or a patent cited by any

[^5]patent in $\tilde{P}_{j i}$. Thus, it consists of two components. The first component picks up patents in $\tilde{P}_{i j}$ citing any of $\tilde{P}_{j i}$,
\[

$$
\begin{equation*}
\omega_{i j}^{21}=\sum_{k=1}^{n_{i j}} \frac{\left|O\left(C_{i}\left(p_{k}\right), \tilde{P}_{j i}\right)\right|}{\left|C_{i}\left(p_{k}\right)\right|} . \tag{2}
\end{equation*}
$$

\]

$\omega_{j i}^{21}$ is similarly defined.
The second component of the second-order overlaps considers the patents in $\tilde{P}_{i j}$ that do not overlap $\tilde{P}_{j i}$, say $\tilde{P}_{i j}^{\prime}$. Suppose $\tilde{P}_{i j}^{\prime}$ contains $n_{i j}^{\prime}$ items. Then check whether each patent in $\tilde{P}_{i j}^{\prime}$ cites any patent cited by patents in $\tilde{P}_{j i}$,

$$
\begin{equation*}
\omega_{i j}^{22}=\sum_{k=1}^{n_{i j}^{\prime}} \frac{\left|O\left(C_{i}\left(p_{k}\right), C_{j}\left(\tilde{P}_{j i}\right)\right)\right|}{\left|C_{i}\left(p_{k}\right)\right|} \tag{3}
\end{equation*}
$$

where $C_{i}(P) \equiv\left\{C_{i}\left(p_{k}\right)\right\}_{k=1}^{n_{i j}^{\prime}}$, abusing notation. $\omega_{j i}^{22}$ is analogous.
The total citation overlap index is the ratio of the sum of the above overlaps to the total number of citations of both firms.

$$
\begin{equation*}
\omega_{i j}=\frac{\omega_{i j}^{1}+\eta\left(\omega_{i j}^{21}+\omega_{j i}^{21}\right)+\eta^{2}\left(\omega_{i j}^{22}+\omega_{j i}^{22}\right)}{\left|P_{i}\right|+\left|P_{j}\right|}, \tag{4}
\end{equation*}
$$

where $\eta \in(0,1)$. We interpret $\eta$ as the discount factor of technological relevance as generations go back. If a new technology is a child of citations, parent level relations are more significant than relations among grand parents. Note that $\omega_{i i}=1, \omega_{i j} \in[0,1]$ and, $\omega_{i j}=\omega_{j i}$.

Example Suppose that $P_{i}=\{1,1,2,3,4\}$ and $P_{j}=\{1,3,5\}$ as in Figure 1. The first-order overlap is the number of common patents, namely $\omega_{i j}^{1}=|\{1,1,3\}|+$ $|\{1,3\}|=5$. Next, look at the patents in $P_{i}$ that do not overlap $P_{j}, \tilde{P}_{i j}=\{2,4\}$. We put some weights for the patents in $\tilde{P}_{i j}$ according to the relations with $\tilde{P}_{j i}=$ \{5\}.

Suppose that patent 2 cites patent 5 and 7 , patent 4 cites patents 3 and 6 , and patent 5 cites patents 6 and 8 . Since we eliminate patents overlapped on the first-order stage, $C_{i}(2)=\{5,7\}, C_{i}(4)=\{6\}$, and $C_{j}(5)=\{6,8\}$. Then,

$$
\omega_{i j}^{21}=\frac{\left|O\left(C_{i}(2), \tilde{P}_{j i}\right)\right|}{\left|C_{i}(2)\right|}+\frac{\left|O\left(C_{i}(4), \tilde{P}_{j i}\right)\right|}{\left|C_{i}(4)\right|}=\frac{1}{2} .
$$

Similarly, $\omega_{j i}^{21}=0$. The second component of the second-order overlap is defined for patents with zero weight in calculation of $\omega^{21}$. In the current example, $\tilde{P}_{i j}^{\prime}=\{4\}$ and $\tilde{P}_{j i}^{\prime}=\{5\}$. Look at whether patent 4's citations overlap citations of patent 5 (excluding overlapped patents at the first-order level). Here,

$$
\omega_{i j}^{22}=\frac{\left|O\left(C_{i}(4), C_{j}(5)\right)\right|}{\left|C_{i}(4)\right|}=1 \quad \text { and } \quad \omega_{j i}^{22}=\frac{\left|O\left(C_{j}(5), C_{i}(4)\right)\right|}{\left|C_{j}(5)\right|}=\frac{1}{2}
$$

Finally, the total overlap index is defined as

$$
\omega_{i j}=\frac{5+\eta\left(\frac{1}{2}+0\right)+\eta^{2}\left(1+\frac{1}{2}\right)}{3+5}
$$

with some constant $\eta \in(0,1)$.
Surely, we can define third- or higher-order overlaps but they require tedious computations. On the other hand, first-order overlaps do not give us much information about similarity of firms because there are not many direct citation overlaps, especially before the mid-1980s. ${ }^{10}$ Hence, we use the first- and second-order overlaps.

The citation overlap index defined in (4) is an index of technological similarity. We transform the citation overlap index such that

$$
\begin{equation*}
d_{i j}=-\log \left(\omega_{i j}\right), \tag{5}
\end{equation*}
$$

as long as $\omega_{i j}>0 . d_{i j}$ is nonnegative, symmetric, $d_{i i}=0$ but the triangle inequality does not hold. Thus we call it technological dissimilarity rather than distance. We will explain how to deal with pairs with $\omega_{i j}=0$ in the next subsection.

Technological dissimilarities are defined in each subcategory and in each pe$\operatorname{riod}$ (5-year window), $\tau . D_{\tau}$ is the matrix of $d_{i j}$, where firm $i$ and $j$ applied for at least one patent (which is granted later) in the current subcategory during period $\tau$. We omit the subscript indicating subcategories for notational simplicity.

We also calculate dynamic citation overlaps in each subcategory. A firm in period $\tau-1$ has a citation overlap index with firms in period $\tau$ (often including the same firm). We calculate the citation overlaps in the same way, derive $d_{i j}^{\tau-1, \tau}$ as the dissimilarity between firm $i$ in period $\tau-1$ and firm $j$ in period $\tau$, and

[^6]define $\hat{D}_{\tau-1, \tau}$ as the dynamic dissimilarity matrix.
The overall dissimilarity matrix, $\mathscr{D}_{\tau}$, for $\tau \geq 2$ is
\[

\mathscr{D}_{\tau} \equiv\left[$$
\begin{array}{cc}
D_{\tau-1} & 0  \tag{6}\\
\hat{D}_{\tau-1, \tau} & D_{\tau}
\end{array}
$$\right]
\]

where

$$
D_{\tau}=\left[\begin{array}{cccc}
0 & 0 & \ldots & 0 \\
d_{2,1}^{\tau} & 0 & \ldots & 0 \\
d_{3,1}^{\tau} & d_{3,2}^{\tau} & \ddots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
d_{n_{\tau}, 1}^{\tau} & d_{n_{\tau}, 2}^{\tau} & \ldots & 0
\end{array}\right], \quad \hat{D}_{\tau-1, \tau}=\left[\begin{array}{cccc}
d_{1,1}^{\tau-1, \tau} & d_{1,2}^{\tau-1, \tau} & \ldots & d_{1, n_{\tau-1}}^{\tau-1, \tau} \\
d_{2,1}^{\tau-1, \tau} & d_{2,2}^{\tau-1, \tau} & \ldots & d_{2, n_{\tau-1}}^{\tau-1, \tau} \\
\vdots & \vdots & \ddots & \vdots \\
d_{n_{\tau}, 1}^{\tau-1, \tau} & d_{n_{\tau}, 2}^{\tau-1, \tau} & \ldots & d_{n_{\tau}, n ⿱-1}^{\tau-1, \tau}
\end{array}\right],
$$

where $n_{\tau}$ is the number of firms. We define $\mathscr{D}_{\tau}$ as a lower triangular matrix because it has full information from symmetry.

### 2.2 Mapping Firm Locations: Multi-dimensional Scaling

Now we estimate the distribution of firms in technological spaces by using the dissimilarity matrix defined in the previous subsection. As in Stuart and Podolny (1996), we estimate firm locations by multi-dimensional scaling (MDS) with 2 dimensions. ${ }^{11}$

MDS estimates a distribution of firms such that the pairwise distances among firms are consistent with the original dissimilarities. More precisely, it estimates the distribution to minimize the stress, $S$, defined as

$$
\begin{equation*}
S=\left[\frac{\sum_{i=1}^{n} \sum_{j>i}^{n} w_{i j}\left(\delta_{i j}-d_{i j}\right)^{2}}{\sum_{i=1}^{n} \sum_{j>i}^{n} w_{i j} d_{i j}^{2}}\right]^{\frac{1}{2}}, \tag{7}
\end{equation*}
$$

where $\delta_{i j}$ is the Euclidean distance between estimated positions of firm $i$ and $j$

[^7]in a 2-dimensional space and $w_{i j}$ is a weight.
We estimate the distribution of firms in a technological space by a dynamic procedure. First, we run MDS over the first 5-year window, $\tau=1$ (1976-1980 except subcategory 33 (biotechnology), which starts with 1986-90 because only a few firms apply patents in this subcategory until the late 1980s.), with the dissimilarity matrix, $D_{1} .{ }^{12}$ Let $X_{1}$ be the resultant distribution of firms. Next, to find the locations of firms within the second 5 -year window, we consider a dissimilarity matrix, $\mathscr{D}_{2}$ defined in (6) and run MDS under the constraint that the locations of firms within the previous 5 -year window, $X_{1}$, are fixed. The initial distribution of the MDS procedure at this stage consists of $X_{1}$, which is predetermined, and a random distribution of firms in $\tau=2$. Since the outcome contains both $X_{1}$ and $X_{2}$, we omit $X_{1}$ to get $X_{2}$. This process is repeated until the final 5-year window.

Since infinite dissimilarity ( or $\omega_{i j}=0$ ) cannot be processed by the MDS procedure, the standard code for MDS ignores such information and allocates random distance without any restriction. ${ }^{13}$ In our procedure, we dropped firm $i$ if $\omega_{i j}=0$ for any $j .{ }^{14}$ Even after we dropped all firms that do not have any technological relatives, it is not rare to have some $\omega_{i j}$ equals zero. For such pairs of firms, we impose the following constraint in our MDS procedure:

$$
\left(w_{i j}, d_{i j}\right)= \begin{cases}\left(1,-\log \bar{\omega}_{i j}\right) \quad \text { if } \delta_{i j}<-\log \bar{\omega}_{i j}  \tag{8}\\ (0, \text { not defined }) & \text { otherwise }\end{cases}
$$

where

$$
\begin{equation*}
\bar{\omega}_{i j} \equiv \frac{2}{\left|C_{i}\right|+\left|C_{j}\right|} . \tag{9}
\end{equation*}
$$

In words, the weight on $d_{i j}$ is zero and relative locations of firm $i$ and $j$ are randomly determined as long as the resulting distance $\delta_{i j}$ is not shorter than the threshold level, $-\log \bar{\omega}_{i j}$, where $\bar{\omega}_{i j}$ is the first-order overlap as if they have just

[^8]

Figure 2: Example of post-MDS firm distribution. Technological subcategory 46 (Semiconductor devices). The top row is the MDS result and the second row is the contours of the estimated density by 2-dimensional kernel density estimation.
one direct citation overlap. But once $\delta_{i j}$ is closer than the threshold level, the weight is set at 1 and a positive value is added to the stress, (7), according to the gap from the threshold. ${ }^{15}$

Figure 2 is an example of firm distribution estimated by MDS for mutually exclusive 5 -year windows. The five panels in the top row are firm distributions in each 5 -year window. The panels in the bottom row draw contours of estimated densities of those firm distributions by using kernel density estimation (lighter color indicates greater density). We estimated these distributions for all subcategories and all 5-year moving windows in the sample.

MDS estimates distances among entities and generates a map satisfying these distances. The stress defined in (7) is neutral for rotation and inversion of the whole map. Since we consider the dynamic dissimilarity matrix to bridge different 5-year windows, the orientations are anchored by distributions in the previous 5-year windows. However, notice that the axes in Figure 2 do not have any

[^9]

Figure 3: Average dissimilarity/distance.
meaning. Firms are just distributed with the estimated relative positioning. ${ }^{16}$

### 2.3 Average Dissimilarity and Distances after MDS

Figure 3 shows the average dissimilarity and the average post-MDS distance among subcategories. The weighted dissimilarity/distance are a weighted average of those with weights of a number of firms in each category. The figure tells us that the average technological distance on technology fields has been getting larger over time.

This fact does not specify changes in the distribution of firm location on technological maps. Figure 4 draws two examples of distributional changes when the average distance increases. The distribution may simply become more fragmented with a higher standard deviation. Alternatively, the original distribution is split into two humps, that is, there are two poles and technological groups emerge around those poles.

[^10]

Figure 4: Examples of changes in distribution, given an increase in the average distance.

## 3 Polarization

### 3.1 A Simple Model for Inter-group Competition

Esteban and Ray (1994) presents the fundamental idea of polarization. Their definition of the measure of polarization on one-dimensional distribution is proportional to

$$
\begin{equation*}
\sum_{i}^{m} \sum_{j}^{m} n_{i}^{1+\alpha} n_{j} \delta_{i j}, \quad \alpha \in[0.25,1] \tag{10}
\end{equation*}
$$

where $i, j=1,2, \ldots, m$ are groups, $n_{i}$ is the share of group $i$, and $\delta_{i j}$ is the distance between groups. To capture inter-group competition, both homogeneity within a group and heterogeneity across groups should be accentuated because a conflict tends to be harsh when there are two large distant groups. Polarization defined in (10) satisfies these requirements, whereas inequality measures such as the Gini coefficient and the Herfindahl-Hirschman index (HHI) accentuate only one of those aspects. Esteban and Ray (2011) construct a model of group contests and describe how the overall efforts depend on the degree of inter-group competition and show that the combination of Gini, HHI, and polarization explain severity of conflicts well.

We apply this polarization measure to the distribution of firms by interpreting group contests as $\mathrm{R} \& \mathrm{D}$ races for becoming a dominant technology. Suppose that each technological category corresponds to an industry. Intra-group homogeneity matters because the probability of winning a race is higher and, moreover, more knowledge spillovers are likely in the future if more applications are created by firms with the same fundamental technology. At the same time, inter-group heterogeneity matters because firms in one technological group have
more incentive to make $\mathrm{R} \& \mathrm{D}$ to win the race when they have rivals which are technologically distant because losing firms will pay greater cost to catch up the winners' technology to survive.

Suppose there are $m \geq 1$ technology groups that compete a race for standard in a technology field. The number of firms in group $i$ is $N_{i}$. Denote $N=\sum_{i=1}^{m} N_{i}$ and $n_{i}=\frac{N_{i}}{N}$. Let $r_{i h}$ be research done by firm $h$ in group $i$ and $\frac{1}{2} r_{i h}^{2}$ is its cost. Probability of winning the race for group $i$ is

$$
\begin{equation*}
p_{i}=\frac{R_{i}}{R} \tag{11}
\end{equation*}
$$

where

$$
\begin{align*}
R_{i} & \equiv\left[\sum_{h=1}^{N_{i}} r_{i h}^{\frac{1}{\varepsilon}}\right]^{\varepsilon}-\psi \sum_{h=1}^{N_{i}} r_{i h}, \quad \varepsilon \geq 1, \psi \in(0,1),  \tag{12}\\
R & \equiv \sum_{i=1}^{m} R_{i} .
\end{align*}
$$

$R_{i}$ is the group-level aggregation of $\mathrm{R} \& \mathrm{D}$. We consider a complementarity among $\mathrm{R} \& \mathrm{D}$ activities within groups, which is represented by $\varepsilon \geq 1$. However, the complementarity effect is weaken by duplication of research. Thus, some portion of research do not contribute to the aggregate R\&D. Parameter $\psi$ stands for the degree of duplication.

The expected payoff function for firm $h$ in group $i$ has three component. The first component is the profit when the fundamental technology of group $i$ becomes the standard in the industry. We assume that the winning group grabs the whole demands in the market, so that firms in losing groups earn no profit. We assume the profit of firms in the winning group is $\frac{\bar{\pi}}{n_{i}}$. The second component comes from catch-up cost when a rival group wins. If group $j$ wins, firms in group $i$ switch their own fundamental technology to the winning technology to survive in the market. The catch-up cost depends on how different their technologies are. Let $\delta_{i j}$ be the technological distance between the two group and $S\left(\delta_{i j}\right)$ be the switching or catch-up cost. $S$ is strictly increasing and $S(0)=0$.

The third component is the cost of R\&D. In sum,

$$
\begin{align*}
\pi_{i h}\left(r_{i h}\right) & =p_{i} \frac{\bar{\pi}}{n_{i}}-\sum_{j=1}^{m} p_{j} S\left(\delta_{i j}\right)-\frac{1}{2} r_{i h}^{2}, \\
& =\frac{\bar{\pi}}{n_{i}}-\sum_{j \neq i} p_{j}\left[\frac{\bar{\pi}}{n_{i}}+S\left(\delta_{i j}\right)\right]-\frac{1}{2} r_{i h}^{2} . \tag{13}
\end{align*}
$$

Define

$$
\Delta_{i j}=\left\{\begin{array}{l}
0, \quad \text { for } j=i,  \tag{14}\\
\frac{\bar{\pi}}{n_{i}}+S\left(\delta_{i j}\right), \quad \text { for } j \neq i .
\end{array}\right.
$$

Then, we write the maximization problem for firm $h$ in group $i$ as

$$
\begin{equation*}
\max -\sum_{j=1}^{m} p_{j} \Delta_{i j}-\frac{1}{2} r_{i h}^{2} . \tag{15}
\end{equation*}
$$

At any interior solution, we have

$$
\begin{equation*}
\frac{1}{R}\left(-\psi+r_{i h}^{\frac{1}{\varepsilon}-1}\left(\sum_{l=1}^{N_{i}} r_{i l}^{\frac{1}{\varepsilon}}\right)^{\varepsilon-1}\right) \sum_{j=1}^{m} p_{j} \Delta_{i j}=r_{i h} . \tag{16}
\end{equation*}
$$

The optimal choice of $r_{i h}$ is unique and does not depend on $h$ under the current assumptions, the equilibrium is symmetric in each group. Thus, we write $r_{i}=r_{i h}$. Then condition (16) becomes

$$
\begin{equation*}
\frac{\sigma_{i}}{R} \sum_{j=1}^{m} p_{j} \Delta_{i j}=r_{i} \tag{17}
\end{equation*}
$$

where

$$
\begin{equation*}
\sigma_{i} \equiv-\psi+N_{i}^{\varepsilon-1} \tag{18}
\end{equation*}
$$

in equilibrium. $\sigma_{i}$ is the marginal contribution of individual $\mathrm{R} \& \mathrm{D}$ in a symmetric equilibrium.

Connection to Polarization Let $\rho \equiv \frac{R}{N}$ and $\mu_{i} \equiv \frac{p_{i}}{n_{i}} . \rho$ is the aggregate R\&D per firm. $\mu_{i}$ is the ratio of intra-group per-firm R\&D to the aggregate per-firm R\&D since

$$
\begin{equation*}
\mu_{i}=\frac{R_{i} / R}{N_{i} / N}=\frac{R_{i} / N_{i}}{R / N}=\frac{\sigma_{i} r_{i}}{\rho} . \tag{19}
\end{equation*}
$$

Multiply both sides of equation (17) by $\rho p_{i}$,

$$
\begin{align*}
& \rho p_{i} \frac{\sigma_{i}}{R} \sum_{j=1}^{m} p_{j} \Delta_{i j}=\rho p_{i} r_{i} \\
& \quad \Leftrightarrow \quad \sum_{j=1}^{m} p_{i} p_{j} \frac{\sigma_{i} \Delta_{i j}}{N}=\rho p_{i} r_{i} \\
& \quad \Leftrightarrow \quad \sum_{j=1}^{m} \mu_{i} \mu_{j} n_{i} n_{j} \frac{\sigma_{i} \Delta_{i j}}{N}=\rho p_{i} r_{i} \tag{20}
\end{align*}
$$

Multiply bothe sides of (20) by $\frac{\rho}{r_{i}}$ and define

$$
\begin{equation*}
\phi\left(\mu_{i}, \mu_{j}, r_{i}, \rho\right) \equiv \frac{\mu_{i} \mu_{j} \rho}{r_{i}} \tag{21}
\end{equation*}
$$

we have

$$
\begin{equation*}
\sum_{j=1}^{m} \phi\left(\mu_{i}, \mu_{j}, r_{i}, \rho\right) n_{i} n_{j} \frac{\sigma_{i} \Delta_{i j}}{N}=\rho^{2} p_{i} \tag{22}
\end{equation*}
$$

Take the summation over $i$,

$$
\begin{equation*}
\sum_{i=1}^{m} \sum_{j=1}^{m} \phi\left(\mu_{i}, \mu_{j}, r_{i}, \rho\right) n_{i} n_{j} \frac{\sigma_{i} \Delta_{i j}}{N}=\rho^{2} \tag{23}
\end{equation*}
$$

Now consider the situation in which $\phi\left(\mu_{i}, \mu_{j}, r_{i}, \rho\right)=\bar{\sigma} \equiv-\psi+\bar{N}^{\varepsilon-1}$, where $\bar{N}=\frac{N}{m}$. This condition holds when everything is symmetric among groups such that $N_{i}=N_{j}$ and $r_{i}=r_{j}$ for all $i$ and $j .{ }^{17}$ Let $\hat{\rho}$ satisfy

$$
\begin{equation*}
\hat{\rho}^{2} \equiv \sum_{i=1}^{m} \sum_{j=1}^{m} n_{i} n_{j} \frac{\bar{\sigma} \sigma_{i} \Delta_{i j}}{N} \tag{24}
\end{equation*}
$$

We consider $\hat{\rho}$ as a proxy for per-capita aggregate R\&D. Developing the right-

[^11]hand side,
\[

$$
\begin{align*}
& \sum_{i=1}^{m} \sum_{j=1}^{m} n_{i} n_{j} \frac{\bar{\sigma} \sigma_{i} \Delta_{i j}}{N} \\
& \quad=-\frac{\bar{\sigma} \psi}{N} \sum_{i=1}^{m} \sum_{j=1}^{m} n_{i} n_{j} \Delta_{i j}+\frac{\bar{\sigma}}{N} \sum_{i=1}^{m} \sum_{j=1}^{m} n_{i} n_{j} N_{i}^{\varepsilon-1} \Delta_{i j} \tag{25}
\end{align*}
$$
\]

The first term of (25) is

$$
\begin{aligned}
-\frac{\bar{\sigma} \psi}{N} \sum_{i=1}^{m} \sum_{j \neq i} n_{i} n_{j}\left(\frac{\bar{\pi}}{n_{i}}+S\left(\delta_{i j}\right)\right) & =-\frac{\bar{\sigma} \psi}{N}\left[\bar{\pi} \sum_{i=1}^{m}\left(1-n_{i}\right)+\sum_{i=1}^{m} \sum_{j \neq i} n_{i} n_{j} S\left(\delta_{i j}\right)\right] \\
& =-\frac{\bar{\sigma} \psi}{N}\left[(m-1) \bar{\pi}+\sum_{i=1}^{m} \sum_{j \neq i} n_{i} n_{j} S\left(\delta_{i j}\right)\right]
\end{aligned}
$$

The second term of (25) is

$$
\begin{aligned}
\frac{\bar{\sigma}}{N^{2-\varepsilon}} \sum_{i=1}^{m} \sum_{j \neq i} n_{i}^{\varepsilon} n_{j}\left(\frac{\bar{\pi}}{n_{i}}+S\left(\delta_{i j}\right)\right) & =\frac{\bar{\sigma}}{N^{2-\varepsilon}} \sum_{i=1}^{m}\left[\bar{\pi} n_{i}^{\varepsilon-1} \sum_{j \neq i} n_{j}+\sum_{j \neq i} n_{i}^{\varepsilon} n_{j} S\left(\delta_{i j}\right)\right] \\
& =\frac{\bar{\sigma}}{N^{2-\varepsilon}}\left[\bar{\pi}\left(\sum_{i=1}^{m} n_{i}^{\varepsilon-1}-\sum_{i=1}^{m} n_{i}^{\varepsilon}\right)+\sum_{i=1}^{m} \sum_{j=1}^{m} n_{i}^{\varepsilon} n_{j} S\left(\delta_{i j}\right)\right]
\end{aligned}
$$

Summing up those terms and assume $S(\boldsymbol{\delta})=a \delta(a>0)$ for simplicity,

$$
\begin{align*}
\hat{\rho}^{2}= & -\frac{\bar{\sigma} \psi(m-1) \bar{\pi}}{N}-\frac{a \bar{\sigma} \psi}{N} \underbrace{\sum_{i=1}^{m} \sum_{j=1}^{m} n_{i} n_{j} \delta_{i j}}_{\text {average distance }} \\
& +\frac{\bar{\sigma} \bar{\pi}}{N^{2-\varepsilon}} \underbrace{\left(\sum_{i=1}^{m} n_{i}^{\varepsilon-1}-\sum_{i=1}^{m} n_{i}^{\varepsilon}\right)}_{\text {fragmentation }}+\frac{a \bar{\sigma}}{N^{2-\varepsilon}} \underbrace{\sum_{i=1}^{m} \sum_{j=1}^{m} n_{i}^{\varepsilon} n_{j} \delta_{i j}}_{\text {polarization }} \tag{26}
\end{align*}
$$

The average individual $R \& D$ is related to three distributional statistics: the average distance (the summation in the second term); fragmentation or negative of concentration, the parenthesis in the third term, which is equivalent to 1 minus HHI when $\varepsilon=2$; and the polarization (when $\varepsilon$ is in the appropriate region), the summation in the forth term.

In the current model, technological distance stimulate individual R\&D because a losing firm must pay higher cost to catch up the new mainstream tech-
nology if the winning group is further away in the technology space. This aspect is captured by polarization and thus the coefficient is positive. But at the same time, more efforts imply more duplications in research within groups. Hence, the $\mathrm{R} \& D$ incentive stimulated by distance is weaken by degree of duplication, which is represented in the negative sign on the average distance. The degree of fragmentation has a positive coefficient, in other words, concentration works negatively because of the free-rider's problem.

Keeping the current model in mind, we move to continuous technology space and introduce the extended version for continuous distributions which is developed by DER in the next subsection.

### 3.2 Polarization Measure on Two-dimensional Spaces

DER extend the measure of polarization in (10) to be applicable for continuous distributions. Our polarization measure follows DER,

$$
\begin{equation*}
P^{\alpha}(f) \equiv \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} f(x)^{1+\alpha} f(y) \delta(x, y) d y d x \tag{27}
\end{equation*}
$$

where $f$ is the density of firms, $\delta(x, y)$ is the Euclidean distance, and $\alpha$ is a positive parameter in between $[0.2,0.5]$. Only the difference from DER is that our polarization is defined over distributions with 2-dimensional domains (onedimension in DER), which makes the valid range of $\alpha$ narrow. We can easily show that the upper bound of $\alpha$ is the inverse of the number of dimension (proof is in Appendix A). The lower bound is complicated. We describe how to get the lower bound of valid $\alpha$ also in Appendix A. In the regressions in the following section, we report the results for both bounds of $\alpha .^{18}$

The average distance, $G$, and concentration, $H$, of density $f$ are defined as follows.

$$
\begin{gather*}
G(f) \equiv \int_{\mathbb{R}^{2}} \int_{\mathbb{R}^{2}} f(x) f(y) \delta(x, y) d y d x  \tag{28}\\
H(f) \equiv \int_{\mathbb{R}^{2}} f(x)^{2} d x \tag{29}
\end{gather*}
$$

Note that $G$ is equivalent to polarization with $\alpha=0$.
We estimate $f_{k \tau}$, the density of firms in category $k$ and period $\tau$, by the

[^12]

Figure 5: Average polarization indices.

2-dimensional kernel density estimation (2D-KDE). ${ }^{19}$ Let $\hat{f}_{k \tau}$ be the estimated distribution. The estimates of (27)-(29) over firm locations on technological fields obtained by the procedure in Section 2, $X_{k \tau}=\left\{x_{1}, x_{2}, \ldots, x_{n_{k \tau}}\right\}$, are

$$
\begin{align*}
& \hat{P}_{k \tau}^{\alpha} \equiv \frac{1}{n_{k \tau}^{2}} \sum_{i=1}^{n_{k \tau}} \sum_{j=1}^{n_{k \tau}} \hat{f}_{k \tau}\left(x_{i}\right)^{\alpha} \delta\left(x_{i}, x_{j}\right),  \tag{30}\\
& \hat{H}_{k \tau} \equiv \frac{1}{n_{k \tau}} \sum_{i=1}^{n_{k \tau}} \hat{f}_{k \tau}\left(x_{i}\right) . \tag{31}
\end{align*}
$$

$\hat{G}_{k \tau}$ is the special case with $\alpha=0$ in (30), thus

$$
\begin{equation*}
\hat{G}_{k \tau} \equiv \frac{1}{n_{k \tau}^{2}} \sum_{i=1}^{n_{k \tau}} \sum_{j=1}^{n_{k \tau}} \delta\left(x_{i}, x_{j}\right) \tag{32}
\end{equation*}
$$

Figure 5 depicts the estimated polarizations averaged over subcategories. The weighted average is computed by setting the share of the number of firms within each period ( 5 -year window) as weights for the subcategories. Clearly, the average polarizations have upward trends regardless of the values of $\alpha$.

[^13]Table 1 shows the descriptive statistics that are used in regressions in the next section.

Table 1: Summary statistics.

|  | Obs. | Mean | SD | Min | Max |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Average dissimilarity | 649 | 6.160758 | .6917609 | 2.632249 | 7.368289 |
| $\hat{G}$ | 647 | 6.032016 | .6695385 | 2.353421 | 7.570821 |
| $\hat{P}^{0.2}$ | 639 | 2.12773 | .1579996 | 1.472612 | 2.530501 |
| $\hat{P}^{0.5}$ | 639 | .4595821 | .0249231 | .3863933 | .5175242 |
| $\hat{H}$ | 639 | .0070822 | .0014643 | .0042083 | .014769 |
| Num. of firms | 651 | 246.4101 | 141.7449 | 0 | 1019 |
| Stress | 647 | .3729808 | .0617119 | $5.09 \mathrm{e}-09$ | .4728863 |
| Num.patent app. | 648 | 3812.71 | 4782.57 | 1 | 40835 |
| CW.patent app. | 648 | 43875.55 | 56416.79 | 2 | 335869 |

## 4 The Impact of Polarization on Innovation

### 4.1 Basic Results

In this section, we investigate the empirical relationship between polarization and innovation. For the measure of innovation, we use citation-weighted number of patent applications, $a_{k t}$, where $k$ is subcategory and $t$ is year of application. Note that we denote $t$ as a year and $\tau(t)$ as the 5 -year window from $t-5$ to $t-1$. Below, we estimate the impact of the distribution properties during $\tau(t)$ on innovations in $t$.

It is important to note that the citation-weighted patent applications after the late 1990s are less informative in our sample and, thus, we drop the citationweighted patent application in and after 1998 from our estimation. Figure 6 illustrates the citation-weighted patent applications over the sample periods. The citation-weighted patent applications hit a peak around 1995 and declined sharply after 1997, whereas the unweighted patent applications continue to increase. This is simply because of the time lags between application and citation. Since the NBER US Patent dataset contains only granted patents, citation-weights are


Figure 6: Non- and citation-weighted number of patent applications.
highly affected by this time-lag problem. ${ }^{20}$
Since $a_{k t}$ is count data, we apply the Poisson regression model and the negative binomial regression model. The equation to be estimated with these models is

$$
\begin{align*}
a_{k t} & =\exp \left\{\beta_{0}^{a}+\beta_{1}^{a} \log \hat{P}_{k, \tau(t)}^{\alpha}+\beta_{2}^{a} \log \hat{H}_{k, \tau(t)}+\beta_{3}^{a} \log \hat{G}_{k, \tau(t)}\right. \\
& \left.+\beta_{4}^{a} \log A_{k, \tau(t)}+\beta_{5}^{a} \log Y_{k, \tau(t)}+\beta_{6}^{a} \log L_{k, \tau(t)}+\beta_{7}^{a} v_{k}+\beta_{8}^{a} v_{t}+\varepsilon_{k t}^{a}\right\} \tag{33}
\end{align*}
$$

where $A_{k, \tau(t)}$ is the citation-weighted stock of patents at the beginning of $\tau(t)$ as the proxy of knowledge stock in the subcategory (described in detail in Appendix B), $Y_{k, \tau(t)}$ is the average of total sales of all related firms during $\tau(t), L_{k, \tau(t)}$ is the average of total employment of those firms, and $v_{k}$ and $v_{t}$ are dummy variables for subcategories and years. This regression evaluates the impact of distribution properties during the past 5 years on the amount of new innovations.

We also consider the impact of distribution properties on growth rate of citation-weighted applications over 5 -year windows, $\gamma_{k t} \equiv \frac{a_{k t}}{a_{k t-5}}-1$. The equa-

[^14]tion to be estimated by panel regression with subcategory fixed effects is
\[

$$
\begin{align*}
\gamma_{k t}= & \beta_{0}^{\gamma}+\beta_{1}^{\gamma} \log \hat{P}_{k, \tau(t)}^{\alpha}+\beta_{2}^{\gamma} \log \hat{H}_{k, \tau(t)}+\beta_{3}^{\gamma} \log \hat{G}_{k, \tau(t)} \\
& +\beta_{4}^{\gamma} \log A_{k, \tau(t)}+\beta_{5}^{\gamma} \log Y_{k, \tau(t)}+\beta_{6}^{\gamma} \log L_{k, \tau(t)}+\beta_{7}^{\gamma} v_{k}+\beta_{8}^{\gamma} v_{t}+\varepsilon_{k t}^{\gamma} . \tag{34}
\end{align*}
$$
\]

Table 2 shows the regression results. Columns (1-6) omitted explanatory variables about knowledge stock and business size (all regressions include subcategory and year dummies). Because citation-weighted patents are count data and highly skewed, the negative binomial regression is appropriate. Columns (3) and (4) report significant positive coefficient on polarization with both the upper and lower boundaries of $\alpha$, and significantly negative coefficients for concentration and the average distance. These signs are consistent with the model in Section 3.1. The change rate of citation-weighted patent applications, $\gamma_{k t}$, also have similar results (Columns (5) and (6), linear regressions). However, this result is not robust. Looking at Columns (1) and (2), which conduct Poisson regressions, we find the opposite signs of coefficients for polarization. Since the estimates of Poisson regression are consistent regardless of the distributional assumption, we need to change the model specification.

Columns (7-12) are results controlled by knowledge stock and business sizes. The knowledge stock has a positive impact on levels of innovation $a_{k t}$ and negative but insignificant impact on growth of innovation. These are natural results in the knowledge accumulation process. The sales volume always has a positive impact because it represents size of demands for subcategories. The coefficients of employment are negative most probably because the combination of sales and employment represents average productivity. The inconsistency between Poisson and negative binomial regressions seen before is now resolved. However, the significance levels in negative binomial regressions (Columns (9) and (10)) becomes low and the sign of coefficients are inconsistent with the model. Only the regressions (11) and (12) about $\gamma_{k t}$ weakly keep the consistency with the model and previous simple model specification.

So far, our hypothesis of inter-group competition does not seem to work well. And the characteristics of firm distributions in technology spaces are not related to aggregate innovations. But this result drastically changes if we split the sample by years. We consider a structural shift in the next subsection.

Table 2: Citation-weighted patent application vs polarization measures.

|  | (1)Poisson | (2)Poisson | (3)NegBin | (4)NegBin | (5) | (6) | (7)Poisson | (8)Poisson | (9)NegBin | (10)NegBin | (11) | (12) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $a_{k t}$ | $a_{k t}$ | $a_{k t}$ | $a_{k t}$ | $\gamma_{k t}$ | $\gamma_{k t}$ | $a_{k t}$ | $a_{k t}$ | $a_{k t}$ | $a_{k t}$ | $\gamma_{k t}$ | $\gamma_{k t}$ |
| $\log \hat{P}_{k \tau(t)}^{0.2}$ | $\begin{gathered} -2.726^{* * *} \\ (-38.78) \end{gathered}$ |  | $\begin{gathered} 4.843^{* * *} \\ (2.82) \end{gathered}$ |  | $\begin{gathered} 6.148^{* * *} \\ (3.27) \end{gathered}$ |  | $\begin{gathered} -3.492^{* * *} \\ (-48.89) \end{gathered}$ |  | $\begin{aligned} & -2.222 \\ & (-1.58) \end{aligned}$ |  | $\begin{gathered} 5.248^{* * *} \\ (2.64) \end{gathered}$ |  |
| $\log \hat{P}_{k \tau(t)}^{0.5}$ |  | $\begin{gathered} -2.111^{* * *} \\ (-57.41) \end{gathered}$ |  | $2.049^{* *}$ <br> (2.18) |  | $2.340^{* *}$ <br> (2.26) |  | $\begin{gathered} -2.154^{* * *} \\ (-57.87) \end{gathered}$ |  | $-1.154$ (-1.53) |  | 1.718 <br> (1.60) |
| $\log \hat{H}_{k \tau(t)}$ | $\begin{gathered} -0.370^{* * *} \\ (-35.79) \end{gathered}$ | $0.0230^{*}$ <br> (1.66) | $\begin{gathered} -0.488^{* *} \\ (-2.07) \end{gathered}$ | $\begin{gathered} -0.665^{* *} \\ (-2.05) \end{gathered}$ | $\begin{gathered} -0.480^{*} \\ (-1.86) \end{gathered}$ | $-0.633^{*}$ <br> (-1.78) | $\begin{gathered} 0.173^{* * *} \\ (16.40) \end{gathered}$ | $\begin{gathered} 0.506^{* * *} \\ (36.15) \end{gathered}$ | $\begin{aligned} & 0.0395 \\ & (0.22) \end{aligned}$ | 0.182 <br> (0.73) | $-0.434^{*}$ <br> (-1.66) | $\begin{aligned} & -0.500 \\ & (-1.39) \end{aligned}$ |
| $\log \hat{G}_{k \tau(t)}$ | $\begin{gathered} 1.199^{* * *} \\ (19.23) \end{gathered}$ | $\begin{gathered} 0.413^{* * *} \\ (12.58) \end{gathered}$ | $\begin{gathered} -4.109^{* * *} \\ (-2.80) \end{gathered}$ | $\begin{gathered} -1.519^{* *} \\ (-1.97) \end{gathered}$ | $\begin{gathered} -6.291^{* * *} \\ (-3.92) \end{gathered}$ | $\begin{gathered} -2.834^{* * *} \\ (-3.35) \end{gathered}$ | $\begin{gathered} 1.927^{* * *} \\ (30.62) \end{gathered}$ | $\begin{gathered} 0.523^{* * *} \\ (15.83) \end{gathered}$ | $\begin{aligned} & 0.873 \\ & (0.75) \end{aligned}$ | $\begin{aligned} & -0.166 \\ & (-0.28) \end{aligned}$ | $\begin{gathered} -5.633^{* * *} \\ (-3.40) \end{gathered}$ | $\begin{gathered} -2.550^{* * *} \\ (-3.00) \end{gathered}$ |
| $\log A_{k \tau(t)}$ |  |  |  |  |  |  | $\begin{aligned} & 0.851^{* * *} \\ & (203.35) \end{aligned}$ | $\begin{aligned} & 0.846^{* * *} \\ & (202.16) \end{aligned}$ | $\begin{gathered} 0.636^{* * *} \\ (8.47) \end{gathered}$ | $\begin{gathered} 0.638^{* * *} \\ (8.49) \end{gathered}$ | -0.0668 <br> (-0.62) | $-0.0745$ <br> (-0.69) |
| $\log Y_{k \tau(t)}$ |  |  |  |  |  |  | $\begin{aligned} & 0.791^{* * *} \\ & (111.48) \end{aligned}$ | $\begin{aligned} & 0.794^{* * *} \\ & (112.09) \end{aligned}$ | $\begin{gathered} 0.681^{* * *} \\ (6.73) \end{gathered}$ | $\begin{gathered} 0.677^{* * *} \\ (6.71) \end{gathered}$ | $\begin{gathered} 0.426^{* * *} \\ (2.94) \end{gathered}$ | $\begin{gathered} 0.460^{* * *} \\ (3.17) \end{gathered}$ |
| $\log L_{k \tau(t)}$ |  |  |  |  |  |  | $\begin{gathered} -0.517^{* * *} \\ (-62.07) \end{gathered}$ | $\begin{gathered} -0.520^{* * *} \\ (-62.38) \end{gathered}$ | $\begin{gathered} -0.404^{* * *} \\ (-3.22) \end{gathered}$ | $\begin{gathered} -0.405^{* * *} \\ (-3.22) \end{gathered}$ | $\begin{gathered} -0.476^{* * *} \\ (-2.68) \end{gathered}$ | $\begin{gathered} -0.487^{* * *} \\ (-2.73) \end{gathered}$ |
| Const. | $\begin{aligned} & 6.507^{* * *} \\ & (191.02) \end{aligned}$ | $\begin{aligned} & 6.163^{* * *} \\ & (183.85) \end{aligned}$ | $\begin{gathered} 9.689^{* * *} \\ (12.20) \end{gathered}$ | $\begin{gathered} 9.399^{* * *} \\ (11.56) \end{gathered}$ | $\begin{gathered} 4.596^{* * *} \\ (5.34) \end{gathered}$ | $\begin{gathered} 4.065^{* * *} \\ (4.62) \end{gathered}$ | $\begin{aligned} & -7.538^{* * *} \\ & (-136.47) \end{aligned}$ | $\begin{aligned} & -7.644^{* * *} \\ & (-140.45) \end{aligned}$ | $\begin{gathered} -4.448^{* * *} \\ (-4.47) \end{gathered}$ | $\begin{gathered} -4.394^{* * *} \\ (-4.45) \end{gathered}$ | $\begin{gathered} 3.379^{* * *} \\ (2.59) \end{gathered}$ | $\begin{gathered} 2.454^{*} \\ (1.90) \end{gathered}$ |
| Overdispersion |  |  | $\begin{gathered} -2.686^{* * *} \\ (-43.40) \end{gathered}$ | $\begin{gathered} -2.680^{* * *} \\ (-43.31) \end{gathered}$ |  |  |  |  | $\begin{gathered} -3.221^{* * *} \\ (-51.47) \end{gathered}$ | $\begin{gathered} -3.221^{* * *} \\ (-51.46) \end{gathered}$ |  |  |
| $N$ | 516 | 516 | 516 | 516 | 516 | 516 | 516 | 516 | 516 | 516 | 516 | 516 |
| adj. $R^{2}$ |  |  |  |  | 0.143 | 0.133 |  |  |  |  | 0.154 | 0.146 |
| pseudo $R^{2}$ | 0.947 | 0.947 | 0.146 | 0.146 |  |  | 0.978 | 0.978 | 0.172 | 0.172 |  |  |

$t$-statistics in parentheses. All regressions consider fixed effects of technological categories and year dummies
${ }^{*} p<0.10,{ }^{* *} p<0.05,{ }^{* * *} p<0.01$

### 4.2 A Structural Change through 1980s

In response to "productivity slow down" from 1970s, industries in the United States had experienced major institutional changes. The biggest issue related to the current context is the patent reform. The patent policy in the United States had dramatically shifted from anti-patent to pro-patent through the early 1980s. Patents had become much more valuable than before and patenting a technology or idea has become one of the most important strategies for firms. At the same time, Jaffe and Lerner (2004) point out that the reform significantly reduced the quality of patent examination because of the flood of patent applications. ${ }^{21}$

This structural shift might affect the relationship between polarization and innovation. Our interpretation of polarization as the degree of inter-group competition may not hold if a bunch of useless patents clustering around some main technologies. More importantly, under the pro-patent system, inter-group competition may stimulate patent litigation rather than R\&D investment, which discourages innovation (Lanjouw and Schankerman (2004)).

To see whether any structural shift exists, we conducted the Chow test to the above negative binomial regression. Figure 7 illustrates the log-likelihood ratio test statistics for each cut-off year. We can see there is a highly significant structural change between former periods and later periods and the peak of significance is 1990. Since the estimations tell the impact of polarization in the preceding 5 years on the patent applications in the current year, the threshold of 1990 implies the polarization of distribution within 1985-1989, around that time the patent reform prevailed.

Table 3 reports the regression results using equations (33) and (34) for samples divided into periods before 1990 and after. We can see a clear structural change between the results. For $t \leq 1990$ (Columns (1)-(4)), the estimates of polarization is significantly positive. Further, the coefficients of HHI and the average distance have signs that are consistent with the model in the previous section and they are mainly significant. To the contrary, the results for $t>1990$ (Columns (5)-(8)) are totally different. In regressions (5) and (6), all coefficients are highly significant but the signs of the coefficients for distributional characteristics are reversed. The story of inter-group competition cannot be applied.

[^15]

Figure 7: Log-likelihood ratio statistics. All cutoff years reject the null hypothesis that former and latter periods separated the cut-offs are nested in the full sample regression.

Figure 8 illustrates the relationship between polarization (for $\alpha=0.5$ ) and the number of patent applications after controlled by the other variables for samples before and in 1990, after 1990, and for the full sample.

The impacts of polarization are not small quantitatively. The non-weighted average polarizations illustrated in Figure 5 change by $3.8 \%$ and $2.6 \%$ in the former period for $\alpha=0.2$ and 0.5 , respectively, and by $5.2 \%$ and $2.6 \%$ in the later period for $\alpha=0.2$ and 0.5 , respectively. Hence, the occurrence of innovations is increased by $4.1 \%-11.6 \%$ through the surge in polarization in the former period and it is decreased by $9.1 \%-35.9 \%$ through the surge in polarization in the later period.

We can attribute the source of the drastic change of the regression results to the change in the impact of polarization on average patent quality, measured by the average number of foward citations. Table 4 reports the regression results where we take the average quality of the patent as the dependent variable in regression equation (34). All regressions include both subcategory and year dummies. As seen in regressions (3)-(4) in Table 4, polarization reduces patent quality only after 1990. Moreover, the estimated coefficients for distributional

Table 3: Regressions by year groups.

|  | $t \leq 1990$ |  |  |  | $t>1990$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | (1) | (2) | (3) | (4) | (5) | (6) | (7) | (8) |
|  | $a_{k t}$ | $a_{k t}$ | $\gamma_{k t}$ | $\gamma_{k t}$ | $a_{k t}$ | $a_{k t}$ | $\gamma_{k t}$ | $\gamma_{k t}$ |
| $\log \hat{P}_{k \tau(t)}^{0.2}$ | $\begin{gathered} 3.053^{* *} \\ (2.25) \end{gathered}$ |  | $\begin{gathered} 7.873^{* * *} \\ (3.05) \end{gathered}$ |  | $\begin{gathered} -6.885^{* * *} \\ (-3.29) \end{gathered}$ |  | $\begin{aligned} & 4.864 \\ & (1.36) \end{aligned}$ |  |
| $\log \hat{P}_{k \tau(t)}^{0.5}$ |  | $\begin{gathered} 1.564^{* *} \\ (2.16) \end{gathered}$ |  | $\begin{gathered} 4.050^{* * *} \\ (2.94) \end{gathered}$ |  | $\begin{gathered} -3.479^{* * *} \\ (-2.84) \end{gathered}$ |  | $\begin{aligned} & 1.865 \\ & (0.89) \end{aligned}$ |
| $\log \hat{H}_{k \tau(t)}$ | $\begin{aligned} & -0.283 \\ & (-1.54) \end{aligned}$ | $\begin{gathered} -0.472^{*} \\ (-1.88) \end{gathered}$ | $\begin{aligned} & -0.425 \\ & (-1.21) \end{aligned}$ | $\begin{aligned} & -0.918^{*} \\ & (-1.91) \end{aligned}$ | $\begin{gathered} 0.922^{* * *} \\ (3.22) \end{gathered}$ | $\begin{gathered} 1.332^{* * *} \\ (3.24) \end{gathered}$ | $\begin{aligned} & -0.169 \\ & (-0.35) \end{aligned}$ | $\begin{aligned} & -0.299 \\ & (-0.43) \end{aligned}$ |
| $\log \hat{G}_{k \tau(t)}$ | $\begin{gathered} -2.816^{* *} \\ (-2.44) \end{gathered}$ | $\begin{gathered} -1.355^{* *} \\ (-2.32) \end{gathered}$ | $\begin{gathered} -6.065^{* * *} \\ (-2.76) \end{gathered}$ | $\begin{gathered} -2.310^{* *} \\ (-2.07) \end{gathered}$ | $\begin{gathered} 6.349^{* * *} \\ (3.62) \end{gathered}$ | $\begin{gathered} 3.121^{* * *} \\ (3.16) \end{gathered}$ | $\begin{gathered} -5.926^{* *} \\ (-1.98) \end{gathered}$ | $\begin{gathered} -3.275^{*} \\ (-1.96) \end{gathered}$ |
| $\log A_{k \tau(t)}$ | $\begin{gathered} 0.334^{* * *} \\ (3.61) \end{gathered}$ | $\begin{gathered} 0.335^{* * *} \\ (3.63) \end{gathered}$ | $\begin{aligned} & -0.236 \\ & (-1.33) \end{aligned}$ | $\begin{aligned} & -0.232 \\ & (-1.31) \end{aligned}$ | $\begin{gathered} 0.438^{* * *} \\ (3.16) \end{gathered}$ | $\begin{gathered} 0.437^{* * *} \\ (3.13) \end{gathered}$ | $\begin{aligned} & 0.140 \\ & (0.59) \end{aligned}$ | $\begin{aligned} & 0.134 \\ & (0.57) \end{aligned}$ |
| $\log Y_{k \tau(t)}$ | $\begin{gathered} 1.145^{* * *} \\ (8.07) \end{gathered}$ | $\begin{gathered} 1.153^{* * *} \\ (8.15) \end{gathered}$ | $\begin{gathered} 1.001^{* * *} \\ (3.73) \end{gathered}$ | $1.021^{* * *}$ (3.81) | $\begin{gathered} 1.189^{* * *} \\ (4.77) \end{gathered}$ | $\begin{gathered} 1.179^{* * *} \\ (4.69) \end{gathered}$ | $\begin{gathered} 1.147^{* * *} \\ (2.74) \end{gathered}$ | $\begin{gathered} 1.177^{* * *} \\ (2.79) \end{gathered}$ |
| $\log L_{k \tau(t)}$ | $\begin{gathered} -0.791^{* * *} \\ (-4.82) \end{gathered}$ | $\begin{gathered} -0.797^{* * *} \\ (-4.87) \end{gathered}$ | $\begin{gathered} -1.190^{* * *} \\ (-3.85) \end{gathered}$ | $\begin{gathered} -1.205^{* * *} \\ (-3.90) \end{gathered}$ | $\begin{gathered} -1.052^{* * *} \\ (-4.09) \end{gathered}$ | $\begin{gathered} -1.085^{* * *} \\ (-4.17) \end{gathered}$ | $\begin{gathered} -0.932^{* *} \\ (-2.17) \end{gathered}$ | $\begin{gathered} -0.924^{* *} \\ (-2.13) \end{gathered}$ |
| Const. | $\begin{gathered} -2.785^{* *} \\ (-2.12) \end{gathered}$ | $\begin{gathered} -2.901^{* *} \\ (-2.23) \end{gathered}$ | $\begin{aligned} & 2.503 \\ & (0.99) \end{aligned}$ | $\begin{aligned} & 2.202 \\ & (0.88) \end{aligned}$ | $\begin{gathered} -6.188^{* * *} \\ (-3.57) \end{gathered}$ | $\begin{gathered} -5.756^{* * *} \\ (-3.30) \end{gathered}$ | $\begin{aligned} & -3.842 \\ & (-1.28) \end{aligned}$ | $\begin{aligned} & -4.659 \\ & (-1.56) \end{aligned}$ |
| Overdispersion | $\begin{gathered} -4.027^{* * *} \\ (-48.09) \end{gathered}$ | $\begin{gathered} -4.026^{* * *} \\ (-48.08) \end{gathered}$ |  |  | $\begin{gathered} -3.790^{* * *} \\ (-38.72) \end{gathered}$ | $\begin{gathered} -3.778^{* * *} \\ (-38.58) \end{gathered}$ |  |  |
| $N$ | 300 | 300 | 300 | 300 | 216 | 216 | 216 | 216 |
| adj. $R^{2}$ |  |  | 0.240 | 0.238 |  |  | 0.098 | 0.093 |
| pseudo $R^{2}$ | 0.198 | 0.198 |  |  | 0.207 | 0.206 |  |  |

$t$-statistics in parentheses. All regressions consider fixed effects of technological categories and year dummies.
${ }^{*} p<0.10,{ }^{* *} p<0.05,{ }^{* * *} p<0.01$


Figure 8: The relationship between polarization and the number of patent applications after controlled by other variables. $\alpha=0.5$.
characteristics are quite similar to those in regressions (5)-(6) in Table 3. In the later periods, the amount of innovation negatively responds to inter-group competition through reduction in quality of each patent. In the environment that patents are used strategically, such as blocking, cross-licensing negotiation, and infringements, competition may induce not R\&D efforts but more rent-seeking activities to win races. This is consistent with the critique to the current US patent system developed by Jaffe and Lerner (2004): the major patent reform has caused degradation of patent quality.

## 5 Discussions

### 5.1 Truncation Problem of Forward Citation for Quality-adjusted Patents

There exist long forward citation lags as reported by Hall et al. (2001), qualityadjusted numbers of patents is exposed to the truncation problem: recent patents tend to be undervalued because they do not have sufficient time lags for subse-

Table 4: Regression on average quality of patents.

|  | $t \leq 1990$ |  | $t>1990$ |  |
| :--- | :---: | :---: | :---: | :---: |
|  | $(1)$ | $(2)$ | $(3)$ | $(4)$ |
|  | $\ln q_{k t}$ | $\ln q_{k t}$ | $\ln q_{k t}$ | $\ln q_{k t}$ |
| $\log \hat{P}_{k \tau(t)}^{0.2}$ | 0.632 |  | $-6.498^{* * *}$ |  |
|  | $(0.55)$ |  | $(-4.43)$ |  |
|  |  |  |  | $-3.273^{* * *}$ |
| $\log \hat{P}_{k \tau(t)}^{0.5}$ |  | 0.414 |  | $(-3.79)$ |
|  |  | $(0.67)$ |  |  |
|  |  |  |  |  |
| $\log \hat{H}_{k \tau(t)}$ | -0.154 | -0.218 | $0.768^{* * *}$ | $1.156^{* * *}$ |
|  | $(-0.98)$ | $(-1.02)$ | $(3.96)$ | $(4.07)$ |
| $\log \hat{G}_{k \tau(t)}$ | -0.742 | -0.498 | $5.649^{* * *}$ | $2.592^{* * *}$ |
|  | $(-0.75)$ | $(-1.00)$ | $(4.58)$ | $(3.74)$ |
| $\log A_{k \tau(t)}$ | -0.0255 | -0.0251 | $-0.368^{* * *}$ | $-0.360^{* * *}$ |
|  | $(-0.32)$ | $(-0.32)$ | $(-3.41)$ | $(-3.29)$ |
|  |  |  |  |  |
| $\log Y_{k \tau(t)}$ | 0.144 | 0.142 | $0.589^{* * *}$ | $0.570^{* * *}$ |
|  | $(1.20)$ | $(1.19)$ | $(3.34)$ | $(3.18)$ |
| $\log L_{k \tau(t)}$ | $-0.293^{* *}$ | $-0.291^{* *}$ | $-0.702^{* * *}$ | $-0.721^{* * *}$ |
|  | $(-2.12)$ | $(-2.11)$ | $(-3.86)$ | $(-3.88)$ |
| $\operatorname{Const.}$ | $3.717^{* * *}$ | $3.759^{* * *}$ | $2.859^{* *}$ | $3.280^{* * *}$ |
| $N$ | $(3.28)$ | $(3.35)$ | $(2.42)$ | $(2.75)$ |
|  | 300 | 300 | 215 | 215 |
|  | 0.050 | 0.051 | 0.755 | 0.748 |

$t$ statistics in parentheses.
${ }^{*} p<0.10,{ }^{* *} p<0.05,{ }^{* * *} p<0.01$
quent citations. To deal with this problem, we multiply citation-weighted patent applications by weights derived from the distribution of forward citation lags, introduced in Hall et al. (2001). We call this HJT weights. For consistency, we also re-estimate knowledge stock with using the HJT weights.

Table 5 shows the same estimations as before with HJT-adjusted patent applications. $a_{k t}^{H J T}$ is HJT-adjusted patent applications in category $k$ and year $t$. $q_{k t}^{H J T}$ are per-patent quality with the HJT weights.

Table 5: Estimations with HJT weights.

|  | Whole sample |  |  |  | $t \leq 1990$ |  |  |  | $t>1990$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\begin{gathered} (1) \\ a_{k t}^{H J T} \\ \hline \end{gathered}$ | $\begin{gathered} (2) \\ a_{k t}^{H J T} \\ \hline \end{gathered}$ | (3) $\ln q_{k t}^{H J T}$ | (4) $\ln q_{k t}^{H J T}$ | $\begin{gathered} (5) \\ a_{k t}^{H J T} \\ \hline \end{gathered}$ | $\begin{gathered} (6) \\ a_{k t}^{H J T} \\ \hline \end{gathered}$ | $\begin{gathered} \text { (7) } \\ \ln q_{k t}^{H J T} \\ \hline \end{gathered}$ | (8) <br> $\ln q_{k t}^{H J T}$ | $\begin{gathered} \text { (9) } \\ a_{k t}^{H J T} \\ \hline \end{gathered}$ | $\begin{gathered} (10) \\ a_{k t}^{H J T} \\ \hline \end{gathered}$ | (11) <br> $\ln q_{k t}^{H J T}$ | (12) <br> $\ln q_{k t}^{H J T}$ |
| $\log \hat{P}_{k \tau(t)}^{0.2}$ | $-1.918$ <br> (-1.37) |  | $\begin{aligned} & -1.305 \\ & (-1.30) \end{aligned}$ |  | 3.102** (2.29) |  | $\begin{aligned} & 0.641 \\ & (0.55) \end{aligned}$ |  | $\begin{gathered} -6.663^{* * *} \\ (-3.14) \end{gathered}$ |  | $\begin{gathered} -6.385^{* * *} \\ (-4.35) \end{gathered}$ |  |
| $\log \hat{P}_{k \tau(t)}^{0.5}$ |  | $\begin{aligned} & -1.025 \\ & (-1.36) \end{aligned}$ |  | $\begin{aligned} & -0.550 \\ & (-1.03) \end{aligned}$ |  | $\begin{gathered} 1.590^{* *} \\ (2.20) \end{gathered}$ |  | $\begin{aligned} & 0.417 \\ & (0.68) \end{aligned}$ |  | $\begin{gathered} -3.283^{* * *} \\ (-2.63) \end{gathered}$ |  | $\begin{gathered} -3.165^{* * *} \\ (-3.66) \end{gathered}$ |
| $\log \hat{H}_{k \tau(t)}$ | $\begin{aligned} & 0.0397 \\ & (0.22) \end{aligned}$ | $\begin{aligned} & 0.171 \\ & (0.68) \end{aligned}$ | $\begin{aligned} & 0.0711 \\ & (0.54) \end{aligned}$ | 0.121 <br> (0.67) | $\begin{aligned} & -0.283 \\ & (-1.54) \end{aligned}$ | $\begin{gathered} -0.475^{*} \\ (-1.89) \end{gathered}$ | -0.156 <br> (-0.99) | $\begin{aligned} & -0.221 \\ & (-1.03) \end{aligned}$ | $\begin{gathered} 0.917^{* * *} \\ (3.18) \end{gathered}$ | $\begin{gathered} 1.290^{* * *} \\ (3.10) \end{gathered}$ | $\begin{gathered} 0.761^{* * *} \\ (3.93) \end{gathered}$ | $\begin{gathered} 1.128^{* * *} \\ (3.97) \end{gathered}$ |
| $\log \hat{G}_{k \tau(t)}$ | $\begin{aligned} & 0.644 \\ & (0.55) \end{aligned}$ | $\begin{aligned} & -0.234 \\ & (-0.40) \end{aligned}$ | $\begin{aligned} & 0.707 \\ & (0.85) \end{aligned}$ | 0.0172 (0.04) | $\begin{gathered} -2.833^{* *} \\ (-2.46) \end{gathered}$ | $\begin{gathered} -1.349^{* *} \\ (-2.31) \end{gathered}$ | $-0.743$ <br> (-0.75) | $\begin{aligned} & -0.495 \\ & (-0.99) \end{aligned}$ | $\begin{gathered} 6.261^{* * *} \\ (3.51) \end{gathered}$ | $\begin{gathered} 3.083^{* * *} \\ (3.07) \end{gathered}$ | $\begin{gathered} 5.662^{* * *} \\ (4.59) \end{gathered}$ | $\begin{gathered} 2.626^{* * *} \\ (3.78) \end{gathered}$ |
| $\log A_{k \tau(t)}^{H J T}$ | $\begin{gathered} 0.692^{* * *} \\ (9.31) \end{gathered}$ | $\begin{gathered} 0.694^{* * *} \\ (9.34) \end{gathered}$ | $-0.0429$ <br> (-0.80) | $-0.0411$ <br> (-0.77) | $\begin{gathered} 0.342^{* * *} \\ (3.73) \end{gathered}$ | $\begin{gathered} 0.344^{* * *} \\ (3.74) \end{gathered}$ | $-0.0287$ <br> (-0.36) | $\begin{aligned} & -0.0281 \\ & (-0.36) \end{aligned}$ | $\begin{gathered} 0.489^{* * *} \\ (3.26) \end{gathered}$ | $\begin{gathered} 0.494^{* * *} \\ (3.26) \end{gathered}$ | $\begin{gathered} -0.332^{* * *} \\ (-3.23) \end{gathered}$ | $\begin{gathered} -0.324^{* * *} \\ (-3.11) \end{gathered}$ |
| $\log Y_{k \tau(t)}$ | $\begin{gathered} 0.657^{* * *} \\ (6.50) \end{gathered}$ | $\begin{gathered} 0.655^{* * *} \\ (6.50) \end{gathered}$ | $\begin{gathered} 0.252^{* * *} \\ (3.47) \end{gathered}$ | $\begin{gathered} 0.246^{* * *} \\ (3.40) \end{gathered}$ | $\begin{gathered} 1.139^{* * *} \\ (8.04) \end{gathered}$ | $\begin{gathered} 1.147^{* * *} \\ (8.12) \end{gathered}$ | $\begin{aligned} & 0.143 \\ & (1.19) \end{aligned}$ | $\begin{aligned} & 0.141 \\ & (1.18) \end{aligned}$ | $\begin{gathered} 1.130^{* * *} \\ (4.27) \end{gathered}$ | $\begin{gathered} 1.112^{* * *} \\ (4.16) \end{gathered}$ | $\begin{gathered} 0.616^{* * *} \\ (3.47) \end{gathered}$ | $\begin{gathered} 0.594^{* * *} \\ (3.29) \end{gathered}$ |
| $\log L_{k \tau(t)}$ | $\begin{gathered} -0.398^{* * *} \\ (-3.18) \end{gathered}$ | $\begin{gathered} -0.399^{* * *} \\ (-3.18) \end{gathered}$ | $\begin{gathered} -0.423^{* * *} \\ (-4.75) \end{gathered}$ | $\begin{gathered} -0.422^{* * *} \\ (-4.73) \end{gathered}$ | $\begin{gathered} -0.785^{* * *} \\ (-4.80) \end{gathered}$ | $\begin{gathered} -0.791^{* * *} \\ (-4.84) \end{gathered}$ | $\begin{gathered} -0.285^{* *} \\ (-2.06) \end{gathered}$ | $\begin{gathered} -0.284^{* *} \\ (-2.05) \end{gathered}$ | $\begin{gathered} -1.009^{* * *} \\ (-3.68) \end{gathered}$ | $\begin{gathered} -1.034^{* * *} \\ (-3.72) \end{gathered}$ | $\begin{gathered} -0.744^{* * *} \\ (-4.07) \end{gathered}$ | $\begin{gathered} -0.760^{* * *} \\ (-4.07) \end{gathered}$ |
| Const. | $\begin{gathered} -3.852^{* * *} \\ (-3.90) \\ \hline \end{gathered}$ | $\begin{gathered} -3.830^{* * *} \\ (-3.91) \end{gathered}$ | $\begin{gathered} 3.586^{* * *} \\ (5.54) \\ \hline \end{gathered}$ | $\begin{gathered} 3.718^{* * *} \\ (5.81) \\ \hline \end{gathered}$ | $\begin{gathered} -2.629^{* *} \\ (-2.02) \\ \hline \end{gathered}$ | $\begin{gathered} -2.748^{* *} \\ (-2.13) \end{gathered}$ | $\begin{gathered} 3.906^{* * *} \\ (3.46) \end{gathered}$ | $\begin{gathered} 3.947^{* * *} \\ (3.54) \end{gathered}$ | $\begin{gathered} -5.562^{* * *} \\ (-3.19) \\ \hline \end{gathered}$ | $\begin{gathered} -5.091^{* * *} \\ (-2.90) \end{gathered}$ | $2.668^{* *}$ <br> (2.27) | $\begin{gathered} 3.123^{* * *} \\ (2.64) \\ \hline \end{gathered}$ |
| Overdispersion | $\begin{gathered} -3.223^{* * *} \\ (-51.62) \end{gathered}$ | $\begin{gathered} -3.223^{* * *} \\ (-51.62) \end{gathered}$ |  |  | $\begin{gathered} -4.028^{* * *} \\ (-48.21) \end{gathered}$ | $\begin{gathered} -4.027^{* * *} \\ (-48.20) \end{gathered}$ |  |  | $\begin{gathered} -3.770^{* * *} \\ (-38.77) \end{gathered}$ | $\begin{gathered} -3.757^{* * *} \\ (-38.62) \end{gathered}$ |  |  |
| $N$ | 515 | 515 | 515 | 515 | 300 | 300 | 300 | 300 | 215 | 215 | 215 | 215 |
| adj. $R^{2}$ |  |  | 0.472 | 0.472 |  |  |  |  |  |  | 0.101 | 0.075 |
|  | 0.175 | 0.175 |  |  | 0.197 | 0.197 |  |  | 0.199 | 0.198 |  |  |

$t$-statistics in parentheses. All regressions consider fixed effects of technological categories and year dummies.
Regressions (1)-(2), (5)-(6), and (9)-(10) are negative binomial regressions. The others are linear regressions.
${ }^{*} p<0.10,{ }^{* *} p<0.05,{ }^{* * *} p<0.01$

### 5.2 Does polarization just respond to more detailed technological categories?

One possible explanation of increasing polarization is that technology has become more segmented. A new pole that emerged in a 2 -digit technological category could be a new field or a new product. If so, observed increasing polarization does not imply inter-group competition. To evaluate this possibility, we check finer primary classifications (3-digit class defined by USPTO) of patents of each firm and observe the distribution of the classifications on each technology space. More concretely, given technology maps created in Section 2, we put 3 -digit class lists for firms in each 2-digit subcategory and 5 -year window. Then take the average distances only among firms associated with each 3-digit class.

If 3-digit classes are randomly distributed, the average distances in a coarser classification is almost the same as that in finer classifications. The difference between them imply a bias from segmentation. If the average distance among 3digit classes has a decreasing trend, it implies that finer classes have concentrated on poles and thus the segmentation effect mainly explains polarization.

Figure 9 illustrates the time-series of those average distances. We draw two types of class distance. One is described above (shown as "Class" in the figure). The other is that we focus on the most important 3-digit class for each firm ("Top class only"), where the top class of a firm is defined as the class in which the firm applied patents most frequently in each 5 -year window (we include both in a tie). Naturally, the average distance within 3-digit classes tends to be lower than that within subcategories. The important fact here is that the average distance among 3-digit classes also have an upward trend. Since the trend is relatively weak so that relative distance among classes to among subcategories have been decreasing, some part of polarization should be attributed to the segmentation effect. However, it does not seem the main source of polarization.


Figure 9: The average distances within 3-digit classes.

### 5.3 Relation between the Increasing Dissimilarity and Polarization

### 5.3.1 Decomposition of Polarization

As shown in DER, the measure of polarization can be decomposed into three components. such as

$$
\begin{equation*}
P^{\alpha}=G \bar{\imath}_{\alpha}(1+\rho), \tag{35}
\end{equation*}
$$

where

$$
\begin{aligned}
g(i) & \equiv \frac{1}{n} \sum_{j=1}^{n} \delta\left(x_{i}, x_{j}\right), \quad G=\frac{1}{n} \sum_{i=1}^{n} g(i), \\
l_{\alpha}(i) & \equiv f\left(x_{i}\right)^{\alpha}, \quad \bar{\imath}_{\alpha}=\frac{1}{n} \sum_{i=1}^{n} \imath_{\alpha}(i), \\
\rho & \equiv \frac{\operatorname{Cov}\left(l_{\alpha}, g\right)}{\bar{i}_{\alpha} G},
\end{aligned}
$$

In other words, polarization equals the product of average distance, concentration with polarization parameter which DER call identification, and their nor-
malized covariance. Figure 10 depicts the time-series behaviors of unweightedaverage identification and normalized covariance for $\alpha \in\{0.2,0.5\}$ across technological categories.

When we apply the growth accounting on (35) with these averaged variables, the degree of contribution of the average distance, $\hat{G}$, is about $246 \%$ whereas $-158 \%$ from the change in identification and $12 \%$ from the change in normalized covariance if we set the initial year window as 1977-1981. ${ }^{22}{ }^{23}$ Therefore, the increasing polarization is mainly driven by increasing average technological distance, which is from increasing average dissimilarity. In the next subsection, we consider whether there exists a mechanism to derive an increasing dissimilarity in our methodology.

### 5.3.2 Citation overlaps with random citations

As the number of patents have been drastically increasing in the recent decades, the expansion of the pool of citable patents may decrease citation overlaps. This is one possible explanation of the observed upward trend in technological dissimilarity. In this subsection, we examine how plausible this explanation is by experimentation.

Suppose that two firms independently apply $p$ patents, each of them cites $m$ patents out of $N$ patents at random. Let $p$ be the average patent application per firm in each year, $m$ be the average number of patent citations of those patent applications, and $N$ be the number of patents previously granted. We consider 10 years and 25 years lag for backward citations. ${ }^{24}$ We obtain the average firstorder citation overlap from 5000 random draws of the lists of citations for each category and year from 1976 to 2000. Then we take the average of technological distances for each 5-year window.

The left panel of Figure 11 shows the average technological distances of random citation firms for 10 and 25 years backward citation lags, and the actual technological distance obtained in Section 2. The right panel is the actual dis-

[^16]

Figure 10: The average identification (left panel) and the average normalized covariance between alienation and identification (right panel) across technological categories .


Figure 11: Experimented average distances with random citation (the left panel) and the average distance in data relative to the distances with random citations (the right panel).
tance relative to the average distances with random citations. Since the average distance with random citation is considered as the baseline distance, the relative distances shown in the right panel tell us the real similarity or dissimilarity between firms. As seen in the figure, the distances with random citations are not increasing from the early 1980s. Thus, the relative distances also have increasing trends in those periods. While the citation pool have been expanded since the late 1980s, firms apply more patents and citations of each patent have been also increasing. Hence, we conclude that the observed upward trend in technological distances is not from the expansion of citation pool.

### 5.4 Technology Group?

The polarization measure is a continuous statistic and we do not identify exact poles and boundaries of technology groups. It is not clear if close firms tend to be in the same technology group in our distributions. To see the relationship among firms, we examine how distances in post-MDS distributions affect patent citation activity. Table 6 shows the results. Column (1) shows the logistic regression in which the dependent variable is whether citation occurs. Column (2) is the negative binomial regression with the number of citations as the dependent variable. Columns (3) and (4) are modifications of Column (2), where the number of citations are counted only within 5 years after granted, between 5 and 10 years after granted, respectively. The post-MDS distances negatively and non-
linearly affect citation activities, which is consistent with the idea of technology groups. All estimations include category and year dummies.

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Table 6: Distance vs. Citation

|  | $(1)$ | $(2)$ | $(3)$ | $(4)$ |
| :--- | :---: | :---: | :---: | :---: |
|  | Logit | Neg.Bin | Neg.Bin | Neg.Bin |
|  | Cite | Num. Cite | Num. Cite (<5 years) | Num. Cite $(<10$ years |
| $\delta_{i j}$ | $-0.0170^{* * *}$ | $-0.453^{* * *}$ | $-0.472^{* * *}$ | $-0.455^{* * *}$ |
|  | $(-15.87)$ | $(-270.16)$ | $(-257.14)$ | $(-224.72)$ |
| $\delta_{i j}^{2}$ | $-0.00755^{* * *}$ | $0.0200^{* * *}$ | $0.0200^{* * *}$ | $0.0199^{* * *}$ |
|  | $(-87.68)$ | $(155.15)$ | $(140.47)$ | $(126.92)$ |
| Const. | $-3.798^{* * *}$ | $-1.288^{* * *}$ | $-2.241^{* * *}$ | $-2.391^{* * *}$ |
|  | $(-510.88)$ | $(-126.09)$ | $(-187.27)$ | $(-184.13)$ |
| Overdispersion |  | $4.117^{* * *}$ | $4.228^{* * *}$ | $4.426^{* * *}$ |
|  |  | $(3990.36)$ | $(3206.80)$ | $(3000.77)$ |
| $N$ | 33321080 | 33321080 | 33321080 | 33321080 |
| pseudo $R^{2}$ | 0.054 | 0.038 | 0.051 | 0.044 |

$t$ statistics in parentheses. ${ }^{*} p<0.10,{ }^{* *} p<0.05,{ }^{* * *} p<0.01$
All regressions include fixed effects of technological categories and year dummies.

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## For Online Publication

## A The Valid Range of $\alpha$

The coefficient of polarization, $\alpha$, has the upper and lower bound to satisfy the axioms introduced in Duclos et al. (2004).

## A. 1 The Upper Bound of $\alpha$

For any density $f(x)$ on $n$-dimensional space, the measure of polarization is defined as

$$
\begin{equation*}
P^{\alpha}(f) \equiv k \iint f(x)^{1+\alpha} f(y)\|x-y\| d x d y \tag{36}
\end{equation*}
$$

where $k$ is a positive constant. Following DER, define the $\lambda$-squeezed density of $f$ as

$$
\begin{equation*}
f^{\lambda}(x) \equiv \frac{1}{\lambda^{n}} f\left(\frac{x-(1-\lambda) \mu_{f}}{\lambda}\right) \quad \text { for } \lambda \in(0,1] \tag{37}
\end{equation*}
$$

where $\mu_{f}$ is the maen of $f$.
Lemma 1 For any $\alpha>0$ and $n \in \mathbb{N}$,

$$
P^{\alpha}\left(f^{\lambda}\right)=\lambda^{1-n \alpha} P^{\alpha}(f)
$$

Proof. By definition,

$$
\begin{aligned}
P^{\alpha}\left(f^{\lambda}\right) & =k \iint f^{\lambda}(x)^{1+\alpha} f^{\lambda}(y)\|x-y\| d x d y \\
& =k \lambda^{-n(2+\alpha)} \iint f\left(\frac{x-(1-\lambda) m}{\lambda}\right)^{1+\alpha} f\left(\frac{y-(1-\lambda) m}{\lambda}\right)\|x-y\| d x d y \\
& =k \lambda^{1-n \alpha} \iint f\left(x^{\prime}\right)^{1+\alpha} f\left(y^{\prime}\right)\left\|x^{\prime}-y^{\prime}\right\| d x^{\prime} d y^{\prime} \\
& =\lambda^{1-n \alpha} P^{\alpha}(f)
\end{aligned}
$$

where we use

$$
x^{\prime} \equiv \frac{x-(1-\lambda) \mu_{f}}{\lambda}, \quad y^{\prime} \equiv \frac{y-(1-\lambda) \mu_{f}}{\lambda}
$$

and thus $\|x-y\|=\lambda\left\|x^{\prime}-y^{\prime}\right\|$.

Lemma 1 suggests that $P^{\alpha}\left(f^{\lambda}\right)$ is nondecreasing in $\lambda$ if and only if $\alpha \leq 1 / n$, which is the upper bound of $\alpha$ to satisfy Axiom 1 in DER.

## A. 2 The Lower Bound of $\alpha$

First, we quote Axiom 2 in DER:
Axiom 2 (DER) If a symmetric distribution is composed of three basic densities with the same root and mutually disjoint supports, then a symmetric squeeze of the side densities cannot reduce polarization.

In this axiom, a "basic density" is a symmetric and unimodal density with a compact support. A "root" is a normalized basic density. We modify Axiom 2 (DER) to the following Axiom 2' so that we apply it to multi-dimensional distributions.

Axiom 2' If a line-symmetric distribution is composed of two basic densities with the same root and mutually disjoint supports, then a symmetric squeeze of the densities cannot reduce polarization.

We search the lowest $\alpha$ to satisfy Axiom 2 '. First, notice that a double squeeze, i.e., a symmetric squeeze of both densities, is decomposed into an outward slide (so as to multiple the distance between the means by $1 / \lambda$ ) and a global squeeze (so as to restore the distance),

$$
\begin{equation*}
0.5 f^{\lambda}+0.5 g^{\lambda}=\overbrace{\underbrace{0.5 f_{(1 / \lambda-1)\left(\mu_{f}-\left(\mu_{f}+\mu_{g}\right) / 2\right)}+0.5 g_{(1 / \lambda-1)\left(\mu_{g}-\left(\mu_{f}+\mu_{g}\right) / 2\right)}}_{\text {outward slide with distance multiplied by } 1 / \lambda})^{\lambda}}^{\text {distance restored, while each squeezed by } \lambda}, \tag{38}
\end{equation*}
$$

where $\mu_{h}$ denotes the mean of density $h$, and $h_{d}$ denotes the density that satisfies $h_{d}(x+d)=h(x)$. The growth rate of polarization by double squeeze can be also decomposed into the two components. From Lemma 1, the response of polarization to a global squeeze is independent of densities. Therefore, the growth rate
of polarization of density (38) by a double squeeze is

$$
\begin{align*}
\frac{d \ln P^{\alpha}\left(0.5 f^{\lambda}+0.5 g^{\lambda}\right)}{d \ln (1 / \lambda)} & =n \alpha-1 \\
& +\frac{d \ln P^{\alpha}\left(0.5 f_{(1 / \lambda-1)\left(\mu_{f}-\left(\mu_{f}+\mu_{g}\right) / 2\right)}+0.5 g_{(1 / \lambda-1)\left(\mu_{g}-\left(\mu_{f}+\mu_{g}\right) / 2\right)}\right.}{d \ln (1 / \lambda)} . \tag{39}
\end{align*}
$$

The last term in the right-hand side is the growth rate by the outward slide, which we focus below.

Next, define $u$ as a uniform basic density such as

$$
u_{m, r}(x)= \begin{cases}1 /\left(\pi r^{n}\right) & \text { if }\|x-m\| \leq r  \tag{40}\\ 0 & \text { otherwise }\end{cases}
$$

A basic density $f$ is decomposed into uniform basic densities with the same mean,

$$
\begin{equation*}
f=\int u_{\mu_{f}, r} d W_{f}(r) \tag{41}
\end{equation*}
$$

for some distribution function $W_{f}$. Below, we assume $f$ is differentiable.
Now consider a distribution that consists of two disjoint symmetric basic densities, $f_{-a} / 2$ and $f_{a} / 2$. According to (41), polarization of this distribution is decomposed into average distances between decomposed uniform basic densities with different levels of double squeezes,
$P^{\alpha}\left(\frac{f_{-a}+f_{a}}{2}\right)=K_{f, \alpha} \iiint \frac{u_{-a, r}(x)+u_{a, r}(x)}{2} \frac{u_{-a, s}(y)+u_{a, s}(y)}{2}\|x-y\| d x d y d V_{f, \alpha}(r, s)$
for some constant $K_{f, \alpha}>0$ and distribution $V_{f, \alpha}$. To avoid complexity, we leave explanation for this decomposition to A.2.1.

Given (42), we can focus on the lower bound of the growth rate of such distances,

$$
\begin{equation*}
\frac{d \ln P^{\alpha}\left(\left(f_{-a}+f_{a}\right) / 2\right)}{d \ln \|a\|} \geq \inf _{r, s \leq r_{f}} \frac{d \ln \iint\left(u_{-a, r}(x)+u_{a, r}(x)\right)\left(u_{-a, s}(y)+u_{a, s}(y)\right)\|x-y\| d x d y}{d \ln \|a\|} . \tag{43}
\end{equation*}
$$

where $r_{f}$ denotes the radius of the support of $f$.
Now we focus on the 2 -dimensional case. We show that the minimand in the
right hand side of (43) is decreasing in $r$. To see this, we look into the properties of the minimand. Consider a distribution that consists of $u_{(-a, 0), r}$, where $a>0$ (for notational convenience, here we write $a$ as a scalar), and a stretched uniform basic density of $u_{(a, 0), 1}$ by $s_{1}>0$ along the horizontal axis and by $s_{2}>0$ along the vertical axis. Let

$$
\begin{equation*}
A_{r,\left(s_{1}, s_{2}\right)}(a)=\iint u_{(-a, 0), r}(x) u_{(a, 0), 1}(y)\left\|x-\left(s_{1}\left(y_{1}-a\right)+a, s_{2} y_{2}\right)\right\| d x d y . \tag{44}
\end{equation*}
$$

Then, the average distance of pairs of any two points on the support of this distribution is $\left(A_{r,\left(s_{1}, s_{2}\right)}(a)+A_{r,\left(s_{1}, s_{2}\right)}(0)\right) / 2$.

Lemma 2 For $r, s_{1}, s_{2}>0$ and $a>\left(r+s_{1}\right) / 2, A_{r,\left(s_{1}, s_{2}\right)}(a)$ and $A_{r,\left(s_{1}, s_{2}\right)}(0)$ are increasing in both $s_{1}$ and $s_{2}$, and $A_{r,\left(s_{1}, s_{2}\right)}^{\prime}(a)$ is decreasing in both $s_{1}$ and $s_{2}$.

Proof. First, consider $A_{r,\left(s_{1}, s_{2}\right)}(0)$. Note that for $y_{1}>0, \int_{-r}^{r}\left\|\left(x_{1}, 0\right)-\left(y_{1}, y_{2}\right)\right\| d x_{1}$ is increasing in $y_{1}$ since $\left\|(r, 0)-\left(y_{1}, y_{2}\right)\right\|<\left\|(-r, 0)-\left(y_{1}, y_{2}\right)\right\|$ when $y_{1}>0$. Thus, for $s>0, \int_{-s}^{s} \int_{-r}^{r}\left\|\left(x_{1}, 0\right)-\left(y_{1}, y_{2}\right)\right\| d x_{1} d y_{1} / s$ is increasing in $s$. Therefore, $A_{r,\left(s_{1}, s_{2}\right)}(0)$ is increasing in $s_{1}$. Similarly, $A_{r,\left(s_{1}, s_{2}\right)}(0)$ and $A_{r,\left(s_{1}, s_{2}\right)}(a)$ are increasing in $s_{2}$. Next, suppose $y_{1}>x_{1}$ and $y_{2}>0$. Since $\partial \|\left(x_{1}-a, x_{2}\right)-$ $\left(y_{1}, y_{2}\right) \| / \partial a=1 / \sqrt{1+\left(x_{2}-y_{2}\right)^{2} /\left(x_{1}-a-y_{1}\right)^{2}}$ is larger at $x_{2}=r$ than at $x_{2}=$ $-r, A_{r,\left(s_{1}, s_{2}\right)}^{\prime}(a)$ is decreasing in $s_{2}$.

Since for $y_{1}>x_{1}, \partial\left\|\left(x_{1}, x_{2}\right)-\left(y_{1}, y_{2}\right)\right\| / \partial y_{1}=1 / \sqrt{1+\left(x_{2}-y_{2}\right)^{2} /\left(x_{1}-y_{1}\right)^{2}}$ is increasing in $y_{1},\left(\left\|\left(x_{1}, x_{2}\right)-\left(a+\Delta, y_{2}\right)\right\|+\left\|\left(x_{1}, x_{2}\right)-\left(a-\Delta, y_{2}\right)\right\|\right) / 2$ is increasing in $\Delta \in\left(0, a-x_{1}\right)$. Thus, $A_{r,\left(s_{1}, s_{2}\right)}(a)$ is increasing in $s_{1}$. Similarly, since $\partial\left(\partial\left\|\left(x_{1}-a, x_{2}\right)-\left(y_{1}, y_{2}\right)\right\| / \partial a\right) / \partial y_{1}=\left(x_{2}-y_{2}\right)^{2} /\left(\left(x_{1}-a-y_{1}\right)^{2}+\left(x_{2}-\right.\right.$ $\left.\left.y_{2}\right)^{2}\right)^{3 / 2}$ is decreasing in $y_{1}, A_{r,\left(s_{1}, s_{2}\right)}^{\prime}(a)$ is decreasing in $s_{1}$.

Lemma 2 implies that the growth rate decreases as each radius increases, i.e., for $r^{\prime} \geq r$,

$$
\begin{align*}
& \frac{d \ln \iint\left(u_{-a, r}(x)+u_{a, r}(x)\right)\left(u_{-a, s}(y)+u_{a, s}(y)\right)\|x-y\| d x d y}{d \ln \|a\|} \\
& \quad \geq \frac{d \ln \iint\left(u_{-a, r^{\prime}}(x)+u_{a, r^{\prime}}(x)\right)\left(u_{-a, s}(y)+u_{a, s}(y)\right)\|x-y\| d x d y}{d \ln \|a\|} . \tag{45}
\end{align*}
$$

Thus, it suffices to consider the growth rate of the average distance within
uniform identical balls touching each other,

$$
\begin{align*}
\frac{d \ln P^{\alpha}\left(\left(f_{-a}+f_{a}\right) / 2\right)}{d \ln \|a\|} & \geq \lim _{r \uparrow\|a\|} \frac{d \ln \iint\left(u_{-a, r}(x)+u_{a, r}(x)\right)\left(u_{-a, r}(y)+u_{a, r}(y)\right)\|x-y\| d x d y}{d \ln \|a\|} \\
& =\left.\lim _{r \uparrow 1} \frac{d \ln P^{\alpha}\left(\left(u_{(-1-e, 0), r}+u_{(1+e, 0), r}\right) / 2\right)}{d \ln (1+e)}\right|_{e=0}, \tag{46}
\end{align*}
$$

which is also equal to the growth rate of polarization by the outward slide. Therefore, the lower bound of $\alpha$ is attained by solving the equation at such density,

$$
\begin{align*}
\lim _{\lambda \uparrow 1} & \frac{d \ln P^{\alpha}\left(\left(u_{(-1,0), 1}^{\lambda}+u_{(1,0), 1}^{\lambda}\right) / 2\right)}{d \ln (1 / \lambda)} \\
& =\left.\lim _{r \uparrow 1} \frac{d \ln P^{\alpha}\left(\left(u_{(-1-e, 0), r}+u_{(1+e, 0), r}\right) / 2\right)}{d \ln (1+e)}\right|_{e=0}+n \alpha-1=0 . \tag{47}
\end{align*}
$$

We can search numerically, which $\alpha$ makes (47) satisfy equality. We obtain $\alpha \approx 0.202 .{ }^{25}$

## A.2.1 Representation in (42)

First, remark the following fact.

## Lemma 3 If

$$
\begin{equation*}
\frac{\partial g(r)}{\partial r}=-\frac{1}{\pi r^{n}} v(r) \tag{48}
\end{equation*}
$$

$\lim _{r \rightarrow \infty} g(r)=0$, and $\lim _{r \rightarrow \infty} \int u_{(0,0), s}(r, 0) v(s) d s=0$, then

$$
\begin{equation*}
g(r)=\int u_{(0,0), s}(r, 0) v(s) d s \tag{49}
\end{equation*}
$$

Proof. For $r^{\prime}<r, u_{(0,0), s}\left(r^{\prime}, 0\right)-u_{(0,0), s}(r, 0)=1 / \pi s^{n}$ if $r^{\prime}<s<r$, and 0 otherwise. Thus, (48) implies

$$
\int u_{(0,0), s}\left(r^{\prime}, 0\right) v(s) d s-\int u_{(0,0), s}(r, 0) v(s) d s=\int_{r^{\prime}}^{r} \frac{1}{\pi s^{n}} v(s) d s=g\left(r^{\prime}\right)-g(r) .
$$

By $\lim _{r \rightarrow \infty} g(r)=0$ and $\lim _{r \rightarrow \infty} \int u_{(0,0), s}(r, 0) v(s) d s=0$, then (49) follows.
Using Lemma 3, we can show the following lemma.

[^17]Lemma 4 If $f$ is symmetric and differentiable, then, for any $\alpha$,

$$
\begin{equation*}
f^{1+\alpha}=\int u_{\mu_{f}, r} \pi r^{n}\left(-\frac{\partial f\left((r, 0)+\mu_{f}\right)}{\partial r}\right)(1+\alpha) f\left((r, 0)+\mu_{f}\right)^{\alpha} d r \tag{50}
\end{equation*}
$$

Proof. Let $g(r)=f\left((r, 0)+\mu_{f}\right)^{1+\alpha}$, and

$$
\frac{\partial g(r)}{\partial r}=(1+\alpha) \frac{\partial f\left((r, 0)+\mu_{f}\right)}{\partial r} f\left((r, 0)+\mu_{f}\right)^{\alpha}=-\frac{1}{\pi r^{n}} v(r)
$$

Then, equation (49) implies

$$
\begin{equation*}
f\left((r, 0)+\mu_{f}\right)^{1+\alpha}=\int u_{(0,0), s}(r, 0) v(s) d s \tag{51}
\end{equation*}
$$

Moreover, for any $x$, let $r=\left\|x-\mu_{f}\right\|$. Then, by the symmetry, $f(x)=f((r, 0)+$ $\left.\mu_{f}\right)$ and $u_{(0,0), s}(r, 0)=u_{\mu_{f}, s}(x)$. Thus, (51) implies (50).

Using Lemma 4 and its special case with $\alpha=0$, we can write the degree of polarization of $\left(f_{a}+f_{-a}\right) / 2$ with $a>\left\|\mu_{f}\right\|$ as

$$
\begin{aligned}
& P^{\alpha}\left(\frac{f_{-a}+f_{a}}{2}\right) \\
& \quad=\iint\left(\iint \frac{u_{-a, r}(x)+u_{a, r}(x)}{2} \frac{u_{-a, s}(y)+u_{a, s}(y)}{2}\|x-y\| d x d y\right) w(r, s) d r d s
\end{aligned}
$$

where the weight function is
$w(r, s)=\left(\frac{1}{2^{\alpha}} \pi r^{n}\left(-\frac{\partial f\left((r, 0)+\mu_{f}\right)}{\partial r}\right)(1+\alpha) f\left((r, 0)+\mu_{f}\right)^{\alpha}\right)\left(\pi s^{n}\left(-\frac{\partial f\left((s, 0)+\mu_{f}\right)}{\partial s}\right)\right)$.
$K_{f, \alpha}$ and $V_{f, \alpha}$ in equation (42) are defined from $w(r, s)$ so that $V_{f, \alpha}$ is a distribution:

$$
\begin{aligned}
K_{f, \alpha} & =k \iint w(r, s) d r d s \\
d V_{f, \alpha} & =w(r, s) d r d s
\end{aligned}
$$

## B Technological Categories and Estimation of Knowledge Capital Stock

Table 7 is the list of the 2-digit technological categories defined by USPTO.

Table 7: Technological categories.

| 1-digit categories | 2-digit categories |
| :--- | :--- |
| 1. Chemical | Agriculture, Food, Textiles (11); Coating (12); Gas (13); <br> Organic Compound (14); Resins (15) |
| 2. Computers <br> \& Communications | Communications (21); Computer Hardware \& Software (22); <br> Computer Peripherals (23); Information Storage (24) |
| 3. Drugs \& Medical | Drugs (31); Surgery \& Medical Instruments (32); <br> Biotechnology (33) |
| 4. Electrical \& Electric | Electrical Devices(41); Electrical Lighting(42); <br> Measuring \& Testing (43); Nuclear \& X-rays (44); <br>  <br> Power Systems (45); Semiconductor Devices(46) |
| 5. Mechanical | Mat. Proc \& Handling (51); Metal Working (52); <br> Motors \& Engines + Parts (53); Optics (54); <br> Transportation (55) |
| 6. Others | Agriculture, Husbandry, Food (61); Amusement Devices (62); <br> Apparel \& Textile (63); Earth Working \& Wells (64); <br> Furniture,House Fixtures (65); Heating (66); <br> Pipes \& Joints (67); Receptacles (68) |

Knowledge stock, $A_{k, \tau(t)}$, is estimated by the cumulative number of citationweighted patents applied till the beginning of $\tau(t)$, namely period $t-5$. In other words,

$$
\begin{equation*}
A_{k, \tau(t)}=\sum_{s=0}^{t-5}(1-\zeta)^{t-5-s} a_{k, s} \tag{52}
\end{equation*}
$$

where $\zeta_{k}$ is the depreciation rate of R\&D in technological category $k$. Since

Table 8: Summary of Depreciation Rates of Business R\&D Assets Based on BEA-NSF Dataset

| Industry | Depreciation rate |
| :--- | :---: |
| a. Computers \& peripheral equipment | $40 \%$ |
| b. Software | $22 \%$ |
| c. Pharmaceutical | $10 \%$ |
| d. Semiconductor | $25 \%$ |
| e. Aerospace | $22 \%$ |
| f. Communication equipment | $27 \%$ |
| g. Computer system design | $36 \%$ |
| h. Motor vehicles, bodies \& trailers, \& parts | $31 \%$ |
| i. Navigational, measuring, electromedical, \& control instruments | $29 \%$ |
| j. Scientific research \& development | $16 \%$ |

the dataset contains patents from 1951 and the initial state is not significant, we simply assume the initial knowledge stock is zero. To calculate $A_{k, \tau(t)}$, we apply the R\&D depreciation rates estimated in Li (2012). Table 8 summarizes the result reported in Li (2012) with zero gestation lag of $\mathrm{R} \& \mathrm{D}$.

By matching technological categories defined in USPTO with the list of industries in Table 8, we use depreciation rates in Table B. We assign a depreciation rate of $15 \%$ to technological categories not listed in in Table B, which is the traditional number assumed in Griliches (1958) (cf. Hall (2007) for details).

Table 9: Summary of Depreciation Rates in the Current Study

| Technological category | Depreciation rate |
| :--- | :---: |
| Communication (21) | $27 \%$ (f) |
| Computer Peripherals (23) | $40 \%$ (a) |
| Other computers \& communications (22,24) | $33 \%$ (mean of a, b, g) |
| Drugs \& Medical (31-33) | $10 \%$ (c) |
| Measuring \& Testing (43) | $29 \%$ (i) |
| Semiconductor Devices (46) | $25 \%$ (d) |
| Motors \& Engines + Parts (53) | $31 \%$ (mean of e and h) |
| Transportation (55) | $27 \%$ |

The numbers in the parentheses in the left column indicate 2-digit technological categories. The alphabets in the parentheses in the right column indicate industries described in Table 8. Depreciation rates for other categories are $15 \%$.


[^0]:    *We are grateful to Diego Comin, Ryoji Hiraguchi, Hajime Katayama, Brinja Meiseberg, Atsushi Oyama, Andrew Wait, and seminar and conference participants at GRIPS, Hitotsubashi University, Musashi University, Waseda University, Gakushuin University, JEA, WEAI, CEF, EEA, EARIE and the Workshop on Economic Growth and STI Policies, for their helpful comments and discussions. This work is supported by the Japan Society for the Promotion of Science, Grant-in-Aid C (25380220), Grant-in-Aid B (No.26285061), and the Research Institute of Science and Technology for Society, Japan Science and Technology Agency. All remaining errors are ours.
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[^1]:    ${ }^{1}$ Since we consider within-category relations between firms, the distance in the product market tends to be low and only weakly depends on technological distance. If we consider broad technology field, we should care about both types of distance as in Bloom et al. (2013). Market competition and R\&D incentive do not have a monotonic relation (Aghion et al. (2005)).
    ${ }^{2}$ Surely, knowledge spillover is not the only impact of technological distance in determining innovations. Closer relation may cause more patent infringements that discourage R\&D investment. Diversity could be a virtue of wide-spread distributions (Weitzman (1998)).

[^2]:    ${ }^{3}$ This story may be considered as a race between technological trajectories or paradigms. (cf. Dosi (1982))

[^3]:    ${ }^{4}$ Akcigit et al. (2013) define a measure based on patent-level technological distance using overlaps of technology classes among citations to measure missallocation of technology.
    ${ }^{5}$ Stuart and Podolny (1996) are interested in firms' "local search" for a new technology. Firms only have bounded information and tend to look at R\&D activities of closely-related firms. Thus, they use the "community matrix" which is developed in social psycology to describe personal familiality.
    ${ }^{6}$ http://www.nber.org/patents/. A detailed description of the dataset is in Hall et al. (2001).

[^4]:    ${ }^{7}$ Stuart and Podolny (1996) also use 5-year windows. Benner and Waldfogel (2008) recommend aggregation of patent data across years into 5- or 10-year periods.

[^5]:    ${ }^{8}$ For example, the citation list pair of $\{1,1,1,2\}$ and $\{1\}$ should be more overlapped than a pair like $\{1,2,2,2\}$ and $\{1\}$.
    ${ }^{9}$ This elimination is reasonable to avoid overevaluation of similarity. If we use all citations of $p$ in calculation and if some citations are included in the first-order overlaps, we add relation between firm $i$ 's own citations on different levels.

[^6]:    ${ }^{10}$ The average number of citations in a patent dramatically increases during the 1980s. See Hall et al. (2001).

[^7]:    ${ }^{11}$ When we apply one-dimensional MDS to our dissimilarity matrixes, we obtain the average stress of 0.55 whereas two-dimensional MDS returns 0.37 on average. This is a large gain of accuracy.

[^8]:    ${ }^{12}$ Since MDS is sensitive to initial distributions, we repeated the MDS procedure 100 times with random initial distributions and selected the outcome with the smallest stress. The initial distributions are generated by a bivariate normal distribution with mean $(0,0)$ and the same standard deviation vector as $D_{\tau}$. We also used 100 random distributions for MDS in the later stages.
    ${ }^{13}$ Our code is based on mdscale.m contained in Matlab Statistics Toolbox.
    ${ }^{14}$ The ratio of firms dropped is about $5-6 \%$ on average. It varies across categories and decreases over time.

[^9]:    ${ }^{15}$ One may consider that $d_{i j}=1-\omega_{i j}$ is a natural definition of the technological dissimilarity without constraints like (8). However, it is too restrictive in that a pair of firms without overlaps has a constant dissimilarity of 1 . Since more than $70 \%$ of pairs of firms have $\omega=0$ in our sample, attaching an arbitrary constant dissimilarity to those pairs results in firm distribution that almost ignores observed positive $\omega$ 's. Instead, we assumed that patent citation overlaps only provide partial information about technological dissimilarity. This is partly because only granted patents are recorded in the dataset, not all technology is patented, and technological relationships are not observed up to second-order overlaps. The constraint (8) introduces varying thresholds and randomness to take into account unobserved technological relations.

[^10]:    ${ }^{16}$ The figures for other subcategories and year windows are available upon request.

[^11]:    ${ }^{17}$ From equation (19), $\phi\left(\mu_{i}, \mu_{j}, r_{i}, \rho\right)=\mu_{j} \sigma_{i}$. When all variables are symmetric, $\mu_{i}=1$ for any $i$ and $\phi\left(\mu_{i}, \mu_{j}, r_{i}, \rho\right)=\bar{\sigma}$, which equals $\frac{\rho}{\bar{r}}$, or the ratio fo per-capita aggregate $\mathrm{R} \& \mathrm{D}$ to individual R\&D.

[^12]:    ${ }^{18}$ When $\alpha>0.2$, squeezing both humps of a distribution with two humps (like the bottom part in the right side of Figure 4) in a symmetric way increases polarization. When $\alpha<0.5$, squeezing the whole distribution reduces polarization.

[^13]:    ${ }^{19}$ For 2-dimensional kernel density estimation, we used the code described in Botev et al. (2010).

[^14]:    ${ }^{20}$ Hall et al. (2001) introduced weights for dealing with this problem but the current problem is not resolved because zero citation multiplied by any weight is zero.

[^15]:    ${ }^{21}$ Kortum and Lerner (1998) explain the surge in patent application during 1980s by the change in R\&D management rather than the patent reform. Hall and Ziedonis (2001) attribute the change to patent management.

[^16]:    ${ }^{22}$ If we use $1976-1980$ as the first 5 -year window, the numbers are $131 \%,-34 \%$, and $3 \%$, respectively. It is because identification in 1976-1980 year window is extremely low.
    ${ }^{23}$ Equation (35) do not exactly hold with sample statistics. Thus, we rescaled the numbers. The non-rescaled percentages sum up to $106 \%$.
    ${ }^{24} \mathrm{Hall}$ et al. (2001) report that about $50 \%$ of citations occur within 10 years after patent grant, about $75 \%$ within 25 years, and about $95 \%$ within 50 years. The result for 50 years lag for backward citations is almost the same as the result with 25 years lag in the current experimentation.

[^17]:    ${ }^{25}$ For the one-dimensional case, this procedure exactly yields 0.25 , the same lower bound in DER.

