The Design of Teacher Assignment: Theory and Evidence*

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Abstract

To assign teachers to schools, a modified version of the well-known deferred acceptance mechanism has been proposed in the literature and is used in practice. We show that this mechanism fails to be fair and efficient for both teachers and schools. We identify the unique strategy-proof mechanism that cannot be improved upon in terms of both efficiency and fairness. We show that this mechanism performs much better by adopting a large market approach and by using a rich dataset on teachers’ applications in France. For instance, the number of teachers moving from their positions more than doubles under our mechanism.

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1 Introduction

Teachers are a key determinant of student achievement, and their distribution across schools can have a major impact on achievement gaps between students from different ethnic or social backgrounds. Growing concerns that disadvantaged students may have lower access to effective teachers have given rise to policies intended to better distribute effective teachers across schools.\(^1\) However, such policies must be implemented with caution, as they might have unexpected effects on teachers’ satisfaction and, ultimately, on the attractiveness of the teaching profession.\(^2\) This raises a central question: how can we design an assignment procedure for teachers that takes into account both teachers’ preferences and schools’ demands? This paper introduces a new assignment procedure and assesses its performance.

In many countries, the labor market for teachers is highly regulated by a central administration that is in charge of assigning teachers to schools.\(^3\) In such systems, teachers submit ranked lists of school preferences, and each school has a ranking of teachers. Diverse criteria are used to rank teachers, ranging from teachers’ performance to standardized test results, teachers’ experience and geographical distance from their spouses. The central administration in charge of designing the assignment mechanism faces a fundamental constraint. Many teachers already have positions and are willing to be reassigned. In practice, tenured teachers have the right to keep their initial positions if they wish. Thus, the administration has to offer a teacher a position that he or she likes at least as much as the school to which he or she is currently assigned. In other words, the assignment of teachers must be *individually rational*.

To fulfill this constraint, a standard approach is to use a variation on the well-known deferred acceptance mechanism (Gale and Shapley (1962)) – DA, for short – to make it individually rational (Compte and Jehiel (2008), Pereyra (2013)). This variation consists of, first, artificially modifying the school’s ordering of teachers such that all teachers initially assigned to a school are moved to the top of that school’s ranking. In a second step, we run the DA mechanism using the modified priorities. This mechanism is used in the assignment of teachers to schools in France or the assignment of on-campus housing at MIT (Guillen and Kesten (2012)). While, by construction, this modified version of DA is individually rational, a first objective of this paper is to show that one loses an important property of DA: it fails to be *efficient* in the sense that one can find alternative assignments whereby both teachers and schools would be weakly – and some strictly – better off (according to the

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\(^1\)Recent initiatives in the U.S. have intended to measure teacher effectiveness and ensure that disadvantaged students have equal access to effective teachers. These policies (for instance, Race to the Top, the Teacher Incentive Fund, and the flexibility policy of the Elementary and Secondary Education Act) allow states to waive a number of provisions in exchange for a commitment to key reform principles. Additionally, the Teach for America program recruits and trains teachers to teach for at least two years in low-income communities. In the U.K., Teach First provides outstanding training for new teachers.

\(^2\)Two important issues facing the teaching profession are the increasing shortage of qualified teachers (Corcoran et al. (1994)) and the difficulty of retaining new teachers in the profession (Boyd et al. (2005)).

\(^3\)This is the case, for example, in France, Italy (Barbieri et al. (2007)), Mexico (Pereyra (2013)), Turkey (Dur and Kesten (2014)), Uruguay (Vegas et al. (2006)) and Portugal.
school’s true ranking of teachers).\footnote{Under the (standard) DA, it is well known that one can reassign teachers and make all of them better off, some strictly. However, this will be done at the expense of schools, given that the (standard) DA is in the Core and, hence, efficient. Here, in stark contrast to the standard DA, we show that, under the modified DA, both teachers and schools can be made better off. Note that, here, one has to adopt an “as if” approach and assume that schools’ ranking of teachers can be interpreted as schools’ preferences. The basic idea is that these rankings reflect normative criteria that this “as if” approach can take into account. A precise discussion of this approach is deferred to the end of the introduction (see “Two-sided efficiency with priorities”).} In addition, this Pareto improvement can be achieved while simultaneously improving fairness, i.e., we could reduce the number of teachers who are refused by a school when other teachers with lower rankings by that school are accepted. We also use standard terminology and say that such teachers and schools form a \textit{blocking pair}.

The main goal of this paper is therefore to design mechanisms that do not suffer from the same limitations as this modified version of DA. We say that matching is \textit{two-sided maximal} if (1) it Pareto dominates the initial assignment and (2) it cannot be improved upon in terms of (2i) efficiency and (2ii) fairness. This requirement is actually quite weak, and it is easily shown that two-sided maximal matchings correspond to assignments that are both Pareto efficient and individually rational on both sides of the market. To characterize two-sided maximal matchings, we provide an algorithm called the block exchange (BE) algorithm. The idea is simple: if two teachers block one another’s schools, we allow these teachers to exchange their schools. Obviously, larger exchanges involving many teachers are possible. We identify these exchanges by finding cycles in a directed graph, where a pair of school $s$ and teacher $t$ is pointing to another pair of school $s'$ and teacher $t'$ if teacher $t$ blocks school $s'$. As a teacher may be involved in several cycles, the outcome of the BE algorithm depends on the order in which we select the cycles. However, an important result of our analysis shows that any possible outcome of the BE algorithm is a two-sided maximal matching, and conversely, any two sided maximal matching can be achieved with an appropriate selection of cycles.

Then, while we obtain a plethora of different possible matchings depending on how we select cycles of exchange, our main theoretical result states that there is a unique way to select cycles that makes this algorithm strategy-proof, meaning that teachers have incentives to report their preferences truthfully. We introduce the unique strategy-proof mechanism which produces two-sided maximal matchings, and we call it the teacher-optimal BE algorithm (TO-BE) to emphasize the fact that TO-BE is a teacher-optimal selection of BE. Interestingly, this mechanism can be characterized using a simple modification of the standard top trading cycle (\textit{Shapley and Scarf (1974)}) – TTC, for short: in a first step, one modifies teachers’ preferences such that no teacher ranks as acceptable a school that considers him unacceptable. A teacher is unacceptable when a school prefers to keep a position vacant rather than assigning that teacher to the position. Once teachers’ preferences have been modified, we run TTC.

Our results on the teacher assignment problem are related to the college admission problem in two ways. First, we see the above result as the counterpart of the characterization result of the college admission problem. While DA is the unique mechanism that is efficient, fair and strategy-proof in the college admission problem, the teacher-optimal BE algorithm is the unique strategy-proof mechanism that is two-sided maximal (and thus cannot be improved
upon in terms of efficiency or fairness). Second, while, a priori, we did not wish to favor one side of the market – the BE algorithm treats schools and teachers symmetrically – once we impose incentive constraints, we ultimately favor the teacher side. Thus, imposing strategy-proofness for teachers has an important cost on the school side. This also shows that the teacher assignment problem has a similar structure to the college admission problem, in which, among the set of all fair mechanisms, only the student-optimal mechanism is strategy-proof. We show that, among the set of two-sided maximal mechanisms, only the teacher-optimal mechanism is strategy-proof.

We provide additional theoretical results in two respects. First, we consider a case in which only teachers are welfare-relevant entities. In this context, we provide a similar characterization to that obtained with the BE algorithm. Here again, we identify a large class of mechanisms depending on how cycles of exchange are selected. However, while this approach obviously favors teachers, we show – contrary to our main theoretical result – that no mechanism in this class is strategy-proof. Second, we simulate matchings in a large market approach in which preferences and schools’ rankings are drawn randomly from a rich class of distributions. In this context, we show that when the market size increases, our mechanisms perform quantitatively better than the modified DA in terms of utilitarian efficiency and the number of blocking pairs. We also identify the cost that the adoption of the unique strategy-proof mechanism could have in terms of utilitarian outcomes and the number of blocking pairs compared to a first-best approach whereby one could select any two-sided maximal mechanism. Our arguments build on techniques from random graph theory, as in Lee (2014), Che and Tercieux (2015a) and Che and Tercieux (2015b).

Finally, we use a nationwide labor market to empirically estimate the magnitude of gains and trade-offs in a real teacher assignment problem. France, like several other countries, has a highly centralized labor market; the 400,000 teachers in the public sector are civil servants. Hence, the central administration manages their recruitment, assignment to schools, and salary scale. We use data on the assignment of 10,500 teachers to regions in 2013. Exploiting the straightforward incentives of the currently employed modified version of DA, we use preferences reported by teachers to run counterfactuals and quantify the performance of our mechanisms.

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5Schools’ preferences are taken into account only by ensuring that schools are not assigned an unacceptable teacher.

6Dur et al. (2015) independently characterize the same class of mechanisms as we obtain, in which only teachers are welfare-relevant entities. They consider the allocation given by DA in a school choice environment. For each school, the authors define a set of teachers who are allowed to form a blocking pair with that school. They characterize the allocations that are (one-sided) efficient under this constraint and Pareto dominate the DA assignment. Our class of mechanisms starts from an arbitrary initial assignment, while given their motivation, they are interested only in the class improving on DA, and thus, they begin from the DA allocation. Our main message concerns the non-existence of a strategy-proof selection in our class of mechanisms. When starting from an arbitrary exogenous initial assignment (which excludes starting from the DA allocation), this result is non-trivial.

7These markets can involve a large number of agents. For instance, in France, approximately 65,000 tenured teachers ask for an assignment every year. In Turkey, 8,850 positions were filled by new teachers in 2009 (Dur and Kesten (2014)).
The results confirm that we can significantly improve upon the modified version of DA (DA∗ for short) in terms of both welfare (of teachers and schools) and blocking pairs. Of the 49 disciplines for which we ran DA∗, 30 of them (representing 95.9% of the teachers) could be simultaneously improved in these two dimensions. Compared to DA∗, the number of teachers moving from their initial assignment more than doubles under our mechanisms, and the distribution of ranks of teachers (over schools they obtain) stochastically dominates that of DA∗. Regarding fairness, the number of teachers who are not blocking with any school increases by 49%. Finally, contrary to DA∗, under our alternative mechanisms, no region has a position for which the teacher assigned to it has a lower priority than the teacher initially assigned to that position. These figures are essentially the same for the unique strategy-proof mechanism mentioned above, which makes it particularly appealing and a natural candidate for practical implementation.

Two-sided efficiency. Our notion of efficiency treats both teachers and schools as welfare-relevant entities (two-sided efficiency). At first glance, this might be surprising, as schools’ rankings of teachers (hereafter, priorities) are given by law. However, there are clear social objectives motivating the criteria used to define teacher priorities. This makes it relevant to adopt an approach “as if” schools’ priority rankings were schools’ preferences. For instance, teacher priorities at schools are determined primarily by their experience, notably in disadvantaged schools, which reflects the administration’s efforts to assign more-experienced teachers to disadvantaged students. If we were to consider teachers as the only welfare-relevant entities, teachers could exchange their positions, and thereby decrease the number of experienced teachers in disadvantaged schools. From an administrative perspective, it would be difficult to consider this a Pareto improvement, as disadvantaged students would be harmed by these assignments. Hence, a meaningful requirement would be to allow for exchanges of positions across teachers only when they do not negatively affect the experience of teachers in disadvantaged schools. This is exactly what the “as if” approach offers when we require a Pareto improvement over the initial assignment. In practice, several other criteria are used to determine teacher priorities that might also reflect broader social objectives. For instance, spousal reunification and children reunification give a priority bonus to teachers at schools close to where their spouses or children live. Again, one can easily see the social objective motivating these priorities. In this context, a meaningful requirement is to allow for exchanges of positions across teachers that are not at the expense of the experience of teachers in (possibly disadvantaged) schools, except when it can allow a teacher to join his/her family. Here again, this is what the “as if” approach provides.

Related literature. Our theoretical setup in this paper covers two standard models in matching theory. The first is the college admission problem as defined by Gale and Shapley (1962). In this context, schools have preferences that are taken into account regarding both efficiency considerations and fairness issues. Second, our model also embeds the house allocation problem as developed by Shapley and Scarf (1974). In this framework, individuals own a house and are willing to exchange their initial assignments. Hence, in this problem, only one side of the market has preferences. Among the goals in this case is ensuring that all in-
individuals eventually obtain an assignment that they weakly prefer to their initial assignment. This problem is very similar to ours, but in our context, we wish to take into account the school side in a way that is similar to the approach in the college admission problem. Despite covering important applications, this mixed model has been studied by few authors, including Guillen and Kesten (2012), who notes that the modified version of the DA mechanism is used for the allocation of on-campus housing at MIT. Compte and Jehiel (2008) and Pereyra (2013) provide results on the properties of this mechanism. They note that fairness and individual rationality are not compatible, and they propose a weakening of the notion of blocking pairs and show that the modified version of DA maximizes fairness under this weakening. By contrast, our work retains the standard definition of blocking pairs and addresses notions of maximal fairness using the usual definition. More importantly, our theoretical and empirical results highlight the high cost that maximizing their notion of fairness can have in terms of efficiency and the traditional notion of fairness.

Our work is also related to Dur and Ünver (2015), who introduce a matching model to study two-sided exchange markets (which include applications such as tuition exchanges or temporary worker exchanges). In their environment, agents initially attached to an institution are allowed to spend some time at another institution. They require that the flow of exports from an institution be equal to the flow of imports to it (a mechanism satisfying this assumption is said to be balanced). They show that, in this environment, a unique mechanism is balanced efficient (i.e., Pareto efficient within mechanisms that are balanced), student group–strategy-proof, acceptable, individually rational, and respects internal priorities. Their notion of efficiency is, like ours, two-sided, and the mechanism they characterize is a version of TTC that is similar to our teacher-optimal BE. However, our applications and theirs are quite different. In our context, when some positions are initially vacant, and some teachers are initially unassigned, we do not wish to impose any balancedness condition. For instance, returning to one of our motivations, when a position is available in a disadvantaged school, due to a teacher who retires for instance, the designer is likely to be willing to allow an effective teacher to go there, even though it may create an imbalance for both the disadvantaged school — that faces more inflows than outflows — and the school to which he is initially matched — that faces more outflows than inflows if the experienced teacher is not replaced. More generally, many mechanisms used in practice (including that used in France) allow teachers to join a school when a position is available that suggests that the balancedness condition is not well suited to our environment. More importantly, the main focus of our paper is on the conflict between efficiency and fairness. We show that DA* can be improved upon in these two dimensions, while our alternative mechanism cannot. This is orthogonal to their main points.

\footnote{Dur and Ünver (2015) report that some tuition exchange programs care about balancedness only over a moving time window (they extend some of their results to this richer environment). Therefore, under tuition exchange programs, some imbalance can be allowed for a short period of time, provided that balancedness is (approximately) satisfied over a longer time span.}
2 Teacher Assignment to Schools in France

France, like several other countries, has a highly centralized labor market for teachers.\textsuperscript{9} Since the 400,000 public school teachers in France are civil servants, the French Ministry of Education is responsible for their recruitment, assignment to schools, and salary scale.\textsuperscript{10} This gives us the opportunity to use a nationwide labor market to compare the performance of different assignment algorithms.

Prior to assignment, the central administration defines priorities for teachers using a point system, which takes into account three legal priorities: spousal reunification, disability, and having a position in a disadvantaged or violent school. Additional teacher characteristics are also accounted for to compute the score, including total seniority in teaching, seniority in the current school, time away from the spouse and/or children. This score determines schools' rankings or preferences. In this section, we will use the terms “priorities” and “preferences” interchangeably (for the motivation on this terminology, see the end of the introduction). The central administration defines the point system, which is well known by all teachers wishing to change schools.\textsuperscript{11}

The French Ministry of Education divides French territory into 31 administrative regions, which are called \textit{académies} (see the map in Appendix A). We will refer to them as \textit{regions} hereafter. Since 1999, the matching process has taken place in two successive phases. First, during a \textit{region assignment} phase, newly tenured teachers and teachers who wish to move to another region submit an ordered list of regions. A matching mechanism (described in the next section) is used to match teachers to regions, using priorities defined by the point system. This phase is managed by the central administration. Then, during the second phase, each region proceeds to \textit{school assignment}. In each region, teachers matched to it after the first phase, and teachers who already have a position in it but wish to change schools within this region report their preferences of schools in the region. The same mechanism as in Phase 1 is used to complete the matching using priorities defined by a similar point system as in Phase 1. The only difference is that teachers are limited in the number of schools that they can rank during this phase, as discussed in the empirical section (Section 5).

In 2013, just over 25,000 teachers applied in Phase 1, and approximately 65,000 submitted lists of preferred schools within a region for reassignment (i.e., in Phase 2). These figures include all newly tenured teachers who have never been assigned a position and tenured teach-

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\textsuperscript{9}Italy (Barbieri et al. (2007)), Portugal, Mexico (Pereyra (2013)), Turkey (Dur and Kesten (2014)), and Uruguay (Vegas et al. (2006))

\textsuperscript{10}Anyone who wishes to become a teacher has to pass a competitive examination that is organized once per year by the Ministry of Education. Those who pass this public sector exam will become civil servants, and thus, their salary is completely regulated by a detailed pay scale. Neither schools nor teachers can influence salary or promotions. All teachers having the same number of years of experience and having passed the same exam earn the same salary. Further details on the recruitment and assignment process are available on the Matching in Practice website: \url{http://www.matching-in-practice.eu/matching-practices-of-teachers-to-schools-france/}

\textsuperscript{11}An official list of criteria used to compute the point system is available on the government website \url{http://cache.media.education.gouv.fr/file/42/84/6/annexeI-493_365846.pdf}
ers who request a transfer. In practice, the assignment process is decomposed into as many markets as there are subjects taught – 107 – and each of which includes different amounts of teachers. Some are large, such as Sports (approximately 2,500 teachers), Contemporary Literature (approximately 2,000 teachers), and Mathematics (approximately 2,000 teachers), while others are smaller, such as Thermal Engineering (approximately 60 teachers) or Esthetician (approximately 15 teachers), with a wide range of subjects in between. As a teacher teaches only one subject, and positions are specific to a subject, the markets can be considered independent from one subject to another.\footnote{In practice, couples from different fields can submit joint applications, which connects the fields. However, we eliminated all couples from our sample. Details are provided in Appendix H.}

A lack of mobility has emerged as a concern for the Ministry. In 2013, of the 17,000 tenured teachers requesting a new assignment, only 40.9\% had their requests satisfied. Similarly, 29\% of the teachers asking to move closer to their families did not obtain a new assignment, many of them for several consecutive years. Due to the important lack of mobility, the Mediator of the French Ministry of Education (2015), responsible for resolving conflicts between the Ministry and teachers, receives approximately 700 complaints from primary and secondary school teachers every year related to assignment issues. He states that “the assignment algorithm opens doors to difficult personal situations that can eventually tarnish the quality and the investment of human resources”. An additional concern exists. Every year, many teachers who do not obtain reassignment to their desired region decide to resign or request a year off. This leaves some students without teachers and regularly requires regions to hire last-minute replacement staff who are not trained to teach. In the least attractive schools, labeled “priority education”, 30\% of teachers do not have a teaching certification, versus 7.6\% in other schools. From that perspective, one of the objectives of this paper is to show that using an alternative mechanism can significantly reduce the current lack of mobility.

\section{Basic Definitions and Motivation} \label{sec:definitions}

Consider a problem in which a finite set of teachers $T$ has to be assigned to a finite set $S$ of schools. For now, we restrict our attention to a one-to-one setting, i.e., an environment in which each school has a single seat (see Appendix G for the treatment of the many-to-one case). Each teacher $t$ has a strict preference relation $\succ_t$ over the set of schools and being unmatched (being unmatched is denoted by $\emptyset$). Similarly, each school $s$ has a strict preference relation $\succ_s$ over teachers and being unmatched.\footnote{Our results easily extend to the case of weak preferences for schools.} For any teacher $t$, we write $s \succeq_t s'$ if and only if $s \succ_t s'$ or $s = s'$. For any school $s$, we define $\succeq_s$ in a similar way. For simplicity, we assume that all teachers and schools prefer to be matched rather than being unmatched. A \textbf{matching} $\mu$ is a mapping from $T \cup S$ into $T \cup S \cup \{\emptyset\}$ such that (i) for each $t \in T$, $\mu(t) \in S \cup \{\emptyset\}$ and for each $s \in S$, $\mu(s) \in T \cup \{\emptyset\}$ and (ii) $\mu(t) = s$ iff $\mu(s) = t$. That is, a matching simply specifies the school to which each teacher is assigned or that a teacher is unmatched. It also specifies the teachers assigned to each school, if any. We also sometimes use the term “assignment”
instead of “matching”. Thus far, our environment is not different from the college admission problem (Gale and Shapley (1962)). However, in a teacher assignment problem, there is an additional component: teachers have an initial assignment. Let us denote the corresponding matching by $\mu_0$. For now, we assume that $\mu_0(t) \neq \emptyset$ for each teacher $t$ and $\mu_0(s) \neq \emptyset$ for each school $s$.\footnote{This implies that $\mu_0$ defines a bijection from $T$ to $S$ and thus $|T| = |S|$.} Hence, initially, all teachers are assigned a school (there is no incoming flow of teachers) and there is no available seat at schools (there is no outgoing flow of teachers). We define a teacher allocation problem as a triplet $[T, S, \succ]$ where $\succ := (\succ_a)_{a \in S \cup T}$.

We will be interested in different efficiency and fairness criteria, depending on whether we regard both teachers and schools or only teachers as welfare-relevant entities. First, we say that a matching $\mu$ is two-sided individually rational (2-IR) if, for each teacher $t$, $\mu(t)$ is acceptable to $t$, i.e., $\mu(t) \succeq_t \mu_0(t)$ and, in addition, for each school $s$, $\mu(s)$ is acceptable to $s$, i.e., $\mu(s) \succeq_s \mu_0(s)$. Similarly, a matching is one-sided individually rational (1-IR) if each teacher finds his assignment acceptable. We say that a matching $\mu$ 2-Pareto dominates (resp. 1-Pareto dominates) another matching $\mu'$ if all teachers and schools (resp. teachers) are weakly better off – and some strictly better off – under $\mu$ than under $\mu'$. A matching is two-sided Pareto-efficient (2-PE) if there is no other matching that 2-Pareto dominates it. Similarly, we define one-sided Pareto-efficient (1-PE) matchings as assignments for which no alternative matching exists that 1-Pareto dominates it. We say that under matching $\mu$, a teacher $t$ has justified envy for teacher $t'$ if $t$ prefers the assignment of $t'$, i.e., $\mu(t') := s$, to his own assignment $\mu(t)$ and $s$ prefers $t$ to its assignment. Using the standard terminology from the literature, we say that $(t, s)$ blocks matching $\mu$. A matching $\mu$ is stable if there is no pair $(t, s)$ blocking $\mu$. We will sometimes say that a matching $\mu$ dominates another matching $\mu'$ in terms of stability if the set of blocking pairs of $\mu$ is included in that of $\mu'$.

Finally, a matching mechanism is a function $\varphi$ that maps problems into matchings. We abuse the notation and write $\varphi(\succ)$ for the matching obtained in problem $[T, S, \succ]$. We also write $\varphi_t(\succ)$ for the school that teacher $t$ obtains under matching $\varphi(\succ)$. It is 2-IR/1-IR/1-PE/2-PE/stable if, for each problem, it systematically selects a matching that is 2-IR/1-IR/1-PE/2-PE/stable.

One of the standard matching mechanisms is DA, as proposed by Gale and Shapley (1962). Because we discuss a closely related mechanism, we first recall the definition of DA.

- **Step 1.** Each teacher $t$ applies to his most preferred school. Each school tentatively accepts its most preferred teacher among the offers it receives and rejects all other offers.

In general,

- **Step $k \geq 1**. Each teacher $t$ who was rejected at step $k - 1$ applies to his most preferred school among those to which he has not yet applied. Each school tentatively accepts its most favorite teacher among the new offers in the current step and the applicant tentatively selected from the previous step (if any), and it rejects all other offers.
The following proposition is well known.

**Proposition 1 (Gale and Shapley (1962))** DA is a stable and 2-PE mechanism.

While DA is stable and 2-PE, it fails to be 1-IR (and thus 2-IR). This is unavoidable: in general, there is a conflict between individual rationality and stability. The basic intuition is that imposing 1-IR on a mechanism yields situations in which some teacher \( t \) may be able to keep his initial assignment \( \mu_0(t) =: s \), while school \( s \) may perfectly prefer other teachers to \( t \). These other teachers may rank \( s \) at the top of their preference relation and hence block with school \( s \). We summarize this discussion in the following observation.\(^{15}\)

**Proposition 2** There is no mechanism that is both 1-IR and stable. Hence, DA is not 1-IR.

Thus, there is a fundamental trade-off between 1-IR and stability, and one may wish to find a mechanism that restores individual rationality while retaining the other desirable properties of DA, such as its stability and its 2-Pareto efficiency, to the greatest extent possible. To do so, an approach followed in the literature (see, for instance, Pereyra (2013) or Compte and Jehiel (2008)) and used in practice consists of artificially modifying the schools’ preferences such that each teacher \( t \) is ranked at the top of the (modified) ranking of the school he is initially assigned to, namely, \( \mu_0(t) \). Other than this modification, the schools’ preference relations remain unchanged.\(^{16}\) Once this is done, one runs DA as defined above using schools’ modified preferences. We denote the corresponding mechanism as DA\(^*\). By construction, this is a 1-IR mechanism, and it is used in practice in several situations. For instance, it is used for the assignment of on-campus housing at MIT (Guillen and Kesten (2012)). It is also used in France for the assignment of teachers to schools. Specifically, a school-proposing deferred acceptance mechanism is run using the modified priorities and the reported preferences. Then, Stable Improvement Cycles are executed as defined in Erdil and Ergin (2008). Using Theorem 1 in Erdil and Ergin (2008), we know that this process yields the outcome of the teacher-proposing deferred acceptance mechanism according to the modified priorities.\(^{17}\) Hence, the mechanism used to assign French teachers to public schools is equivalent to DA\(^*\).

By construction, this mechanism is 1-IR, hence, by Proposition 2, we know that it is not stable. However, is there a sense in which the violation of stability is minimal? What

\(^{15}\)This is highlighted in Compte and Jehiel (2008) and Pereyra (2013).

\(^{16}\)Formally, for each school \( s \), a new preference relation \( \succ'_s \) is defined such that \( \mu_0(s) \succ'_s t' \) for each \( t' \neq \mu_0(s) \), and for each \( t, t' \) distinct from the school’s initial assignment \( \mu_0(s) \), we have \( t \succ'_s t' \) if and only if \( t \succ_t t' \).

\(^{17}\)In the French system, teachers’ priorities at schools can be coarse. Hence, in practice, the algorithm begins by breaking ties (using teachers’ birth dates). Once ties are broken, school-proposing DA is run using the modified priorities with no ties and the reported preferences. From this outcome, stable improvement cycles are run, again using the modified (strict) priorities. Thus, the outcome is equivalent to the teacher-proposing deferred acceptance with the same tie-breaking rule, which, in turn, may be Pareto dominated by a teacher-optimal stable mechanism. Our mechanisms and results can be easily extended to an environment with coarse priorities.
about efficiency: Is DA* 2-PE? Furthermore, if the answers to those questions are negative, can we find ways to improve upon this? The following example will illustrate an important disadvantage of DA* to which we will return both in our theoretical analysis and in our empirical assessment.

Example 1 We consider a simple environment with \( n \) teachers and \( n \) schools with a 1-IR initial assignment \( \mu_0 \). Let us assume that a teacher \( t^* \) is initially assigned to school \( s^* \) (i.e., \( \mu_0(t^*) = s^* \)) and is ranked first by all schools. In addition, school \( s^* \) is ranked at the bottom of each teacher’s preference relation – including \( t^* \); hence, \( t^* \) is willing to move. We claim that, under these assumptions, no teacher will move from his initial assignment if we use DA* to assign teachers. To see this, note first that \( t^* \) does not move from his initial assignment. Indeed, because DA* is 1-IR, if \( t^* \) were to move, then some teacher \( t \) would have to take the seat at school \( s^* \) (or be unmatched), but since \( s^* \) is the worst school for every teacher (and \( \mu_0 \) is 1-IR), this assignment would violate the individual rationality condition for teacher \( t \), a contradiction. Note that this implies that, under DA* algorithm, \( t^* \) applies to every school \( s \) (but is eventually rejected). Now, to see that no teacher other than \( t^* \) moves, assume on the contrary that \( t \neq t^* \) is assigned a school \( s \neq \mu_0(t) \). As mentioned above, at some step of DA* algorithm, \( t^* \) applies to \( s \). Since \( t^* \) is ranked above \( t \) in the preference relation of school \( s \) (recall that \( s \neq \mu_0(t) \)), \( t \) cannot eventually be matched to school \( s \), a contradiction.

To recap, under our assumptions, no teacher moves from his initial assignment. Since the initial assignment can perform very poorly in terms of basic criteria such as stability or 2-Pareto efficiency, we can easily imagine the existence of alternative matchings that would make both teachers and schools better off and, hence, shrink the set of blocking pairs.

The driving force in this example is the existence of a teacher who is ranked at the top of each school’s ranking and who is initially assigned to the worst school. This is, of course, a stylized example, and one can easily imagine less extreme examples in which a similar phenomenon would occur. The basic idea is that, for DA* to perform poorly, it is enough to have one teacher (a single one is enough) being assigned an unpopular school and who himself has a fairly high ranking for a relatively large fraction of the schools. Our theoretical analysis and our empirical assessment will give a sense in which the described phenomenon is far from being a peculiarity.

Remark 1 Contrary to what we have in the example, in practice, there are open seats at schools. One may argue that high-priority teachers such as \( t^* \) will succeed in obtaining available seats at schools they desire and, hence, that the above phenomenon would be considerably weakened. However, in an environment in which teachers’ preferences tend to be similar (i.e., are positively correlated), there will be competition to access good schools. These good schools have a limited number of seats available, and one may easily imagine that once these open seats are filled by some of the high-priority teachers, a similar phenomenon as in the example could occur among the remaining teachers. We ran simulations in a rich environment (allowing for correlation in teachers’ and schools’ preferences, available seats, newcomers and positive
assortment in the initial assignment) that confirm this intuition. The results are reported in Appendix B.

The above example identifies a weakness of $DA^*$: it can be improved upon both in terms of efficiency (on both sides) and in terms of the set of blocking pairs (i.e., we can shrink its set of blocking pairs). Thus, we are interested in mechanisms/matchings that do not have this type of disadvantage. We also wish to retain the elementary property that our mechanism/matching improves on the initial assignment. This suggests the following definitions.

**Definition 1** A matching $\mu$ is **two-sided maximal** if $\mu$ is 2-IR$^{18}$ and there is no other matching $\mu'$ such that (1) all teachers and schools are weakly better off and some strictly better off and (2) the set of blocking pairs under $\mu'$ is a subset of that under $\mu$.

This notion treats both schools and teachers as welfare-relevant entities. As we argued above, one may also ignore the school side. In this case, we obtain the following natural counterpart.

**Definition 2** A matching is **one-sided maximal** if $\mu$ is 1-IR and there is no other matching $\mu'$ such that (1) all teachers are weakly better off and some strictly better off and (2) the set of blocking pairs under $\mu'$ is a subset of that under $\mu$.

Consistent with our previous notions, we say that a mechanism is two-sided (resp. one-sided) maximal if it systematically selects a two-sided (resp. one-sided) maximal matching.

Let us note that, if there is a matching $\mu'$ under which all teachers and schools are weakly better off and some strictly better off than under a matching $\mu$, then the set of blocking pairs under $\mu'$ is a subset of that under $\mu$. Thus, in the definition of two-sided maximality, requirement (2) can be dropped.$^{19}$ This yields the following straightforward equivalent definition.

**Proposition 3** A matching $\mu$ is **two-sided maximal** if and only if $\mu$ is 2-IR and 2-PE.

Given Example 1 above, we have the following straightforward proposition.

**Proposition 4** $DA^*$ is not two-sided maximal and, hence, not one-sided maximal. (Thus, $DA^*$ is not 2-PE.)

Given the above weaknesses of $DA^*$, the obvious goal henceforth is to identify the class of mechanisms characterizing two-sided and one-sided maximality and to study the properties of those mechanisms. This is the aim of the next section.

$^{18}$Recall that the motivation for imposing 2-IR is to ensure that our assignments Pareto-dominate the initial assignment.

$^{19}$However, one can easily check that (2) in the definition of one-sided maximality cannot be dropped.
4 Theoretical Analysis

For each notion of maximality defined above (Definitions 1 and 2), the following two sections identify a class of mechanisms that characterizes it. Once the characterization results are proved, we analyze the properties of the mechanisms in that class. While the class of mechanisms can be very large (as illustrated by Proposition 3), imposing standard additional conditions drastically reduces the set of candidate mechanisms. In particular, a striking outcome of this analysis is that, once the standard strategy-proofness notion is imposed, a unique two-sided maximal mechanism is shown to survive. In addition, while one may expect that giving more weight to teachers (as opposed to schools) as in one-sided maximal mechanisms may help in terms of incentive properties, another conceptually interesting outcome of our analysis is that no one-sided maximal mechanism is strategy-proof.

4.1 Two-sided maximality

In the next section, we define a class of mechanisms that characterizes the set of two-sided maximal mechanisms. The mechanism will sequentially clear cycles of an appropriately constructed directed graph in the spirit of Gale’s top trading cycle, originally introduced in Shapley and Scarf (1974) and later studied by Abdulkadiroglu and Sonmez (2003).

4.1.1 The Block Exchange Algorithm

The basic idea behind the mechanisms we define is the following: starting from the initial assignment, if a teacher $t$ blocks the school initially assigned to $t'$ and $t'$ also blocks with the school initially assigned to $t$, then we allow $t$ and $t'$ to trade their initial assignments. This is a pairwise exchange between $t$ and $t'$, but one may of course imagine three-way exchanges or even larger exchanges. Once such an exchange has been made, we obtain a new matching, and we can again search for possible trades. More precisely, our class of mechanisms is induced by the following algorithm, named the Block Exchange (BE, for short):

- **Step 0**: set $\mu(0) := \mu_0$.

- **Step $k \geq 1$**: Given $\mu(k - 1)$, let the teachers and their assignments stand for the vertices of a directed graph where, for each pair of nodes $(t, s)$ and $(t', s')$, there is an edge $(t, s) \rightarrow (t', s')$ if and only if teacher $t$ blocks $\mu(k - 1)$ with school $s'$. If there is no cycle, then let $\mu(k - 1)$ be the outcome of the algorithm. Otherwise, select a cycle in this directed graph. For each edge $(t, s) \rightarrow (t', s')$ in the cycle, assign teacher $t$ to school $s'$. Let $\mu(k)$ be the matching so obtained. Go to step $k + 1$.

It is easy to verify that this algorithm converges in (finite and) polynomial time.\(^{20}\) In the above description, we do not specify how the algorithm should select the cycle of the directed

\(^{20}\)To see that this algorithm converges in a finite number of steps, observe that, whenever we carry out a
graph. Therefore, one may think of the above description as defining a class of mechanisms, where a mechanism is determined only after we fully specify how to act when confronted with multiple cycles. One can imagine these selections to be random or dependent on earlier selections. In general, for each profile of preferences for teachers and schools \( \succ \), a possible outcome of BE is a matching that can be obtained by using an appropriate selection of cycles in the above procedure. Hence, we consider the following correspondence \( BE : \succ \Rightarrow \mu \) where \( BE(\succ) \) stands for the set of all possible outcomes of BE. A selection of the BE algorithm is a mapping \( \varphi : \succ \mapsto \mu \) s.t. \( \varphi(\succ) \in BE(\succ) \). Obviously, each selection \( \varphi \) of BE defines a mechanism.

As mentioned above, our class of mechanisms shares some similarities with Gale’s TTC. However, there are two important differences. The first and the most minor is that a teacher in a node can point to several nodes and thus, implicitly, to several schools. This is why, contrary to TTC, we have an issue regarding selection of cycles and why our algorithm does not define a unique mechanism. However, as we will see in the next result, this is necessary for our characterization. Second, and certainly more importantly, our algorithm takes into account welfare on both sides of the market. Indeed, a teacher in a node \((t, s)\) can point to a school in \((t', s')\) only if \(s'\) agrees (i.e., \(s'\) prefers \(t\) to its assignment \(t'\)). This is what ensures, contrary to TTC, that each time we carry out a cycle, both teachers and schools become better off. This has the desirable implication that each time a cycle is cleared, the set of blocking pairs shrinks.

The BE algorithm starts from the initial assignment and then improves on it in terms of the welfare of teachers and schools. More generally, one could start from any matching obtained by running another mechanism \( \varphi \). Doing so will guarantee that the (modified) BE algorithm will select a matching that dominates that of \( \varphi \) in terms of the welfare of both teachers and schools. This modification of the BE algorithm that takes the composition of BE and \( \varphi \) will be denoted by \( BE \circ \varphi \). Given our starting point that \( DA^* \) performs poorly in terms of the welfare of teachers and schools, we will be particularly interested in \( BE \circ DA^* \).

The next example illustrates how the BE algorithm works.

**Example 2** There are 4 teachers \( t_1, \ldots, t_4 \) and 4 schools \( s_1, \ldots, s_4 \) with one seat each. The initial matching \( \mu_0 \) is such that, for \( k = 1, \ldots, 4 \), \( \mu_0(t_k) = s_k \). Preferences are the following:

\[
\begin{align*}
\succ t_1: & \quad s_2 \ s_3 \ s_1 \ s_4 \\
\succ t_2: & \quad s_3 \ s_1 \ s_2 \ s_4 \\
\succ t_3: & \quad s_1 \ s_2 \ s_3 \ s_4 \\
\succ t_4: & \quad s_1 \ s_2 \ s_3 \ s_4 \\
\succ s_1: & \quad t_4 \ t_2 \ t_1 \ t_3 \\
\succ s_2: & \quad t_4 \ t_3 \ t_1 \ t_2 \\
\succ s_3: & \quad t_4 \ t_3 \ t_2 \ t_1 \\
\succ s_4: & \quad t_4 \ t_1 \ t_2 \ t_3
\end{align*}
\]

This example has a similar feature as Example 1: \( t_4 \) is the best teacher and is matched to the worst school. Thus, we know that, in that case, \( DA^* \) coincides with the initial assignment.
We have six blocking pairs: \((t_1, s_2), (t_2, s_1), (t_3, s_2)\) and \((t_4, s_k)\) for \(k = 1, 2, 3\). The graph for BE is then the following:

\[
\begin{array}{c}
(t_1, s_1) \\
\mid \quad \mid \quad \mid \\
\downarrow \quad \downarrow \quad \downarrow \\
(t_2, s_2) \\
\mid \quad \mid \quad \mid \\
\downarrow \quad \downarrow \quad \downarrow \\
(t_3, s_3) \\
\mid \quad \mid \quad \mid \\
\downarrow \quad \downarrow \quad \downarrow \\
(t_4, s_4)
\end{array}
\]

The only cycle in this graph is \((t_1, s_1) \rightsquigarrow (t_2, s_2)\), and it can be verified that, once implemented, there are no cycles left in the new matching; thus, the matching of BE is given by

\[
BE = \begin{pmatrix}
t_1 & t_2 & t_3 & t_4 \\
s_2 & s_1 & s_3 & s_4
\end{pmatrix}
\]

There are now 4 blocking pairs: \((t_3, s_2)\) and \((t_4, s_k)\) for \(k = 1, 2, 3\), and teachers \(t_1\) and \(t_2\) as well as schools \(s_1\) and \(s_2\) are better off.

We now turn to our characterization result.

**Theorem 1** Fix a preference profile. The set of possible outcomes of the BE algorithm coincides with the set of two-sided maximal matchings.

Before proving the above statement, we prove the following simple lemma.

**Lemma 1** Assume that \(\mu'\) 2-Pareto dominates \(\mu\). Starting from \(\mu(0) = \mu\), there is a collection of disjoint cycles in the directed graph associated with the BE algorithm that, once carried out, yields matching \(\mu'\), as was to be shown.

**Proof.** Consider the directed graph where teachers and their assignments under \(\mu\) stand for the vertices and for each pair of nodes \((t, s)\) and \((t', s')\), there is an edge \((t, s) \rightarrow (t', s')\) if and only if teacher \(t\) is assigned to \(s'\) under \(\mu'\). By the definition of matchings, this directed graph has at least one cycle and cycles are disjoint. Note that because \(\mu'\) 2-Pareto dominates
\( \mu \), in this graph, \((t, s) \rightarrow (t', s')\) if and only if teacher \( t \) blocks \( \mu \) with school \( s' \). Hence, the graph we built is a subgraph of the directed graph associated with the BE algorithm starting from \( \mu \). By construction, we have a collection of disjoint cycles in this directed graph that, once carried out, yields matching \( \mu' \).

We are now in a position to complete the proof of Theorem 1.

**Proof of Theorem 1.** If \( \mu \) is an outcome of BE, then it must be two-sided maximal. Indeed, if this were not the case, then by the above lemma, there would exist a cycle in the directed graph associated with the BE algorithm starting from \( \mu \), which contradicts our assumption that \( \mu \) is an outcome of the BE algorithm. Now, if \( \mu \) is two-sided maximal, it 2-Pareto dominates the initial assignment \( \mu_0 \). Hence, appealing again to the above lemma, there is a collection of disjoint cycles in the directed graph associated with the BE algorithm starting from \( \mu_0 \) that, once carried out, yields the assignment \( \mu \). Clearly, once \( \mu \) is achieved by the BE algorithm, there are no more cycles in the associated graph.

While this result provides a simple and computationally easy procedure to find two-sided maximal matchings, the class of mechanisms defined by this algorithm is huge. Indeed, appealing to Proposition 3, this corresponds to the whole class of mechanisms that are both 2-PE and 2-IR. As we will see, by imposing the standard requirement of strategy-proofness, a unique mechanism will remain. The next section will state and prove this result and identify this mechanism.

### 4.1.2 Incentives under Block Exchanges

First, recall that a mechanism \( \varphi \) is **strategy-proof** if, for each profile of preferences \( \succ \) and teacher \( t \), \( \varphi_i(\succ) \succeq_i \varphi_i(\succ'_i, \succ_{-i}) \) for any possible report \( \succ'_i \) of teacher \( t \).\(^{21}\) The following example shows that some selections of the BE algorithm are not strategy-proof.

**Example 3** Consider an environment with three teachers \( \{t_1, t_2, t_3\} \) and three schools \( \{s_1, s_2, s_3\} \). For each \( i = 1, 2, 3 \), we assume that teacher \( t_i \) is initially assigned to school \( s_i \). Teacher \( t_1 \)'s most preferred school is \( s_2 \), and he ranks his initial assignment \( s_1 \) second. Teacher \( t_2 \) ranks \( s_1 \) first, followed by \( s_3 \). Teacher \( t_3 \) ranks \( s_2 \) first and his initial assignment \( s_3 \) second. Finally, we assume that each teacher is ranked in last position by the school to which he is initially assigned. We obtain the following graph for the BE algorithm.

\[ \text{Graph:} \]

\[ (t_1, s_1) \rightarrow (t_2, s_2) \]

\[ (t_2, s_2) \rightarrow (t_3, s_3) \]

\[ (t_3, s_3) \rightarrow (t_1, s_1) \]

\[ \text{Conclusion:} \]

\[ \varphi(t_1, s_1) \succeq \varphi(t_1, s_1) \]

\[^{21}\text{Using standard notation, } \succ_{-t} \text{ denotes the vector of preference relations } \succ'_{\neq t}.\]
There are two possible cycles that overlap at \((t_2, s_2)\). Consider a selection of the BE algorithm that picks cycle \((t_2, s_2) \mapsto (t_3, s_3)\). In that case, the algorithm ends at the end of step 1, and teacher \(t_2\) is eventually matched to school \(s_3\), his second most preferred school. However, if teacher \(t_2\) lies and claims that he ranks \(s_3\) below his initial assignment, the directed graph associated with the BE algorithm has a single cycle \((t_1, s_1) \mapsto (t_2, s_2)\). In that case, the unique selection of the BE algorithm assigns \(t_2\) to his most preferred school \(s_1\). Hence, \(t_2\) has a profitable deviation under the selection of the BE algorithm considered here.

While this example is simple, an important objection for practical market design purposes is that the manipulation requires that teachers have fairly precise information regarding the preferences in the market (i.e., of the other teachers and of schools). While this is true for many mechanisms, there is a sense in which – in some realistic instances – some selections of the BE (or associated) algorithm can be manipulated without requiring a considerable amount of information on both preferences in the market and the details of the mechanism. A simple instance of this phenomenon can be illustrated for BEcDA\(^*\). Indeed, under this mechanism, a teacher who would initially be assigned to a popular school that dislikes him can use the following strategy: report his most preferred school sincerely and then rank the school to which he is initially assigned in second place (even though this may not match his true preferences). If, under DA\(^*\), the teacher does not receive his first choice, he will certainly receive his initial assignment. Given that this school is popular and dislikes him, the teacher is likely to be part of a cycle involving his most preferred school under the BE algorithm. Hence, at an intuitive level, this mechanism can be manipulated by teachers who may only have coarse information on preferences in the market.

In the following, we define a mechanism that is a selection of the BE algorithm and is strategy-proof. More surprisingly, we will prove further in the text that this is the unique selection satisfying this property. Before providing the definition of the mechanism, we need an additional piece of notation. Given a matching \(\mu\) and a set of schools \(S' \subseteq S\), we let \(\text{Opp}(t, \mu, S') := \{ s \in S' | t \succ_s \mu(s) \}\) be the opportunity set of teacher \(t\) among schools in \(S'\). Note that for each teacher \(t\), if \(\mu_0(t) \in S'\), then \(\text{Opp}(t, \mu_0, S') \neq \emptyset\) since \(\mu_0(t) \in \text{Opp}(t, \mu_0, S')\).

- **Step 0**: Set \(\mu(0) = \mu_0, T(0) := T\) and \(S(0) := S\).

- **Step \(k \geq 1\)**: Given \(T(k-1)\) and \(S(k-1)\), let the teachers in \(T(k-1)\) and their assignments stand for the vertices of a directed graph, where for each pair of nodes \((t, s)\) and \((t', s')\), there is an edge \((t, s) \rightarrow (t', s')\) if and only if teacher \(t\) ranks school \(s'\) first in his opportunity set \(\text{Opp}(t, \mu(k-1), S(k-1)) = \text{Opp}(t, \mu_0, S(k-1))\). The directed graph so obtained is a directed graph with out-degree one\(^{22}\); as such, it has at least one

\(^{22}\)Since, by construction, if \(t\) is not yet eliminated from the algorithm (i.e., he is in \(T(k-1)\)), the school to which \(t\) is initially assigned is also not eliminated. Hence, \(\mu_0(t) \in S(k-1)\). As we have already noted, this implies that \(\text{Opp}(t, \mu_0, S(k-1))\) is non-empty. Now, because teachers have strict preferences, there is a unique most preferred school for \(t\) in \(\text{Opp}(t, \mu_0, S(k-1))\).
cycle, and cycles are pairwise disjoint. For each edge \((t, s) \rightarrow (t', s')\) in a cycle, assign teacher \(t\) to school \(s'\). Let \(\mu(k)\) be the assignment obtained and \(T(k)\) (resp., \(S(k)\)) be the set of teachers (resp., schools) who are not part of any cycle at the current step. If \(T(k)\) is empty, then return \(\mu(k)\) as the outcome of the algorithm. Otherwise, go to step \(k + 1\).

As will become clear, our mechanism has a tight relationship with the TTC mechanism. Recall that TTC operates in the same manner as the above mechanism except that the pointing behavior does not refer to the opportunity set: an edge \((t, s) \rightarrow (t', s')\) is added if and only if teacher \(t\) ranks school \(s'\) first within the set of all remaining schools (i.e., at step \(k\), those are the schools in \(S(k-1)\)). We will make use of the following straightforward equivalence result.

**Lemma 2** Fix a preference profile \(\succ\). \(\text{TO-BE}(\succ)\) is equal to \(\text{TTC}(\succ')\) where, for each teacher \(t\), the preference relation \(\succ'_t\) ranks schools outside his opportunity set \(\text{Opp}(t, \mu_0, S)\) below his initial assignment.

From this simple lemma, we obtain the following proposition.

**Theorem 2** \(\text{TO-BE}\) is strategy-proof and is a selection of the BE algorithm.

**Proof.** Given that an agent’s report has no impact on his opportunity sets, Lemma 2 above (together with the well-known fact that TTC is strategy-proof) implies that TO-BE is strategy-proof. Now, we show that TO-BE is a selection of BE. Appealing to Theorem 1, it is enough to show that TO-BE is a two-sided maximal mechanism. If this were not the case, it would mean that, for some preference profile \(\succ\), starting from \(\text{TO-BE}(\succ)\), there would be a cycle in the directed graph associated with the BE algorithm. It is easily verified that this cycle would still be present if the preferences of teachers were to be modified such that any school outside the opportunity set of a teacher \(t\) (i.e., outside \(\text{Opp}(t, \mu_0, S)\)) is ranked below his initial assignment. In this modified problem, by Lemma 2, TO-BE is equivalent to TTC. However, if we carry out the cycle starting from TO-BE, we obtain a matching that, for teachers, Pareto dominates TO-BE and, hence, TTC. This contradicts the well-known fact that TTC is 1-PE.

Say that a selection \(\varphi\) of the BE algorithm is teacher-optimal if there is no selection of BE that 1-Pareto dominates \(\varphi\). The following result justifies the terminology used thus far: TO-BE is indeed teacher-optimal.

**Proposition 5** Take any mechanism \(\varphi\) that is 2-IR. TO-BE is not 1-Pareto dominated by \(\varphi\).

**Proof.** Proceed by contradiction and assume that TO-BE is 1-Pareto dominated by \(\varphi\) at preference profile \(\succ\). Since \(\varphi\) is 2-IR, \(\varphi(t) \in \text{Opp}(t, \mu_0, S)\). Hence, TO-BE is still 1-Pareto
dominated by $\varphi$ at the modified preference profile where each teacher $t$ ranks schools outside his opportunity set $\text{Opp}(t, \mu_0, S)$ below his initial assignment. By Lemma 2, this implies that at the modified preference profile, TTC is 1-Pareto dominated by $\varphi$, which is not possible given that TTC is 1-PE. □

**Corollary 1** TO-BE is a teacher-optimal selection of BE.

We now turn to the most striking result of this section. Apart from TO-BE, no selection of the BE algorithm is strategy-proof.

As we already mentioned, this shows that the teacher assignment problem has a similar structure to the college admission problem. Indeed, in the college admission problem, imposing two-sided efficiency and stability yields a large set of stable mechanisms. Some of these mechanisms favor students whilst others favor colleges. Our characterization of two-sided maximal matchings is similar. We end up with a plethora of possible mechanisms, some favoring teachers and others favoring schools. In the college admission problem, once one-sided strategy-proofness is imposed, a unique mechanism is obtained: the stable mechanism which favors students (DA). Similarly, the next result shows that, in the teacher assignment problem, once we impose the same incentive constraints, we end up with a unique mechanism: TO-BE, which favors teachers. While the structure is very similar, the two mechanisms (DA and TO-BE) are very different and, hence, so are the underlying arguments.

**Theorem 3** TO-BE is the unique selection of the BE algorithm that is strategy-proof.

**Proof.** The proof is relegated to Appendix C. □

While the formal details of the argument are provided in the appendix, let us give a sketch of the proof for this result.

As is well-known, in a Shapley-Scarf economy (in which schools are replaced by objects with no preferences but are initially owned by the other side of the market), TTC is the unique element of the core (Shapley and Scarf (1974) and Roth and Postlewaite (1977)). Because TO-BE is related to TTC, it can be related to some notion of the core. This notion is used in the course of the argument for Theorem 3. Define the two-sided notion of the core as the set of matchings $\mu$ s.t. there is no (two-sided blocking) coalition $B \subseteq T$ for which there is a matching $\nu$ s.t. for each $t \in B$, $\nu(t)$ is a school to which a teacher in $B$ is initially matched and for all $t \in B : \nu(t) \succeq_t \mu(t)$ and, for $s := \nu(t)$, $t \succeq_s \mu_0(s)$ with a strict equality for some teacher (or school). Given a profile of preferences, it is easily verified that a matching is in the two-sided core if and only if it is in the (standard) core when preferences are modified in such a way that each teacher $t$ ranks schools outside his opportunity set $\text{Opp}(t, \mu_0, S)$ below his initial assignment. Thus, appealing to the results mentioned above (i.e., Shapley and Scarf (1974) and Roth and Postlewaite (1977)), we conclude that the two-sided core is a singleton and – given Lemma 2 – coincides with TO-BE.
Now, to provide intuition for Theorem 3, let us consider a selection $\varphi$ of BE that is strategy-proof. Toward a contradiction, assume that $\varphi$ and TO-BE differ at $\succ$. We first prove a useful technical result: there exists a teacher $t$ s.t. $\text{TO-BE}_t(\succ) \succ_t \varphi_t(\succ) \succ_t \mu_0(t)$. That there is a teacher who strictly prefers the assignment of TO-BE to that of $\varphi$ is straightforward, given that TO-BE is teacher-optimal (Proposition 1). The non-trivial part consists of showing that this same teacher also strictly prefers the assignment of $\varphi$ to that of $\mu_0$. If this were not the case, then among all teachers who strictly prefer TO-BE to $\varphi$, the assignment they would obtain with $\varphi$ would coincide with the initial assignment. Hence, if we denote by $B$ the complementary set of teachers, namely, those who weakly prefer the assignment given by $\varphi$ to that given by TO-BE, we know that the assignment they obtain under $\varphi$ corresponds to the initial assignment of some other teacher in $B$. Given that $\varphi$ is 2-IR, this is very close to showing that $B$ is a two-sided blocking coalition. To show this, we need to find a teacher in $B$ who actually strictly prefers $\varphi$ to TO-BE. Our argument shows that if this were not the case, then this would contradict that $\varphi$ is 2-PE (and thus a selection of BE).

Now, given the above technical point, the proof proceeds as follows. Given the profile $\succ$, we consider modified preferences $\succ_t'$ for teachers who only rank as acceptable their school under $\text{TO-BE}(\succ)$. Given that this is the unique acceptable assignment for each teacher, the technical lemma implies that $\text{TO-BE}(\succ')$ must be equal to $\varphi(\succ')$. We consider a sequence of unilateral deviations of teachers reporting $\succ_t$ instead of $\succ_t'$, which ultimately returns us to $\succ$ and along which the equality between TO-BE and $\varphi$ is maintained. To give an idea of why the equality is maintained along the sequence of unilateral deviations, let us assume that, starting from $\succ'$, $t$ reports $\succ_t$ instead of $\succ_t'$. If under $(\succ_t, \succ_t')$, $\varphi$ and TO-BE select different outcomes, then again, by the technical lemma, we know that $\text{TO-BE}(\succ_t, \succ_t') \succ_t \varphi_t(\succ_t, \succ_t') \succ_t \mu_0(t)$. By definition, TO-BE is not affected by $t$’s deviation, but then, because TO-BE and $\varphi$ coincide at $\succ'$, we have $\text{TO-BE}(\succ_t, \succ_t') = \varphi(\succ')$, which, by the previous argument, is strictly preferred to $\varphi_t(\succ_t, \succ_t')$ at $\succ_t$. Thus, at $(\succ_t, \succ_t')$, $t$ can claim that his preferences are $\succ_t'$ and be better off, which contradicts the strategy-proofness of $\varphi$.

Hence, for a unilateral deviation by teacher $t$, $\varphi$ and TO-BE must remain equal. Proceeding inductively in this way, we can show that, after a sequence of unilateral deviations from $\succ_t'$ to $\succ_t$ by each teacher, the equality between TO-BE and $\varphi$ is maintained, and hence, TO-BE and $\varphi$ coincide at $\succ$.

Before closing this section, we discuss our approach relative to that of Ma (1994). Ma shows that in the Shapley-Scarf economy, the unique mechanism that is 1-IR, 1-PE and strategy-proof is TTC. Intuitively, our result applies to richer environments in which schools have non-trivial preferences that are taken into account when determining welfare. This suggests that our result is a generalization of Ma’s. Indeed, to see this, note that, in the specific situation in which each school ranks its initial assignment at the bottom of its ranking, TO-BE and TTC coincide. In this context, 1-IR and 2-IR are obviously equivalent. In addition, since 1-PE implies 2-PE, we obtain that the class of mechanisms considered by Ma is a subset

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$^{23}$Obviously, this condition cannot hold for teachers other than $t'$ by construction of $\succ'$. 

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of the selections of the BE algorithm. Applying Theorem 3 to these selections yields Ma’s result. While our argument builds upon that of Ma, there are a number of crucial differences. As mentioned above, even in the very specific environment in which each school ranks its initial assignment at the bottom of its preference relation, the BE algorithm contains many other mechanisms that include, in particular, all those that are 2-PE but not 1-PE and all 1-PE mechanisms that are sensitive to schools’ preferences. In addition, our result applies in general to settings in which schools’ preferences are arbitrary and, thus, to many other types of mechanisms that are not even well defined in Ma’s environment.

### 4.2 One-sided maximality

We now turn to the characterization of one-sided maximality. Like we did for two-sided maximality, we introduce a class of mechanisms with possible outcomes spanning the whole set of one-sided maximal matchings. With two-sided maximality, the underlying criteria targeted by the designer are the welfare of teachers and schools, as well as the set of blocking pairs. In contrast, with one-sided maximality, the designer only targets the welfare of teachers and the set of blocking pairs. The basic idea behind the mechanism of this section is as follows: under the BE algorithm, two teachers can exchange their assignments if and only if they both block with the school initially assigned to the other teacher. However, one can imagine a pair of teachers $t$ and $t'$ who each desire the school of the other teacher — say $s$ and $s'$, respectively — and, while school $s$ does not necessarily rank $t'$ above $t$, it does rank first $t'$ among the individuals who desire $s$. If, similarly, $s'$ ranks $t$ first among the individuals who desire $s'$, then it is easily shown that an exchange between $t$ and $t'$ increases the welfare of teachers and shrinks the set of blocking pairs. Hence, based on a similar idea, we will weaken the definition of the pointing behavior in the directed graph defined in BE in such a way that — although schools may become worse off — both teachers’ welfare increases and the set of blocking pairs shrinks each time we carry out a cycle. The following algorithm — named one-sided BE (1S-BE for short) — accomplishes this weakening, and Theorem 4 below provides a sense in which this is the best weakening one can hope to achieve.

- **Step 0**: set $\mu(0) := \mu_0$.

- **Step $k \geq 1$**: Given $\mu(k - 1)$, let the teachers and their assignments stand for the vertices of a directed graph, where for each pair of nodes $(t, s)$ and $(t', s')$, there is an edge $(t, s) \rightarrow (t', s')$ if and only if either (1) teacher $t$ blocks with school $s'$ or (2) $t$ desires $s'$ and $t$ is ranked first by $s'$ among teachers who both desire $s'$ and do not block with $s'$. If there is no cycle, then set $\mu(k - 1)$ as the outcome of the algorithm. Otherwise, select a cycle in this directed graph. For each edge $(t, s) \rightarrow (t', s')$ in the

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24 That is, 1-PE mechanisms that select two different matchings for two different profiles of preferences where teachers’ preferences remain unchanged.

25 Henceforth, given a matching $\mu$, we say that $t$ desires $s$ if $s \succ_t \mu(t)$. 

21
cycle, assign teacher \( t \) to school \( s' \). Let \( \mu(k) \) be the matching so obtained. Go to step \( k + 1 \).

Here, again, it is easy to verify that this algorithm converges in (finite and) polynomial time. Similar to our process for the BE algorithm, we do not specify how the algorithm should select the cycle of the directed graph, and thus, this algorithm defines a class of mechanisms. Each mechanism in this class is a selection of the correspondence from preference profiles to matchings corresponding to the whole set of possible outcomes that can be achieved by the 1S-BE algorithm.

By construction, starting from \( \mu(k - 1) \), the directed graph defined above is a supergraph of the directed graph that would have been built under the BE algorithm. Hence, there will be more cycles in our graph and more possibilities to improve teachers’ welfare and to shrink the set of blocking pairs. This reflects the fact that we dropped the constraint that schools’ welfare must increase along the algorithm, and thus, more can be achieved in terms of teachers’ welfare and the set of blocking pairs. This is illustrated in the following example.

**Example 4** Consider the same market as in Example 2. The graph of 1S-BE contains the edges of the graph of BE, but it has two new additional edges. Indeed, \( t_1 \) and \( t_2 \) both desire \( s_3 \) but do not block with it under \( \mu_0 \), and \( t_2 \) is preferred to \( t_1 \) at \( s_3 \); thus, the node \( (t_2, s_2) \) can now point to \( (t_3, s_3) \). Concerning \( t_3 \), he is the only one who desires \( s_1 \) and does not block with it, and thus, \( (t_3, s_3) \) can point to \( (t_1, s_1) \). Therefore, the graph of 1S-BE is as follows:

Note that now there are two additional cycles: \( (t_1, s_1) \rightarrow (t_2, s_2) \rightarrow (t_3, s_3) \rightarrow (t_1, s_1) \) and \( (t_1, s_1) \leftrightarrow (t_2, s_2) \). Having implemented the first cycle, it can be verified that there are no cycles left, and thus, the matching given by 1S-BE is

\[
\begin{pmatrix}
  t_1 & t_2 & t_3 & t_4 \\
  s_2 & s_3 & s_1 & s_4
\end{pmatrix}
\]

Note that even if one wished to select one of the two other cycles, another cycle would lead to the same matching.
Note that there are now only three blocking pairs: \((t_k, s_k)\) for \(k = 1, 2, 3\).

Following the notions introduced for the BE algorithm, we will note \(1S\text{-BE}\circ\varphi\) for the composition of BE and of a mechanism \(\varphi\). An outcome of such a (modified) \(1S\text{-BE}\) algorithm selects matchings that dominate that of \(\varphi\) both in terms of teacher welfare and the set of blocking pairs (but not necessarily in terms of school welfare); i.e., all teachers are weakly better off, and the set of blocking pairs is a subset of that of \(\varphi\). Again, in the sequel, we will be particularly interested in starting the \(1S\text{-BE}\) algorithm from the matching given by \(DA^*\), i.e., \(1S\text{-BE}\circ DA^*\).

We now turn to our characterization result. We note that, while the argument in the proof of Theorem 1 is simple, the proof of the characterization result below is non-trivial.

**Theorem 4** Fix a preference profile. The set of possible outcomes of the \(1S\text{-BE}\) algorithm coincides with the set of one-sided maximal matchings.

**Proof.** The proof is relegated to Appendix D.

Assume that matching \(\mu'\) dominates \(\mu\) in terms of teachers’ welfare and stability and consider the directed exchange graph in which teachers and their assignments under \(\mu\) stand for the vertices and where, for each pair of nodes \((t, s)\) and \((t', s')\), there is an edge \((t, s)\rightarrow(t', s')\) if and only if teacher \(t\) is assigned to \(s'\) under \(\mu'\). If \(\mu'\) were to dominate \(\mu\) in terms of teachers’ and schools’ welfare and in terms of stability, then, as argued in the proof of Lemma 1, each cycle of exchange in this graph is actually a cycle of the graph associated with the BE algorithm. This is central to the characterization result in Theorem 1. In the present case, in which \(\mu'\) dominates \(\mu\) in terms of teachers’ welfare and blocking pairs (but not necessarily in terms of schools’ welfare), one may expect that these cycles of exchange would be cycles of the graph associated with the \(1S\text{-BE}\) algorithm. This turns out not to be the case, and this is an important source of difficulty in the argument to prove Theorem 4. However, although cycles of exchange are not necessarily cycles of \(1S\text{-BE}\), we show that, whenever there is a \(\mu'\) that dominates \(\mu\) in terms of teachers’ welfare and stability, there must exist a cycle in the graph (which may not be a cycle of exchange) of \(1S\text{-BE}\) starting from \(\mu\). With this existence, one direction of Theorem 4 can easily be proved. Indeed, given a matching \(\mu\) obtained with the \(1S\text{-BE}\) algorithm, if, toward a contradiction, it is not one-sided maximal, then, by definition, there must exist a matching \(\mu'\) that 1-Pareto dominates \(\mu\), such that its set of blocking pairs is a subset of that of \(\mu\). However, in that case, we know that there must exist a cycle in the graph associated with \(1S\text{-BE}\) starting at \(\mu\), which contradicts the fact that \(\mu\) is a matching obtained with the \(1S\text{-BE}\) algorithm.

Here, this result also provides a computationally easy procedure to find one-sided maximal matchings. As for the BE algorithm, it is easy to construct selections of the \(1S\text{-BE}\) algorithm that are not strategy-proof. In light of Theorem 3, an outstanding question naturally arises: is there any selection of the \(1S\text{-BE}\) algorithm that is strategy-proof? While there is a unique selection of the BE algorithm that is strategy-proof, the next result provides a negative answer for the \(1S\text{-BE}\) algorithm.
Theorem 5  There is no selection of the 1S-BE algorithm that is strategy-proof.

Proof. The proof is relegated to Appendix E. □

This result highlights an important difference between the classes of two-sided and one-sided maximal mechanisms. One can understand the difference as follows. In contrast to the graph of BE, 1S-BE can have an edge \((t, s) \rightarrow (t', s')\) if \(t\) desires \(s'\) and \(t\) is ranked first by \(s'\) among teachers who both desire \(s'\) and do not block with \(s'\). Because of this condition, a teacher can modify the pointing behavior of others: indeed, if \(t\) is ranked first by \(s'\) among teachers who both desire \(s'\) and do not block with \(s'\), then teacher \(t\) can change the set of outgoing edges of other teachers depending on whether he claims that he desires \(s'\). In the course of the argument for Theorem 5, we rely on this additional feature. Indeed, we present an instance in which, for each possible selection of cycles under the 1S-BE algorithm, one teacher can profitably misreport his preferences. Two types of manipulations are used in that case: one is basic and consists of ranking as acceptable an unacceptable school in order to be able, once matched with it, to exchange it for a better one. However, for some selections of cycles, another manipulation is needed whereby a teacher ranks as unacceptable an acceptable school to expand the set of outgoing edges of other teachers. Again, this new type of manipulation is central to the argument in Theorem 5 and is not available under the BE algorithm.

Before closing this section, we note that the 1S-BE algorithm shares some similarities with the stable improvement cycle (SIC) algorithm defined by Erdil and Ergin (2008). Indeed, the 1S-BE can be seen as a generalization of the SIC algorithm. To further discuss this relationship, let us recall the definition of the SIC algorithm.

- **Step 0**: set \(\mu(0) := \mu_0\).

- **Step \(k \geq 1\)**: Given \(\mu(k - 1)\), let the teachers and their assignments stand for the vertices of a directed graph, where for each pair of nodes \((t, s)\) and \((t', s')\), there is an edge \((t, s) \rightarrow (t', s')\) if and only if \(t\) desires \(s'\) and \(t\) is ranked first by \(s'\) among teachers who desire \(s'\). If there is no cycle, then set \(\mu(k - 1)\) as the outcome of the algorithm. Otherwise, select a cycle in this directed graph. For each edge \((t, s) \rightarrow (t', s')\) in the cycle, assign teacher \(t\) to school \(s'\). Let \(\mu(k)\) be the matching so obtained. Go to step \(k + 1\).

The SIC algorithm has been constructed to improve on stable outcomes whenever an outcome is not teacher-optimal, as is the case, for instance, with the outcome of the teacher-proposing DA when schools have weak preferences. Now, note that when we start from a stable outcome, SIC and 1S-BE are the same. Obviously, in our environment, in which schools have strict preferences, if we start from the outcome of DA – which here is the teacher-optimal stable assignment – the SIC and the 1S-BE do not have any cycles in their associated directed graphs. More generally, if we were to weaken the assumption of strict preferences on the school side, the 1S-BE and the SIC algorithm – starting from DA – would yield the same set of possible outcomes. However, our mechanism goes much further in extending the properties
of the SIC algorithm to cases in which the starting assignment is arbitrary. To illustrate why this is true and why we cannot make use of the SIC algorithm for our purposes, consider one of our initial motivations, which is to find ways to improve on the outcome of DA$^*$. Both BE$\triangleright$DA$^*$ and 1S-BE$\triangleright$DA$^*$ succeed in doing so. However, the SIC algorithm (starting from the outcome of DA$^*$) is of no help for this purpose. To see this, recall that, under the SIC algorithm, $(t, s) \rightarrow (t', s')$ if and only if $t$ desires $s'$ and $t$ is ranked first by $s'$ among teachers who desire $s'$. Because, given the individual rationality of DA$^*$, no teacher desires his initial assignment under the matching achieved by DA$^*$, the pointing behavior – and hence the directed graph – associated with SIC (starting from DA$^*$) remains unchanged if we use the modified schools’ preferences used to run DA$^*$ as opposed to the true schools’ preferences. However, under the modified preferences, by definition, DA$^*$ yields the teacher-optimal stable matching. Hence, there cannot be any cycle in the graph associated with SIC (again, starting from DA$^*$).

4.3 Large Markets

Let us summarize our findings thus far. We provided a stylized example in which DA$^*$ performs poorly in terms of the set of teachers moving from their initial position. Due to this lack of movement, we show that one can improve on this algorithm in terms of the welfare of both teachers and schools, as well as set of blocking pairs. We provide a whole class of mechanisms – characterized by the BE algorithm – that does not suffer from such flaws. While this seems to be an improvement over DA$^*$, this is still quite weak. As mentioned above, these results essentially show that DA$^*$ is not on the Pareto frontier, while our mechanisms are. These theoretical findings raise a new set of questions concerning both the magnitude of the underperformance of DA$^*$ and the performance of the different selections of the BE algorithm. To answer these questions, we adopt a large-market approach in this section that allows us to quantify some aspects of the mechanisms’ performance when the market grows.

Specifically, the aim of this section is to answer three questions. First, since lack of movement is an important weakness of DA$^*$, we may naturally wonder the following: Is there more movement under all selections of the BE algorithm compared to DA$^*$? Second, while all selections of the BE algorithm are two-sided maximal, as noted in Proposition 3, how do the different selections of the BE algorithm compare in terms of the welfare of teachers and schools? In particular, we ask the following: Based on standard welfare criteria, is there a best selection of BE? As we will show, there is a meaningful sense in which a best selection of BE exists in terms of welfare on both sides of the market. From our analysis of incentives, we identified a natural candidate mechanism – the teacher-optimal BE – and one may wonder how it compares with the best selection of BE. In other words, we wish to answer the following: Is there a cost of strategy-proofness? The following large-market analysis helps to answer these questions.

We assume that there are $K$ tiers for the schools. More precisely, there is a partition
{S_k}_{k=1}^K of S such that the utility of teacher t for school s ∈ S_k (k = 1, ..., K) is given by

$$U_t(s) = u_k + \xi_{ts}$$

where $\xi_{ts} \sim U[0,1]$. We assume that $u_1 > u_2 > ... > u_K$. For each $k = 1, ..., K$, we denote by $x_k$ the fraction of schools having common value $u_k$ and further assume that $x_k > 0$.

This distribution of preferences in terms of tiers allows for some type of positive correlation in teachers’ preferences. Prior literature has highlighted the positive correlation in preferences. Indeed, by studying teachers’ preferences for schools in the US, Boyd et al. (2013) find that teachers demonstrate preferences for schools that are suburban and have a smaller proportion of students in poverty. In addition, although this structure is special, we believe that the basic insights obtained under these distributions extend far beyond this class of distributions.

For schools’ preferences, we assume that

$$V_s(t) = \eta_{ts}$$

where $\eta_{ts} \sim U[0,1]$. The additive separability structure of our utilities and the specific uniform distribution employed are not essential to our argument. In addition, we could assume that school’s preferences are drawn in a similar way as students’ preferences (allowing tiers); in that case, our results would remain essentially the same. Schools’ preferences are based only on an idiosyncratic shock in order to simplify the exposition.

Finally, the initial assignment $\mu_0$ is selected at random among all possible $n!$ matchings, where $n := |T| = |S|$. A random environment is hence characterized by the number of tiers, their size and common values $[K, \{x_k\}_{k=1}^K; \{u_k\}_{k=1}^K]$. The maximum normalized sum of teachers’ payoffs that can be achieved in this society is $\bar{U}_T := \sum_{k=1}^K x_k (u_k + 1)$, which is attained if all teachers are matched to schools with which they enjoy the highest possible idiosyncratic payoff. The maximum normalized sum of schools’ payoffs that can be achieved in this society is $\bar{V}_S := 1$, which is attained if all schools are matched to teachers with which they enjoy the highest possible idiosyncratic payoff. Clearly, in our environment, in which preferences are drawn randomly, a mechanism can be seen as a random variable. In the sequel, we let $\varphi(t)$ be the random assignment that teacher t obtains under mechanism $\varphi$.

27 In France, in our dataset, we also observe that some school regions are systematically preferred to others, as measured by the number of teachers ranking these regions first. Performing this exercise shows a clear pattern of tiers: whereas 43 and 57 teachers (out of 10,579) rank the regions of Amiens and Créteil first, respectively, more than 1,000 teachers rank the attractive regions of Paris, Bordeaux or Rennes as their first choices. The differences observed are likely related to differences across regions in the proportion of students from disadvantaged social backgrounds or minority students.

28 We essentially need utilities to be continuous and increasing in both components and the distribution of the idiosyncratic shocks to have full support in a compact interval in $\mathbb{R}$.

29 More precisely, the only issue when introducing a richer class of schools’ preferences is that asymptotic stability and individual rationality become incompatible. However, if we ignore asymptotic stability, all of our results can be extended when allowing the richer class of preferences.

26
In general, our mechanisms will fail to achieve the maximum sum of utilities on either side. However, a meaningful question is how often this phenomenon occurs when the market increases in size. The following concepts will help to answer this question. We say that a mechanism $\varphi$ **asymptotically maximizes movement** if, for any random environment, 

$$\frac{|\{t \in T | \varphi(t) \neq \mu_0(t)\}|}{|T|} \xrightarrow{p} 1.$$ 

A mechanism $\varphi$ is **asymptotically teacher-efficient** if, for any random environment, 

$$\frac{1}{|T|} \sum_{t \in T} U_t(\varphi(t)) \rightarrow_p \bar{U}_T.$$ 

Similarly, $\varphi$ is **asymptotically school-efficient** if, for any random environment, 

$$\frac{1}{|S|} \sum_{s \in S} V_s(\varphi(s)) \rightarrow_p \bar{V}_S.$$ 

Finally, $\varphi$ is **asymptotically stable** if, for any random environment and any $\varepsilon > 0$, 

$$\frac{|\{(t, s) \in T \times S | U_t(s) > U(\varphi(t)) + \varepsilon \text{ and } V_s(t) > V(\varphi(t)) + \varepsilon\}|}{|T \times S|} \xrightarrow{p} 0.$$ 

The next three results provide some answers to the three questions posed at the beginning of this section. The proofs of these results are relegated to Appendix F (except for Theorem 6).

**Theorem 6** $DA^*$ does not maximize movement, and hence, it is not asymptotically teacher-efficient, asymptotically school-efficient, or asymptotically stable.

The basic idea behind the above theorem is very similar to the underlying argument in Example 1. Indeed, consider a random environment with two tiers of schools (i.e., $K = 2$) where the second tier corresponds to “bad” schools (while the first corresponds to “good” schools). Formally, we assume that $u_1 > u_2 + 1$, and thus, irrespective of the idiosyncratic shocks, a school in tier 1 is always preferred to a school in tier 2. The intuition for the result is as follows. Fix any teacher $t$ initially assigned to a school in the first tier. With non-vanishing probability, if $t$ applies to a school in tier 1 other than his initial assignment, some teacher in the second tier will be preferred by that school. Hence, teacher $t$ will be replaced by that teacher. This simple argument implies that – among teachers initially assigned to schools in tier 1 – the expected fraction of teachers staying at their initial assignment is bounded away from 0.

Specifically, for each $k = 1, 2$, let $T_k$ denote the set of teachers who are initially assigned to a school in $S_k$. Consider any teacher $t \in T_1$. Let $E_t$ be the event that for each school $s \in S_1$, there is a teacher $r \in T_2$ s.t. $r$ is ranked above $t$ (according to $s$’s preferences). Note that, for a school $s$, the probability that $t$ is ranked above each individual in $T_2$ is the probability that
\( \{t\} = \arg \max \{ \eta_{t^e}, \eta_{r^e} \}_{r \in T_2} \). Since \( \{ \eta_{t^e}, \eta_{r^e} \}_{r \in T_2} \) is a collection of iid random variables, for each \( r \in T_2 \), by symmetry, the probability that the maximum is achieved by \( t \) must be the same as the probability that it is achieved by any \( r \in T_2 \). Hence, the probability of \( \{t\} = \arg \max \{ \eta_{t^e}, \eta_{r^e} \}_{r \in T_2} \) must be \( \frac{1}{1 + |T_2|} \). We can now easily compute the probability of \( E_t \):

\[
\Pr(E_t) = \left( 1 - \frac{1}{|T_2| + 1} \right)^{|S_1|} = \left( \left( 1 - \frac{1}{|T_2| + 1} \right)^{|T_2|} \right)^{|S_1|/|T_2|}
\]

\[
\to \left( \frac{1}{e} \right)^{x_1/x_2} \quad \text{as } n \to \infty.
\]

Note that, using the same logic as in Example 1, whenever \( E_t \) occurs, \( t \) cannot move from his initial assignment. Indeed, if \( t \) applies to some school \( s \), this must be to a school in \( S_1 \). However, by construction, each teacher \( t \in T_2 \) applies to each school in \( S_1 \). In particular, the teacher in \( T_2 \) being ranked above \( t \) by school \( s \) applies to \( s \), showing that, eventually, \( t \) cannot be matched to \( s \) under DA*. Thus, the expected fraction of individuals in \( T_1 \) who do not move must be

\[
\frac{1}{|T_1|} \mathbb{E} \left[ \sum_{t \in T_1} 1_{\{t \text{ does not move} \}} \right] = \frac{1}{|T_1|} |T_1| \mathbb{E} \left[ 1_{\{t \text{ does not move} \}} \right] = \Pr \{ t \text{ does not move} \} \geq \Pr(E_t).
\]

Thus, the lim inf of the expected fraction of teachers not moving is bounded away from 0. Note that the lower bound computed here can be improved. Indeed, for \( t \) not to move, one only needs that, for each school \( s \in S_1 \) that \( t \) finds acceptable, there is a teacher \( r \in T_2 \) s.t. \( r \) is ranked above \( t \) (according to \( s \)’s true preferences). In general, simulations suggest that a much larger fraction of teachers are not moving. In addition, these simulations show that the assumption we made above that \( u_1 > u_2 + 1 \) is not necessary and that the result seems to hold in much broader contexts.\(^{30}\) Let us now think of the best possible outcome of the BE algorithm. While the way to implement this outcome may not be practical, we consider this a benchmark and want to compare this to what can typically be achieved by mechanisms that can be implemented easily, such as TO-BE.

**Theorem 7** Each selection of BE asymptotically maximizes movement. There is a selection of BE that is asymptotically teacher-efficient, asymptotically school-efficient and asymptotically stable.

The intuition for the first part of the result is basic. Indeed, assume, toward a contradiction, that the set of teachers not moving under some selection of BE is large. For each pair of

\(^{30}\)Available upon request.
teachers $t$ and $t'$ in that set, the probability that $t$ blocks with the initial assignment (and hence the assignment under the given selection) of $t'$ and that, vice versa, $t'$ blocks with the initial assignment of $t$ (and thus gains from the assignment under the given selection) is bounded away from 0. Hence, given our assumption that the set of teachers not moving is large, with high probability, there will be such a pair of teachers. In other words, there will be a cycle in the graph associated with BE when starting from the assignment given by the selection, which contradicts the definition of a selection.

As for the other part of the theorem, the intuition can be seen as follows: for a given tier $k$, for any school in $S_k$ and any agent initially matched to such a school in $S_k$, the probability that they both enjoy high idiosyncratic payoffs when matched with one another is bounded away from 0. Thus, as the market grows, with a probability approaching one, one can appeal to Erdős-Rényi’s result on the existence of a (perfect) matching within the set of individuals and schools. However, there are two difficulties here. First, one has to ensure the individual rationality of the matching so obtained, which we do by restricting the set of teachers and schools to those having idiosyncratic payoffs for their initial match bounded away from the upper bound. Second, in the sketch we just provided, we implicitly assume that the designer has access to an agent’s cardinal utilities. However, in this paper, we assume—as is usually the case in practice—that matching mechanisms map ordinal preferences into matchings, and a large part of the proof is devoted to addressing this issue.

Now, as we have already noted, while the BE algorithm treats teachers and schools symmetrically, TO-BE favors teachers at the expense of schools. Thus, it is natural to expect that TO-BE is asymptotically teacher-efficient. In addition, TO-BE ensures only that schools are assigned a teacher that they weakly prefer to their initial assignment. Hence, for each school, its assignment under TO-BE is a random draw within the set of teachers that it finds acceptable. Thus, given its idiosyncratic payoff for its initial assignment $\eta_{\mu_0(s)s}$, the expected payoff of a school $s$ under TO-BE is $E[\eta_{st} \mid \eta_{st} \geq \eta_{\mu_0(s)s}] = \frac{1}{2} (1 + \eta_{\mu_0(s)s})$. Thus, the unconditional expected payoff of school $s$ under TO-BE is $E[\frac{1}{2} (1 + \eta_{\mu_0(s)s})] = \frac{3}{4}$. Thus, TO-BE cannot be asymptotically school-efficient.

**Theorem 8** TO-BE is asymptotically teacher-efficient. Under TO-BE, the expected payoff of a school is $\frac{3}{4}$, and thus, TO-BE is neither asymptotically school-efficient nor asymptotically stable.

The heuristic to understand why TO-BE is asymptotically teacher-efficient is as follows: assume it is not. This implies that for some tier, there is a large set of teachers who are obtaining an idiosyncratic payoff bounded away from the upper bound. Now, for each pair of teachers $t$ and $t'$ in that set, intuitively, the probability that $t$ blocks with the assignment of $t'$ and that, vice versa, $t'$ blocks with the assignment of $t$ is bounded away from 0. Hence, given our assumption that the set of teachers not moving is large, intuitively, with high probability, there will be a cycle in the graph associated with BE when starting from the assignment given by the selection, which contradicts the definition of a selection. While this is an intuitive way of describing
the result, there is a difficulty here. Indeed, if we fix the set of teachers who are obtaining an idiosyncratic payoff bounded away from the upper bound, this has some implications for the distribution of preferences. Hence, there is a conditioning issue, and the intuition provided above does not take this into account. This raises an important technical difficulty that we circumvent using random graph arguments in the spirit of those developed by Lee (2014) and, more specifically, Che and Tercieux (2015b).

From the above, we should expect several results from our data analysis. First, DA* should rarely be two-sided maximal, particularly in markets with a large number of teachers. In addition, the BE algorithm and TO-BE should ensure more movement than DA* and perform better in terms of teachers’ welfare. We will see that our data analysis largely confirms these findings. We should also expect TO-BE to perform more poorly than the BE algorithm: TO-BE may exhibit a loss in terms of schools’ welfare and blocking pairs relative to the BE algorithm. In terms of schools’ welfare and the set of blocking pairs, it is not clear a priori how to compare TO-BE and DA*. Our data analysis will help further discriminate between these mechanisms.

5 Empirical Analysis

The aim of this section is to assess our theoretical findings using a dataset on the assignments of all public school teachers in France. We provide a brief presentation of the dataset. Then, we run counterfactual scenarios for our mechanisms and measure the extent of the improvements they may yield in terms of school and teacher welfare, as well as fairness.

5.1 Data

We use several datasets related to teacher assignment in 2013. For both the first and the second phases of the assignment, these datasets contain four pieces of information: (1) teachers’ reported preferences, (2) regions/schools’ priorities, (3) each teacher’s initial assignment (if any) and (4) regions/schools’ vacant positions. This empirical study focuses on the first phase of the assignment primarily because teachers have incentives to report their preferences sincerely, and the preferences we observe are more straightforward to interpret. Several features of the assignment process support this position. First, since the mechanism in use is DA* with no limit on the number of regions teachers can rank, it is a dominant strategy for all agents to be truthful. The fact that strategy-proof mechanisms generate reliable preference data for guiding policy is a common argument in their favor (see, e.g., Abdulkadiroglu et al. 31

31Given the agents’ assessments over schools they may obtain in the second phase, agents have well-defined preferences over regions.

32As discussed in Appendix H, preferences reported during the second phase of the assignment are more difficult to interpret because of both a binding constraint on the number of schools teachers can rank and the ability to rank larger geographic areas than a school (cities, for instance).
Second, since the ministry manages the assignment process in partnership with teachers’ trade unions, teachers are very well informed about the entire process, and trade unions have never advised teachers to strategically rank the school regions. We therefore take for granted that agents’ reported preferences in Phase 1 are the true preferences to run our counterfactuals.

The sample of teachers used for the analysis takes into account two restrictions. First, the sample is restricted to the 49 subjects that contain more than 10 teachers. Second, to match our theoretical framework, all initially non-matched teachers (newly tenured) and all empty seats in regions are suppressed. Hence, the initial assignment corresponds to a market in which each teacher is initially assigned to a region and each seat in each region is initially assigned a teacher. The final sample contains 10,579 teachers corresponding to 49 subjects ranging from 6 to 1,753 teachers. We end this section by providing two pieces of information on this market.

**Fact 0** (i) Under the regular DA mechanism, there are at least 1,325 teachers for whom individual rationality is violated; i.e., they are assigned to a region that they consider worse than their initial region. (ii) The individually rational mechanism that maximizes movement allows 2,257 teachers to move from their initial assignment.

This shows that the regular DA mechanism is indeed not individually rational in this market, and the violation of individual rationality is quite strong. The second point shows that there is congestion on this market: if we focus only on individually rational matchings and attempt to ensure as much movement as possible, 21% of teachers will be able to move. We should bear in mind this upper bound when considering the performance of our algorithms and the scope of their improvement.

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33 This assumption is sometimes challenged, however. See, for instance, Fack et al. (2015).
34 The mobility process is the main source of teacher unionization in France. Because competition exists between trade unions, they have high incentives to provide detailed information and tailored help for teachers throughout the process. In practice, trade unions help teachers to identify the criteria they can use to compute their priorities, they negotiate the number of positions offered in each region with the ministry, and they validate the mobility project submitted by the ministry.
35 In our dataset, for each teacher, we have the reported preferences only up to his initial region. Hence, we do not know how teachers rank regions below their initial assignment. However, one can show that, when running DA on these truncated preferences, the number of unassigned teachers is a lower bound on the number of teachers for whom individual rationality is violated when running DA on the full preference lists.
36 To find such an assignment, we build a bipartite graph with teachers on one side and schools on the other side. We consider the complete bipartite graph, where each edge will be associated with a weight. We assign weight $\infty$ to edges $(t, s)$, where $s$ is unacceptable to $t$ (i.e., worse than his initial assignment). We assign weight 1 to the edge if $t$ is initially matched to $s$. Finally, we assign weight 0 to all other edges (i.e., if $t$ finds $s$ strictly better than his initial assignment). The weight of a matching is defined as the sum of weights over all its edges. We use a standard algorithm to find a matching with minimal weight (see Kuhn (1955) and Munkres (1957)). It is easily verified that such a matching maximizes movement among all individually rational matchings.
37 The relatively small fraction of teachers able to move is explained primarily by the high proportion of teachers reporting short lists. Indeed, on average, teachers rank 1.64 regions and 75% of teachers ask for only
5.2 Results

5.2.1 Preliminaries: many-to-one

Before turning to the description of the results, we need to briefly discuss the generalization of our mechanisms to the many-to-one framework. A school/region can now be assigned several teachers, and starting with preferences over single teachers, we need to define schools’ preferences for a group of teachers. We adopt a very conservative approach here that will only strengthen our main empirical findings. Consider a school/region with $q$ positions to fill and two vectors of size $q$, say $x := (t_1, \ldots, t_q)$ and $y := (t_1, \ldots, t_q)$. Let us assume that each of these vectors is ordered in such a way that for each $k = 1, \ldots, q - 1$, the $k$th element of vector $x$ is preferred to its $k + 1$th element; we make analogous assumptions for vector $y$. We say that $x$ is preferred by the school/region to $y$ if, for each $k = 1, \ldots, q$, the $k$th element of vector $x$ is (weakly) preferred to the $k$th element of vector $y$.

With this definition in mind, all our concepts (two-sided maximality or one-sided maximality) can be naturally extended. Mechanisms characterizing these notions can also be easily extended. Because these are the mechanisms we use to run our counterfactuals, we state them precisely in Appendix G.

The aim of the following empirical analysis is to test our theoretical results. Therefore, we will focus on three main dimensions: teachers’ welfare, regions’ welfare and number of blocking pairs. Since BE and 1S-BE define a class of mechanisms, we randomly select outcomes within this class. As is made clear in Appendix G, in a many-to-one environment, TO-BE is extended to a class of mechanisms parametrized by an ordering over teachers. We randomly select an ordering and hence randomly select an outcome in this class. We randomly draw selections for each mechanism ten times. In addition, there are indifferences in priorities of regions over teachers.\(^{38}\) We use a single tie-breaking rule to break ties in regions’ priorities. We draw randomly the tie-breaking rule ten times. The results reported in Tables 1 to 3 for BE, TO-BE and 1S-BE correspond to average outcomes over one hundred draws – ten random selections of tie-breaking rules times ten random selections of outcomes. The results for DA* correspond to an average over ten iterations of tie-break only. The results for the BE algorithm and the 1S-BE are successively presented in the next section.\(^{39}\)

\(^{38}\)Many young teachers use only one criterion – the number of years of experience – to compute their priorities, and thus, they have the same priority in a given region.

\(^{39}\)As explained in Section 2, regions use multiple criteria to rank teachers (spousal reunification, disability, having a position in a disadvantaged or violent school, total seniority in teaching, seniority in the current school, time away from the spouse and/or children, etc). However, when running our alternative algorithms, we use only the seniority criteria (both total seniority in teaching and seniority in the current school) to determine a teacher’s priority in his initial region. Indeed, the other criteria are supposed to help a teacher to leave his current region, so it would not make sense to use these criteria for the region to which he is currently assigned.
5.2.2 Two-sided maximality: BE and TO-BE

How far is DA* from being two-sided maximal?

In the theoretical analysis, we noted an important flaw of DA*: it can be improved in three main dimensions, namely, teachers’ welfare, regions’ welfare and fairness. In practice, a first simple way to test whether DA* is two-sided maximal is to run the BE algorithm starting from the matching obtained by DA* and then to observe whether the two matchings obtained with DA* and BE◦DA* differ. If they differ, this means that some cycles exist in the graph associated with the BE algorithm starting from DA*, and thus, DA* is not two-sided efficient, which is a necessary condition for two-sided maximality. Fact 1 below illustrates that point in our data:

Fact 1 DA* is not two-sided maximal in 33 out of 49 subjects. These subjects represent 95.9% of the teachers. 40

This first fact suggests that the theoretical phenomenon we highlight is not rare. Based on this observation, we now estimate how far DA* is from maximality in terms of the three criteria in which we are interested. Regarding teachers’ welfare, two results reported in Table 1 are worthy of comment. First, on average, BE◦DA* more than doubles the number of teachers who are assigned to a new region relative to DA*: 565 teachers move from their initial allocation under DA* versus 1,488 under BE◦DA*. Second, the same table reports the cumulative distribution of the number of teachers who obtain school rank \(k\). While we know from the theory that the distribution of the rank obtained by teachers under BE◦DA* first-order stochastically dominates this same distribution under DA*, the dominance is indeed significant.

There are several possible measures of regions’ welfare. We focus below on one natural approach; however, we test the robustness of our results to the use of alternative approaches, which yield no significant differences in the results. Given a mechanism, we examine the improvement a region obtains (from the initial assignment) in terms of the number of positions improved. More precisely, given a region, we first take the initial assignment and sort it by decreasing order of priorities. We obtain a vector in which the first element/position is the teacher with the highest priority in that region at the initial assignment, the second element/position is the teacher with the second highest, and so forth. Call this vector \(x\). We perform the same operation for the assignment of this region with the mechanism under study. Let us call this vector \(y\). Finally, we say that a position \(k\) is assigned a teacher with higher (resp., lower) priority if the \(k\)th element of vector \(y\) has a higher (resp., lower) priority than

40 Even if BE◦DA* = DA*, it could be the case that DA* is not two-sided maximal. Indeed, in our definition of two-sided maximality, we require that schools must not be harmed relative to the initial allocation. Since DA* may harm schools, it can be two-sided Pareto efficient but still violate two-sided maximality. In 30 subjects, BE◦DA* ≠ DA*, and in 3 subjects, BE◦DA* = DA*, but DA* harms the welfare of at least one region relative to the initial assignment. Finally, we note that, if we restrict our attention to the 19 subjects with more than 100 teachers, in only one subject is DA* two-sided maximal.
the $k$th element of vector $y$. Based on this, we compute the percentage of net improvement in positions, i.e., the percentage of positions receiving a teacher with a higher priority minus the percentage of positions being assigned a teacher with a lower priority.

Table 3 reports, for the different mechanisms we run, the cumulative distribution of the percentage of net improvement in positions, i.e., for each percentage $x$, the proportion of regions having less than $x$ percent of net improvement in positions. Again, we observe that the distribution under $\text{BE} \circ \text{DA}^*$ first-order stochastically dominates this same distribution under $\text{DA}^*$.

Finally, we compare the performance of $\text{DA}^*$ and $\text{BE} \circ \text{DA}^*$ in terms of fairness. The first row of Table 2 reports that, on average, 2,496.5 teachers are not blocking under $\text{DA}^*$ and 3,799.4 are not blocking under $\text{BE} \circ \text{DA}^*$, which represents a 52.1% increase in the number of teachers who are not blocking with any region. More generally, we observe that fairness is significantly increased.\footnote{The number of teachers who are part of a blocking pair is quite high. This is intuitive since the number of teachers moving is low and many teachers stay at their initial allocation, thus possibly creating envy. This can be seen as the cost of imposing the individual rationality constraint.}

Overall, these results show that $\text{DA}^*$ fails to be two-sided maximal in a large number of cases, and the scope of improvement seems to be very large. To address this issue, a first natural candidate would be to run the BE algorithm from the assignment achieved by $\text{DA}^*$. However, as mentioned in our theoretical analysis, this mechanism is prone to easy manipulations. Alternatively, we focus our attention on both the BE algorithm that is run directly from the initial assignment (this is referred to as BE(Init) in our tables and graphs) and its strategy-proof selection: the TO-BE mechanism. In the next section, we evaluate the performance of these two mechanisms in terms of teachers’ welfare, regions’ welfare and the number of blocking pairs.

**Performance of BE and TO-BE**

Before commenting on the results, it is worth briefly discussing the relevance of comparing BE and TO-BE to $\text{DA}^*$. We should bear in mind that, for an arbitrary outcome of the BE mechanism, its set of blocking pairs may differ from that of $\text{DA}^*$, and similarly, the outcome may not 2-Pareto dominate $\text{DA}^*$. However the comparison remains interesting for two reasons. First, we know from the above results that $\text{DA}^*$ is far from being two-sided maximal, and thus, BE and TO-BE – which are two-sided maximal – can be expected to perform much better. Second, our theoretical results (Theorems 6, 7 and 8) suggest that BE and TO-BE perform better in large markets than $\text{DA}^*$.

We first focus our attention on the performance of BE and TO-BE in terms of teachers’ welfare. Both mechanisms significantly improve the number of teachers moving relative to $\text{DA}^*$: on average, 565 teachers obtain a new assignment under $\text{DA}^*$, versus 1,461.5 under BE and 1,373 under TO-BE.

**Fact 2** The distribution of ranks obtained by teachers under TO-BE first-order stochastically...
dominates the distribution of BE, which dominates that of DA∗.

Note, however, that there is no 2-Pareto domination between the matchings: some teachers may prefer their assignment under DA∗ to the one that they obtain under BE or TO-BE.\textsuperscript{42}

Regarding stability, BE and TO-BE also perform significantly better than DA∗. Table 2 shows that the average number of teachers not being part of a blocking pair increases from 2,496.5 under DA∗ to 3,731.3 and 3,742.7 under BE and TO-BE, respectively.

**Fact 3** The distributions of the number of regions teachers can block with under DA∗, BE and TO-BE can be ranked stochastically: DA∗ is dominated by BE, which is dominated by TO-BE.\textsuperscript{43}

Finally, comparing regions’ welfare across mechanisms is of particular interest, as we know that DA∗ can harm some regions, in contrast to BE and TO-BE. This is confirmed by Table 3. Under DA∗, 1.04% of the regions have at least 1% of their positions assigned a teacher with a lower priority than under the initial assignment. On the contrary, under BE and TO-BE, no region has a position for which the teacher assigned to it has a lower priority than the teacher initially assigned to that position.

**Fact 4** The distributions of the percentage of net improvement in positions can be stochastically ordered: the distribution of DA∗ is dominated by that of TO-BE, which is dominated by that of BE.

The lower performance of TO-BE compared to BE in terms of regions’ welfare is in line with our theoretical predictions regarding the cost of the strategy-proofness imposed by TO-BE (Theorem 7 and 8).

Overall, these results suggest that BE and TO-BE perform much better than DA∗ in terms of teachers’ welfare, regions’ welfare and fairness. The good performance of TO-BE is of particular interest due to its incentive properties. These results provide evidence that, although two-sided maximality is a strong requirement, our mechanisms can generate large improvements and distributions dominating those of DA∗.\textsuperscript{44} The next section tests whether we can further improve upon DA∗ by relaxing the constraint that no region should be harmed (relative to the initial assignment). To do so, we provide empirical evidence on the performance of 1S-BE, the one-sided maximal algorithm we defined in Section 4.2.

\textsuperscript{42}On average, 258.5 teachers obtain a region they rank strictly higher under DA∗ than under BE (254.5 under TO-BE). Conversely, 1,152.7 teachers strictly prefer their assignment under BE to that under DA∗, and the corresponding number is 1,096.7 under TO-BE.

\textsuperscript{43}As discussed for teachers’ welfare, it is worth noting that the set of blocking pairs of each matching may differ. Some teachers may block with a region under BE or TO-BE but not under DA∗.

\textsuperscript{44}These results are all the more encouraging because they are obtained in a restrictive environment in which teachers rank a very limited number of regions. Even better results could be expected in environments in which agents have longer ranked lists.
5.2.3 One-sided maximality: 1S-BE

As done previously for BE and TO-BE, we first aim to estimate how far DA* is from being one-sided maximal. To do so, we compare the matching under DA* to that under 1S-BE that we run from DA*. For a large number of subjects, we have seen that DA* is not two-sided maximal; thus, it is not one-sided maximal. Because the constraint on regions’ welfare is relaxed under 1S-BE relative to BE, the improvements we have found for BE◦DA* in terms of teachers’ welfare and blocking pairs can be seen as a lower bound on the potential improvements under 1S-BE◦DA*. Indeed, Table 1 reports that 1S-BE◦DA* yields a threefold increase in the number of teachers moving relative to DA* and increases this figure by 15% compared to BE◦DA*. This suggests that there is still significant potential for improvement with respect to considering one-sided maximality.

Fact 5 DA* is not one-sided maximal in 31 subjects, and 95.3% of the teachers belong to these subjects. In one subject, DA* is two-sided maximal but not one-sided maximal.

We now turn to the results on 1S-BE starting from the initial allocation (referred to as 1S-BE(Init) in our tables and graphs) to compare its performance with that of the other mechanisms. Regarding teachers’ welfare and fairness, the distributions of both the ranks obtained by teachers (Table 1) and the number of teachers blocking (Table 2) under 1S-BE stochastically dominate the distribution of all other algorithms mentioned previously: BE, TO-BE and DA*. Finally, regions’ welfare is the key difference between two- and one-sided maximality. Even if improvements in teachers’ welfare and fairness are large with 1S-BE, we know that this comes at the expense of the regions’ welfare.

Fact 6 Under 1S-BE, in 4.9% of the regions, the percentage of positions filled by a teacher with a lower priority is higher than the percentage of positions filled by a teacher with a higher priority. This is in contrast with BE or TO-BE, under which, by definition, regions cannot be assigned teachers with a lower priority relative to the initial assignment.

6 Concluding Remarks

In many countries, a central administration is in charge of assigning teachers to schools. In an attempt to ensure that every teacher is assigned to a school that he or she weakly prefers to his or her current one, several countries have adopted a modified version of the well-known deferred acceptance mechanism (DA) for teacher assignment. In this paper, we show that this mechanism fails to be fair and efficient for both teachers and schools. Ensuring that schools are not harmed by teacher reassignments is important as schools’ priorities partly reflect a social objective, notably in terms of the experience of teachers assigned to deprived schools. To

45 As explained above, some teachers may prefer their match under DA*; 195 teachers do so under 1S-BE, which is less than the corresponding figure under BE or TO-BE.
address the weakness of modified version of DA, we characterize the class of mechanisms that cannot be improved upon in terms of both efficiency and fairness, and we show that this class contains a unique strategy-proof mechanism. We further test and confirm the performance of this alternative mechanism by showing that it performs much better in terms of utilitarian efficiency and fairness when the market size grows. Finally, we use a rich dataset on teachers’ applications for transfers in France to measure the relevant gains. Compared to the modified version of DA, this counterfactual analysis shows significant efficiency and fairness gains. In particular, the number of teachers moving from their initial assignments more than doubles under our mechanism.

In the design of school choice allocation mechanisms, the notions of efficiency and fairness have received considerable attention. In this context, it is known that these two goals are incompatible (see Roth (1982), Abdulkadiroglu and Sonmez (2003) and Abdulkadiroglu et al. (2009)). Efficient matching mechanisms, such as the top trading cycle, attain efficiency but fail to be fair. Fair mechanisms such as the DA algorithm do not guarantee efficiency. This trade-off between efficiency and fairness is well studied; in particular, it is well understood how to attain one objective with the minimum possible sacrifice of the other goal.\textsuperscript{46} Hence, the task for the designer often boils down to a choice between two mechanisms: the DA mechanism in which students propose or the top trading cycle mechanism.\textsuperscript{47} In contrast, our work shows that, in the teacher assignment problem, the individually rational version of DA identified in the literature can be improved in terms of both efficiency and fairness. In addition, we identify a mechanism closely related to the top trading cycle mechanism (TO-BE) as a natural alternative for a designer concerned with these two core notions. This contrast with the previous literature is striking and makes clear that the teacher assignment problem is novel and presents important differences from previously studied contexts.

In the theoretical part of this paper, we assumed a one-to-one environment. All our results extend to the many-to-one environment, except for Theorem 3.\textsuperscript{48} Indeed, as shown in our Appendix G, there are several natural ways to extend the teacher-optimal BE to a many-to-one environment. Hence, the class of mechanisms that cannot be improved upon in terms of both efficiency and fairness does not contain a unique strategy-proof mechanism in this environment. However, in the many-to-one setting, we obtain a class of two-sided maximal mechanisms that are strategy-proof, which includes all versions of TO-BE defined in our appendix. In addition, the theoretical performance of TO-BE and BE (compared to DA\textsuperscript{*}) identified in the one-to-one environment can be observed in our empirical results where regions have several available seats, confirming that the main message of our paper extends

\textsuperscript{46}For instance, DA selects a fair matching that Pareto dominates all other fair mechanisms for the proposing side (Gale and Shapley (1962)). Similarly, there is a sense in which the top trading cycle mechanism (Abdulkadiroglu and Sonmez (2003)), which allows agents to sequentially trade their priorities, is efficient with minimal unfairness (Abdulkadiroglu et al. (2015)).

\textsuperscript{47}See also Che and Tercieux (2015a) for additional perspectives on this topic.

\textsuperscript{48}Theorem 1, 2 and 5 extend in a straightforward way. All results in the large market section (Section 4.3) are also fairly easy to extend to a many-to-one environment. The extension of Theorem 4 is non-trivial, and the proof is provided in the supplementary material section S.1.
to the many-to-one environment.

In this paper, in order to focus on improving the reallocation of teachers who initially have an assignment, we assumed away teachers who recently graduated (newcomers) and available seats at schools. In an ongoing work, we complement the current approach by incorporating vacant positions and newly recruited teachers who do not have an initial assignment. Under current practice in France, one of the most important issues is the large outgoing flow of teachers from the least attractive regions (with, as a consequence, a large incoming flow of inexperienced teachers). Importantly, in our ongoing work, we observe that, under TO-BE, this flow is dramatically reduced. The reason is simple: to leave these regions, one has to be replaced by a teacher with higher priority/experience. As one would naturally expect, experienced teachers’ demand for these regions is relatively low, making it more difficult for teachers to leave these regions. While a decrease in the outgoing flow mechanically increases the number of experienced teachers in these regions, this phenomenon may have several negative features. In the first place, this may discourage experienced teachers from applying to these regions. Moreover, if newcomers are eventually trapped in such regions, the teaching profession may become less attractive and the overall quality of teachers may decrease. Overall, we sought to remain agnostic on how much the outgoing flow should be reduced in these regions. Hence, in our ongoing work, we tailor the current mechanism to ensure that the outgoing flow can be targeted by the decision maker. In particular, an option is to leave this flow unchanged compared to the current flow (achieved by DA*). Even under such a conservative approach, the overall mobility of initially assigned teachers can still be significantly increased, by 44.9%.

This study has clear policy implications for countries using a centralized assignment system. However, we would like to stress that it also helps to envision what would be the impact of a transition from a decentralized to a centralized assignment system in other countries. In particular, we show that adopting the modified version of DA, rather than one of the alternative mechanisms we suggest, would largely under-estimate the performance of a centralized system (for instance, in terms of teacher mobility).

References


Our conversation with agents from the Ministry of Education suggests that this is one of their most desired options.


Pereyra, Juan Sebastián, “A Dynamic School Choice Model,” *Games and economic behavior*, 2013, 80, 100–114.


Table 1: Welfare of teachers under different mechanisms

<table>
<thead>
<tr>
<th>Choice</th>
<th>Init</th>
<th>DA*</th>
<th>TO-BE</th>
<th>BE(Init)</th>
<th>BE(DA*)</th>
<th>1S-BE(Init)</th>
<th>1S-BE(DA*)</th>
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</thead>
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<tr>
<td>1</td>
<td>0</td>
<td>422.5</td>
<td>1163.0</td>
<td>1153.5</td>
<td>1169.9</td>
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<td>1347.8</td>
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<tr>
<td>2</td>
<td>7935</td>
<td>8084.2</td>
<td>8318.8</td>
<td>8287.2</td>
<td>8290.1</td>
<td>8386.1</td>
<td>8370.9</td>
</tr>
<tr>
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<td>9125</td>
<td>9220.5</td>
<td>9361.5</td>
<td>9336.1</td>
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</table>

Notes: This table presents the cumulative distribution of the number of teachers who obtain school rank \( k \) under their initial assignment in column 1, under DA* in column 2, TO-BE in column 3, BE(Init) in column 4, BE(DA*) in column 5, 1S-BE(Init) in column 6 and 1S-BE(DA*) in column 7. The data come from the assignment process of French teachers to regions in 2013.

Table 2: Stability of the matchings obtained with different mechanisms

<table>
<thead>
<tr>
<th>Nb regions</th>
<th>Init</th>
<th>DA*</th>
<th>TO-BE</th>
<th>BE(Init)</th>
<th>BE(DA*)</th>
<th>1S-BE(Init)</th>
<th>1S-BE(DA*)</th>
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<td>0</td>
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</table>

Notes: The upper part of this table presents the cumulative distribution of the number of teachers who obtain school rank \( k \) under their initial assignment in column 1, under DA* in column 2, TO-BE in column 3, BE(Init) in column 4, BE(DA*) in column 5, 1S-BE(Init) in column 6 and 1S-BE(DA*) in column 7. The data come from the assignment process of French teachers to regions in 2013. Column 1 reports the cumulative distribution of the number of regions with which teachers block under their initial assignment. The following columns report the cumulative distribution of the number of regions with which teachers block under DA*, TO-BE, BE(Init), BE(DA*), 1S-BE(Init) and 1S-BE(DA*).
Table 3: Welfare of regions under different mechanisms

<table>
<thead>
<tr>
<th>Net percentage of positions</th>
<th>DA*</th>
<th>TO-BE</th>
<th>BE(Init)</th>
<th>BE(DA*)</th>
<th>1S-BE(Init)</th>
<th>1S-BE(DA*)</th>
</tr>
</thead>
<tbody>
<tr>
<td>-100/-91%</td>
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<td>0</td>
<td>0</td>
<td>0.18</td>
<td>0.80</td>
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<tr>
<td>-90/-71%</td>
<td>0.18</td>
<td>0</td>
<td>0</td>
<td>0.18</td>
<td>1.06</td>
<td>0.93</td>
</tr>
<tr>
<td>-70/-51%</td>
<td>0.31</td>
<td>0</td>
<td>0</td>
<td>0.31</td>
<td>1.74</td>
<td>1.41</td>
</tr>
<tr>
<td>-50/-31%</td>
<td>0.57</td>
<td>0</td>
<td>0</td>
<td>0.50</td>
<td>3.19</td>
<td>2.57</td>
</tr>
<tr>
<td>-30/-1%</td>
<td>1.03</td>
<td>0</td>
<td>0</td>
<td>0.93</td>
<td>4.86</td>
<td>4</td>
</tr>
<tr>
<td>0%</td>
<td>84.32</td>
<td>72.01</td>
<td>71.18</td>
<td>70.90</td>
<td>72.67</td>
<td>71.81</td>
</tr>
<tr>
<td>1/29%</td>
<td>87.95</td>
<td>75.62</td>
<td>74.59</td>
<td>74.73</td>
<td>76.56</td>
<td>76.02</td>
</tr>
<tr>
<td>30/49%</td>
<td>91.05</td>
<td>79.11</td>
<td>78.02</td>
<td>77.66</td>
<td>80.01</td>
<td>79.14</td>
</tr>
<tr>
<td>50/69%</td>
<td>94.84</td>
<td>85.20</td>
<td>84.31</td>
<td>84.03</td>
<td>85.76</td>
<td>84.94</td>
</tr>
<tr>
<td>70/89%</td>
<td>97.40</td>
<td>90.32</td>
<td>89.70</td>
<td>89.04</td>
<td>89.63</td>
<td>88.82</td>
</tr>
<tr>
<td>90/100%</td>
<td>100</td>
<td>100</td>
<td>100</td>
<td>100</td>
<td>100</td>
<td>100</td>
</tr>
</tbody>
</table>

% of regions with no priority change  
83.22 72.01 71.18 69.83 67.05 67.12  
† Note: this table presents the cumulative percentage of regions having a net welfare improvement (relative to their initial assignment). For each of the 49 subjects*31 regions, we compute the number of positions being assigned a teacher with a higher priority, from which we subtract the number of positions being assigned a teacher with a lower priority. Then, for each subject*region, the net total is divided by the total number of positions to obtain the percentage of positions being improved in net terms. Finally, the total number of regions considered is divided by 49 × 31 to obtain the average percentages of regions. For instance, on average, under the DA*, 0.18% of the regions have between 91% and 100% of their seats assigned a teacher with a lower priority (in net terms).
In this section, we report a certain number of simulations. Our goal here is to argue that, in a realistic setting where a significant fraction of teachers are newcomers and where each school has a significant fraction of available seats, the effect identified in Example 1 can occur quite often. In order to do so, we consider the following environment. We have 600 teachers and
30 schools with 20 seats each; 300 teachers are newcomers, while the other half of teachers initially have an assignment. We assume that the total number of seats equals the total number of teachers so that half of the seats of each school are occupied and the other half are open seats.

We randomly draw the utility of teacher $t$ for school $s$ as follows:

$$U_t(s) = u_s + \xi_{st}$$

where $u_s$ is the common value of school $s$ drawn uniformly over the interval $[0, a]$ and $\xi_{st}$ is the idiosyncratic shock drawn uniformly over the interval $[0, 1]$. Parameter $a$ measures the degree of correlation in teachers’ preferences. For schools’ preferences, we have a similar specification:

$$V_s(t) = v_t + \eta_{st}.$$  

We assume that both common values ($v_t$) and idiosyncratic shocks ($\eta_{st}$) are drawn uniformly in $[0, 1]$.

Finally, given the dynamic nature of the teacher assignment process, teachers initially assigned good schools have a higher priority on average than teachers assigned poorer schools. In order to take this into account, we assume that the initial assignment is assortative: teachers with high common values are initially matched to schools with high common values. Formally, we assume that the 10 teachers $t$ having a common value $v_t$ within the 10 highest are matched to the school $s$ with the highest common value $u_s$. Similarly, the next 10 teachers having a common value within the next 10 highest are matched to the school with the second highest common value, and so on.

We draw teachers’ and schools’ preferences 50 times. For each draw, we compute the outcome of DA* and an outcome on the Pareto frontier, which Pareto-dominates DA*. The following table reports the number (averaged across iterations) of teachers staying at their initial assignment for both DA* and the Pareto-dominating matching for several possible values of the correlation parameter $a$.

In many instances, DA* can be improved both in terms of efficiency and stability, as in Example 1. The intuition is essentially the same: within top schools (i.e., for instance, the schools corresponding to the ten highest common values), open seats are filled very quickly by teachers initially matched to these top schools and partly by teachers initially matched to poorer schools. Hence, at some point, we return to the context of the example where teachers initially matched to good schools are willing to move to other good schools but cannot do so because of the large set of remaining tenured teachers – initially matched to poorer schools – among whom some teachers may have a higher priority at the schools they are targeting.

---

50More precisely, in order to find the Pareto-dominating outcome, we run TO-BE starting from the allocation given by DA*. See Section 4.1 for the definition of TO-BE.

51In our environment, teachers always prefer being matched to being unmatched. Given that the total number of seats equals the number of teachers, all teachers who are initially unmatched will end up being matched under DA* and therefore under the Pareto-dominating matching.
Table 4: Simulations results

<table>
<thead>
<tr>
<th>[0, a]</th>
<th>DA* init</th>
<th>Pareto-dominating matching</th>
</tr>
</thead>
<tbody>
<tr>
<td>[0, 0.1]</td>
<td>22.54</td>
<td>22.08</td>
</tr>
<tr>
<td>[0, 0.5]</td>
<td>54.5</td>
<td>43.08</td>
</tr>
<tr>
<td>[0, 0.15]</td>
<td>187.58</td>
<td>151.54</td>
</tr>
<tr>
<td>[0, 0.30]</td>
<td>186.46</td>
<td>165.86</td>
</tr>
<tr>
<td>[0, 0.60]</td>
<td>187.38</td>
<td>176.36</td>
</tr>
<tr>
<td>[0, 100]</td>
<td>189.22</td>
<td>180.6</td>
</tr>
<tr>
<td>[0, 1000]</td>
<td>190.2</td>
<td>189.2</td>
</tr>
</tbody>
</table>

The simulations reveal that the scope of the improvement can potentially be large depending on the precise value of the correlation parameter $a$ (it is maximized for intermediate values of the parameter).

C Proof of Theorem 3

We want to prove the following proposition.

**Proposition 6** Let $\varphi$ be any selection of BE. If $\varphi \neq$ TO-BE then $\varphi$ is not strategy-proof.

**Lemma 3** Let $\varphi$ be any selection of BE. Fix any profile of preferences $\succ$ and assume that $\varphi(\succ) \neq$ TO-BE($\succ$). Let $x$ be the outcome of TO-BE($\succ$) and let $y$ be that of $\varphi(\succ)$. There exists $t$ s.t. $x(t) \succ_t y(t) \succ_t \mu_0(t)$.

**Proof.** Let $T(x, y)$ be the set of teachers for which $x(t) \succ_t y(t) \succeq_t \mu_0(t)$. We know that $x$ is not 1-Pareto dominated by $y$ (by Proposition 5), and since $y$ is individually rational and $x \neq y$, we must have $T(x, y) \neq \emptyset$. Proceed by contradiction and assume that, for all $t \in T(x, y)$, we have $y(t) = \mu_0(t)$. Let $B := T \setminus T(x, y)$. Note that for any $t \in B$, $y(t)$ is a school initially assigned to some teacher in $B$. In addition, by definition, for all $t \in B$, $y(t) \succeq_t x(t)$. If there was no teacher $t \in B$ for which $y(t) \succ_t x(t)$, then we would have the following situation: $y$ would select the initial allocation for all $t \in T(x, y)$ and would be identical to $x$ for all $t \notin T(x, y)$. Given that $x \neq y$, we must have $x(t) \neq y(t) = \mu_0(t)$ for some $t \in T(x, y)$. Since $x$ is individually rational, we have $x(t) \succ_t y(t) = \mu_0(t)$ for those $t \in T(x, y)$. Hence $x$ 1-Pareto-dominates $y$. However, all schools are also better off under $x$ than under $y$. Indeed, for each school $s$ s.t. $y(s) \notin T(x, y)$, $y(s) = x(s)$ and for each school $s$ s.t. $y(s) \in T(x, y)$, because $x$ is individually rational on both sides, $x(s) \succeq_s y(s) = \mu_0(s)$ with a strict inequality for $s$ satisfying $x(s) \neq y(s)$ (and this $s$ must exist since $x \neq y$). Thus, $x$ is individually rational on both sides and 2-Pareto-dominates $y$, which is not possible, given that $y$ is an outcome of BE.
To recap, we have that, for any \( t \in B \), \( y(t) \) is a school initially assigned to some teacher in \( B \) and for all \( t \in B \), \( y(t) \succeq_t x(t) \) with a strict inequality for some \( t \in B \). In addition, since \( y \) is the outcome of \( \varphi(\succ) \) and \( \varphi \) 2-Pareto-dominates the initial allocation \( \mu_0 \), we must have that, for all schools \( s \), \( y(s) \preceq_s \mu_0(s) \). Hence, \( B \) is a two-sided blocking coalition for \( x \), which is a contradiction since \( x \) must be a point in the two–sided Core.

**Proof of Proposition 6.** We start from a profile of preferences \( \succ \) under which \( \varphi(\succ) \neq \text{TO-BE}(\succ) \) which must exist because of our assumption that \( \varphi \neq \text{TO-BE} \). Given our profile of preferences \( \succ \), we let the profile of preferences \( \succ' \) be defined as follows. For any \( t \), any school \( s \) other than \( \text{TO-BE}(\succ)[t] \) are ranked as unacceptable for \( t \) under \( \succ' \). We must have \( \text{TO-BE}(\succ) = \text{TO-BE}(\succ') \). Now, we are in a position to prove the following lemma.

**Lemma 4** \( \text{TO-BE}(\succ') = \varphi(\succ') \).

**Proof.** Suppose \( x := \text{TO-BE}(\succ') \neq \varphi(\succ') =: y \). By the above lemma, there exists \( t \) s.t. \( x(t) \succ'_t y(t) \succ'_t \mu_0(t) \), which yields a contradiction, by construction of \( \succ'_t \).

Note that TO-BE also satisfies the following property: for any profile of preferences \( \succ \), for any teacher \( t \), \( \text{TO-BE}(\succ)(t) = \text{TO-BE}(\succ_{-t}, \succ'_t)(t) \). This will be used in the following lemma.

**Lemma 5** If \( \varphi \) is strategy-proof, then \( \text{TO-BE}(\succ_Z, \succ'_Z) = \varphi(\succ_Z, \succ'_Z) \) for any \( Z \subseteq T \).

**Proof.** Assume \( \varphi \) is strategy-proof. The proof is by induction on the size of \( Z \). For \( |Z| = 0 \), the result is given by the previous lemma. Now, the induction hypothesis is that \( \text{TO-BE}(\succ_Z, \succ'_Z) = \varphi(\succ_Z, \succ'_Z) \) for any subset \( Z \) with \( |Z| = k \). Proceed by contradiction and suppose that there is \( Z \) s.t. \( |Z| = k + 1 \) for which \( x := \text{TO-BE}(\succ_Z, \succ'_Z) \neq \varphi(\succ_Z, \succ'_Z) =: y \). By the first lemma above, there exists \( t \) s.t. \( \text{TO-BE}(\succ_Z, \succ'_Z)(t) \succ_t \varphi(\succ_Z, \succ'_Z)(t) \succ_t \mu_0(t) \) where \( \succ_t = \succ'_t \) if \( t \notin Z \) while \( \succ_t = \succ_t \) otherwise. If \( t \notin Z \), then there is a straightforward contradiction since, under \( \succ'_t \), there is a single school which is ranked above \( \mu_0(t) \) for teacher \( t \). Now, assume that \( t \in Z \). By the property noticed just before the statement of the lemma, we must have \( \text{TO-BE}(\succ_{Z \setminus \{t\}}, \succ'_{Z \setminus \{t\}})(t) = \text{TO-BE}(\succ_Z, \succ'_Z)(t) \) and, by our induction hypothesis, \( \varphi(\succ_{Z \setminus \{t\}}, \succ'_Z, \succ'_t)(t) = \text{TO-BE}(\succ_{Z \setminus \{t\}}, \succ'_Z, \succ'_t)(t) \). Thus, we obtain \( \varphi(\succ_{Z \setminus \{t\}}, \succ'_Z, \succ'_t)(t) = \text{TO-BE}(\succ_{Z \setminus \{t\}}, \succ'_Z, \succ'_t)(t) = \text{TO-BE}(\succ_Z, \succ'_Z)(t) \succ_t \varphi(\succ_Z, \succ'_Z)(t) \), which is a contradiction with the assumption that \( \varphi \) is strategy-proof (indeed, at \( (\succ_Z, \succ'_Z) \), teacher \( t \in Z \) has an incentive to report \( \succ'_t \) instead of \( \succ_t \)).

Taking \( Z = T \) in the above lemma, given that \( \varphi(\succ) \neq \text{TO-BE}(\succ) \), we obtain the following corollary, which completes the proof of our proposition.

**Corollary 2** \( \varphi \) is not strategy-proof.
D Proof of Theorem 4

In the sequel, we prove our characterization result of one-sided maximal matchings given in Theorem 4. Our proof is divided into two parts. We start by showing that any outcome of the 1S-BE algorithm is a one-sided maximal matching (Section D.1):

Proposition 7 If $\mu$ is an outcome of the 1S-BE algorithm, then $\mu$ is one-sided maximal.

Then, we move to the proof that any one-sided maximal matching corresponds to a possible outcome of the 1S-BE algorithm (Section D.2):

Proposition 8 If $\mu$ is one-sided maximal, then $\mu$ is an outcome of the 1S-BE algorithm.

D.1 Proof of Proposition 7

Before moving to the proof, we introduce a new notation. Given matching $\mu$, we denote $B_\mu$ for the set of blocking pairs of $\mu$.

In the sequel, we fix two matchings $\mu$ and $\mu'$ such that $\mu'$ Pareto-dominates $\mu$ for teachers and $B_{\mu'} \subseteq B_\mu$. We show below that, starting from $\mu$, the graph associated to the 1S-BE algorithm must have a cycle. Hence, any outcome of 1S-BE must be one-sided maximal, as claimed in Proposition 7.

To provide the intuition of each step of the proof, which uses many graphical arguments, we will use an example to illustrate each part. This example involves 6 teachers, $t_1, t_2, t_3, t_4, t_5, t_6$ and 6 schools $s_1, s_2, s_3, s_4, s_5, s_6$. In the example, matchings $\mu$ and $\mu'$ are as follows:

$$
\mu = \left(\begin{array}{cccccc}
t_1 & t_2 & t_3 & t_4 & t_5 & t_6 \\
s_1 & s_2 & s_3 & s_4 & s_5 & s_6 \\
\end{array}\right)
$$

$$
\mu' = \left(\begin{array}{cccccc}
t_1 & t_2 & t_3 & t_4 & t_5 & t_6 \\
s_2 & s_3 & s_4 & s_5 & s_6 & s_1 \\
\end{array}\right)
$$

As in Lemma 1, we can exhibit cycles of exchanges that can be used to go from $\mu$ to $\mu'$ in the proposition.

In Lemma 1, these cycles of exchanges were actual cycles in the graph associated with BE. However, when considering the graph associated with 1S-BE, this is no longer the case: the cycles of exchanges are not necessarily cycles of the graph associated with 1S-BE. Before moving to the first lemma, we note that all the nodes that are not part of cycles of exchanges are those where the teacher of that node has the same allocation between $\mu$ and $\mu'$. In the following the nodes of the cycles of exchanges will be all the nodes $(t, s)$ s.t $\mu(t) \neq \mu'(t)$. We will say that a node $(t, s)$ 1S-BE-points to another node $(t', s')$ if $(t, s)$ points toward $(t', s')$ in the graph associated with the 1S-BE algorithm (starting from $\mu$).
Lemma 6 Fix a node \((t, s)\) of the cycles of exchanges. Then:

1. either its predecessor according to the cycles of exchanges 1S-BE-points toward \((t, s)\);
2. or there is a node \((t', s')\) in the cycles of exchanges such that \(t'\) does not block with \(s\) under \(\mu\), \(s \succ_{t'} s'\) and \(t'\) has the highest priority among those who desire \(s\) but do not block with it under \(\mu\). Therefore, \((t', s')\) 1S-BE-points toward \((t, s)\).

Before moving to the proof, let us illustrate this lemma in the example. Assume that all the nodes except \((t_3, s_3)\) are 1S-BE-pointed by their predecessors in the cycle of exchanges. According to Lemma 6, there must be a node \((t', s')\) in the cycle of exchanges that 1S-BE-points toward \((t_3, s_3)\). In the graph of Figure 1, this node is assumed to be \((t_5, s_5)\). The dashed edge from \((t_2, s_2)\) to \((t_3, s_3)\) shows that this is not an edge of the 1S-BE graph but only an edge corresponding to the cycle of exchanges.

Proof. Call \((t'', s'')\) the predecessor of node \((t, s)\) in the cycles of exchanges so that \(s'' := \mu(t'')\) and \(s := \mu'(t'')\). Because \(\mu'\) Pareto-dominates \(\mu\) for teachers, we know that \(s \succ_{t''} s''\) so that \(t''\) desires \(s\) under \(\mu\). Assume that \((t'', s'')\) does not 1S-BE-point to \((t, s)\). This means that \(t''\) does not block with \(s\) under \(\mu\) and that there is another teacher \(t'\) who does not block with \(s\) and has the highest priority among those who desire \(s\) and do not block with it. Thus, \((t', s')\) (where \(s' := \mu(t')\)) 1S-BE points toward \((t, s)\). It remains to show that \((t', s')\) is part of the cycles of exchanges. If this were not the case, it would mean that \(\mu(t') = \mu'(t') = s'\). Let us recap. We have that \(t'\) does not block with \(s\) under \(\mu\). In addition, by definition of \(t'\), we must have that \(t' \succ_{s} t''\) (since \(t''\) does not block with \(s\) under \(\mu\) and desires \(s\)). In addition, \(t'\) desires \(s\) under \(\mu\) and so \(\mu(t') = \mu'(t')\) implies that \(t'\) also desires \(s\) under \(\mu'\). Hence, because \(t'' \in \mu'(s)\), we obtain that \(t'\) blocks with \(s\) under \(\mu'\). This contradicts our assumption that \(B_{\mu'} = B_{\mu}\). 

Lemma 6 allows us to identify a subgraph \((N', E')\) of the 1S-BE graph starting from \(\mu\) such that \(N'\) are the nodes of the cycles of exchanges and the set of edges \(E'\) is built as follows. We start from \(E' = \emptyset\) and add the following edges: for each node \((t, s)\) in the cycles of exchange, if its predecessor \((\tilde{t}, \tilde{s})\) under the cycles of exchanges 1S-BE-points to \((t, s)\) then \(((\tilde{t}, \tilde{s}), (t, s))\) is added to \(E'\). If, on the contrary, \((\tilde{t}, \tilde{s})\) does not 1S-BE-point to \((t, s)\), then we pick the node \((t', s')\) in the cycles of exchanges identified in the second condition of Lemma 6, which 1S-BE-points toward \((t, s)\), and we add \(((t', s'), (t, s))\) to \(E'\). Note that, by construction, each node in \(N'\) has a unique in-going edge in \((N', E')\). In the example, this subgraph \((N', E')\) is given by the right graph in Figure 1 (the solid arrows). Note that this graph admits a cycle: \((t_3, s_3) \rightarrow (t_4, s_4) \rightarrow (t_5, s_5) \rightarrow (t_3, s_3)\). This is a simple property of digraphs with in-degree one:

Lemma 7 Fix a finite digraph \((N, E)\) such that each node has in-degree one. There exists a cycle in this graph.
**Proof**. Fix a node \( n_1 \) in the graph \((N,E)\). Because it has in-degree one, we can let \( n_2 \) be the unique node pointing to \( n_1 \). Again, from \( n_2 \), we can let \( n_3 \) be the unique node pointing to \( n_2 \). Because there is a finite number of nodes in the graph, this process must cycle at some point. \( \blacksquare \)

As the example illustrates, applying this lemma to \((N',E')\) leads to the following corollary:

**Corollary 3** There is a cycle in the subgraph \((N',E')\).

We are now in a position to prove Proposition 7.

**Completion of the proof of Proposition 7.** Let \( \mu \) be an outcome of the 1S-BE algorithm. Proceed by contradiction and assume that \( \mu \) is not one-sided maximal. Thus, there must exist a matching \( \mu' \) such that \( \mu' \) Pareto-dominates \( \mu \) for teachers and \( B_{\mu'} \subseteq B_{\mu} \). Corollary 3 implies that there must be a cycle in the graph associated with 1S-BE starting from \( \mu \), contradicting the fact that \( \mu \) is an outcome of 1S-BE. \( \blacksquare \)

**Figure 1:** Cycles of exchanges and \((N',E')\).

a) Cycle of exchanges

\[
\begin{align*}
(t_1, s_1) & \quad \rightarrow \quad (t_2, s_2) \\
(t_6, s_6) & \quad \rightarrow \quad (t_3, s_3) \\
(t_5, s_5) & \quad \rightarrow \quad (t_4, s_4) \\
\end{align*}
\]

b) \((N',E')\)

\[
\begin{align*}
(t_1, s_1) & \quad \rightarrow \quad (t_2, s_2) \\
(t_6, s_6) & \quad \rightarrow \quad (t_3, s_3) \\
(t_5, s_5) & \quad \rightarrow \quad (t_4, s_4) \\
\end{align*}
\]

**D.2 Proof of Proposition 8**

In the sequel, we fix a one-sided maximal matching \( \mu' \). We let \( \mu \) be a matching such that \( \mu' \) Pareto-dominates for teachers \( \mu \) and satisfies \( B_{\mu'} \subseteq B_{\mu} \). We claim that there is a cycle in the graph associated with 1S-BE starting from \( \mu \) which, once implemented, leads to a matching \( \tilde{\mu} \) such that \( \mu' \) Pareto-dominates \( \tilde{\mu} \) for teachers and satisfies \( B_{\mu'} \subseteq B_{\tilde{\mu}} \). Note that this implies Proposition 8. Indeed, because, by definition, \( \mu' \) Pareto-dominates \( \mu_0 \) and \( B_{\mu'} \subseteq B_{\mu_0} \),
we must have a cycle in the graph associated with 1S-BE starting from \( \mu_0 \), which, once implemented, yields to a matching say \( \tilde{\mu}_1 \) such that \( \mu' \) Pareto-dominates \( \tilde{\mu}_1 \) for teachers and satisfies \( B_{\mu'} \subseteq B_{\tilde{\mu}_1} \). Now, we can iterate the reasoning, and we again obtain that there is a cycle in the graph associated with 1S-BE starting from \( \tilde{\mu}_1 \), which, once implemented, yields to a matching say \( \tilde{\mu}_2 \) such that \( \mu' \) Pareto-dominates \( \tilde{\mu}_2 \) for teachers and satisfies \( B_{\mu'} \subseteq B_{\tilde{\mu}_2} \). We can pursue this reasoning. At some point, because the environment is finite, we must reach matching \( \mu' \).

In the sequel, as in the proof of Proposition 7, we consider the digraph \((N', E')\) as built in Section D after Lemma 6. Consider a cycle \( \tilde{C} \) in this graph (which exists by Lemma 7). Let \( \tilde{\mu} \) be the matching obtained once the cycle \( \tilde{C} \) is implemented. In the example introduced in Section D, this matching would be

\[
\mu_1 = \begin{pmatrix}
t_1 & t_2 & t_3 & t_4 & t_5 & t_6 \\
s_1 & s_2 & s_4 & s_5 & s_3 & s_6
\end{pmatrix}
\]

We first show the following lemma:

**Lemma 8** \( \mu' \) Pareto-dominates \( \tilde{\mu} \) for teachers.

**Proof.** Fix a teacher \( t \). If the node \((t, s)\) to which \( t \) belongs is not part of the cycles of exchanges, we know that \( t \) does not move from \( \mu \) to \( \mu' \) and so \((t, s)\) is not in the cycle \( \tilde{C} \). Hence, \( \mu(t) = \tilde{\mu}(t) = \mu'(t) \). Therefore, assume that \((t, s)\) is part of the cycles of exchanges and let \( s := \mu(t) \) and \( s' := \mu'(t) \) with \( s \neq s' \). There are three possible cases:

- **Case 1:** \( s = \tilde{\mu}(t) \neq s' \). Because \( \mu' \) Pareto-dominates \( \mu \) for teachers, we have that \( \mu'(t) = s' \succeq_t \tilde{\mu}(t) = \mu(t) = s \).
- **Case 2:** \( s \neq \tilde{\mu}(t) = s' \). In such a case, we trivially have \( \mu'(t) \succeq_t \tilde{\mu}(t) \).
- **Case 3:** \( s \neq \tilde{\mu}(t) := s_1 \neq s' \). By construction of the graph \((N', E')\), when we implement cycle \( \tilde{C} \), we know that there is a unique edge \((t, s), (t_1, s_1)\) in \( \tilde{C} \) and that \((t, s)\) is not the predecessor of \((t_1, s_1)\) under the cycles of exchanges, since otherwise, \( t \) would be matched to \( s' \) under \( \tilde{\mu} \), which is not the case by assumption. Hence, by construction of \((N', E')\), the predecessor of \((t_1, s_1)\) under the cycles of exchanges, say \((t'', s'')\), does not 1S-BE point to \((t_1, s_1)\). In addition, \( t \) does not block with \( s_1 \) under \( \mu \), \( s_1 \succ_t s \); \( t \) has the highest priority among those who desire \( s_1 \) but do not block with it under \( \mu \); and 1S-BE-points to \((t_1, s_1)\). Because \((t'', s'')\) does not 1S-BE point to \((t_1, s_1)\), we know that \( t'' \) does not block with \( s_1 \). Because \((t'', s'')\) points to \((t_1, s_1)\) under the cycles of exchange, we must have that \( t'' \) desires \( s_1 \). Thus, we conclude that \( t \succ_{s_1} t'' \).

Now, proceed by contradiction and assume that \( (\tilde{\mu}(t) =) s_1 \succ_t s' (= \mu'(t)) \). Because \( t'' \in \mu'(s_1) \) (recall that \((t'', s'')\) is the predecessor of \((t_1, s_1)\) under the cycles of exchange)
and $t \succ_s t''$, we have that $t$ blocks with $s_1$ under $\mu'$, i.e., $(t, s_1) \in B_{\mu'}$. But, as already claimed, $(t, s_1) \notin B_{\mu}$. This contradicts $B_{\mu'} \subseteq B_{\mu}$. Thus, we must have $\mu'(t) \succeq_t \bar{\mu}(t)$.\(^{52}\)

We have shown that $\forall t$, $\mu'(t) \succeq_t \bar{\mu}(t)$. \(\blacksquare\)

The following lemma completes the argument.\(^{53}\)

**Lemma 9** We have that $B_{\mu'} \subseteq B_{\bar{\mu}}$.

**Proof.** The proof proceeds by contradiction. Assume that there is a teacher $t$ and a school $s$ s.t. $(t, s) \in B_{\mu'}$ but $(t, s) \notin B_{\bar{\mu}}$. Note first that teacher $t$ desires $s$ under $\bar{\mu}$ because $s \succ_t \mu'(t)$ (by $(t, s) \in B_{\mu'}$) and $\mu'(t) \succeq_t \bar{\mu}(t)$ (by Lemma 8). Therefore, because $(t, s) \notin B_{\bar{\mu}}$, we must have that $\bar{t} \succ_s t$ for $\bar{t} := \bar{\mu}(s)$. Since $(t, s) \in B_{\mu'} \subseteq B_{\mu}$, we know that $t$ blocks with $s$ under $\mu$ and therefore, since we are in a one-to-one setting, $\mu(\bar{t}) \neq s$. This implies that $(\bar{t}, \mu(\bar{t}))$ is part of cycle $\bar{C}$. Since $(t, s) \in B_{\mu'}$, we also know that $\mu'(\bar{t}) \neq s$. Therefore, to recap, we have that $\mu(\bar{t}) \neq \bar{\mu}(\bar{t}) \neq \mu'(\bar{t})$. However, this means that, in the graph $(N', E')$, $(\bar{t}, \mu(\bar{t}))$ points to $(s, \mu(s))$, while $(\bar{t}, \mu'(\bar{t}))$ is not the predecessor of $(s, \mu(s))$ in the graph of exchanges. By construction of $(N', E')$, this means that $\bar{t}$ does not block with $s$ under $\mu$ and has the highest priority among teachers who desire $s$ under $\mu$ and do not block with it under $\mu$. In particular, because $\bar{t}$ does not block with $s$ under $\mu$ (but desires it under $\mu$), we must have $\mu(s) \succ_s \bar{t}$. In addition, since $(t, s) \in B_{\mu}$, we must have $t \succ_s \mu(s) \succ_s \bar{t}$, contradicting that $\bar{t} \succ_s t$. \(\blacksquare\)

### E Proof of Theorem 5

In order to prove this result, we exhibit an instance where, irrespective of which (sequence of) cycle(s) one selects in the graphs associated with 1S-BE, one teacher will gain by misreporting his preferences. Assume that there are five teachers $t_1, \ldots, t_5$ and five schools $s_1, \ldots, s_5$. Teachers’ and schools’ preferences are given as follows:

- $t_1 \succ s_5, s_1$  \(\succ s_1: t_5, t_2, t_1\)
- $t_2 \succ s_1, s_3, s_2$  \(\succ s_2: t_5, t_2\)
- $t_3 \succ s_4, s_5, s_3$  \(\succ s_3: t_3, t_2, t_4\)
- $t_4 \succ s_5, s_3, s_4$  \(\succ s_4: t_3, t_4\)
- $t_5 \succ s_2, s_1, s_5$  \(\succ s_5: t_4, t_2, t_5, t_3, t_1\)

\(^{52}\)Case 3 in Lemma 8 can be illustrated in the example. The node $(t, s)$ would be $(t_5, s_5)$ in the right graph of Figure 1. $t_5$ is matched to $s_3$ under $\mu$ but is matched to $s_6$ under $\mu'$. Under $\bar{C}$ (i.e., $(t_3, s_3) \rightarrow (t_4, s_4) \rightarrow (t_5, s_5) \rightarrow (t_3, s_3)$), node $(t_5, s_5)$ points to $(t_3, s_3)$, while $(t_2, s_2)$ does not 1S-BE-point to $(t_3, s_3)$. Because $(t_2, s_2)$ points to $(t_3, s_3)$ in the cycle of exchanges, it means that $t_2 \in \mu'(s_3)$ so that, if $t_5$ preferred $s_3$ to his match under $\mu'$, $s_2$, it would imply that $t_5$ blocks with $s_3$ under $\mu'$, while he does not under $\mu$; this would yield the contradiction.

\(^{53}\)Note that, to this point, all the arguments we provided can be applied to the many-to-one environment. However, the following lemma explicitly uses the one-to-one environment and is no longer true for many-to-one. However, we can use additional arguments to show that Proposition 8 holds in the many-to-one setting. This is provided in Section S.1 of the supplementary material.
We let $\succ := (\succ_{t_1}, \ldots, \succ_{t_5})$. The initial assignment is given by:

$$
\mu_0 = \begin{pmatrix} t_1 & t_2 & t_3 & t_4 & t_5 \\ s_1 & s_2 & s_3 & s_4 & s_5 \end{pmatrix}
$$

Starting from the initial assignment, the solid arrows in the graph below correspond to the graph associated with 1S-BE.

We added dashed arrows from one node to another if the teacher in the origin of the arrow prefers the school in the pointed node. These arrows are not actual arrows of the graph associated with 1S-BE and therefore cannot be used to select a cycle. These arrows only facilitate the understanding of the argument.

When $\succ$ is submitted, there are two possible choices of cycles in the graph:

- A large cycle given by $(t_2, s_2) \rightarrow (t_3, s_3) \rightarrow (t_4, s_4) \rightarrow (t_5, s_5) \rightarrow (t_2, s_2)$. Denote this cycle by $\bar{C}$.
- A small cycle given by $(t_2, s_2) \rightarrow (t_3, s_3) \rightarrow (t_5, s_5) \rightarrow (t_2, s_2)$. Denote this cycle by $C$.

We decompose the analysis for these two cases.

**Case A: Under $\succ$, $\bar{C}$ is selected:**

Once this cycle is cleared, there are no cycles left in the graph associated with 1S-BE, and the final matching of 1S-BE is given by

$$
\bar{\mu} = \begin{pmatrix} t_1 & t_2 & t_3 & t_4 & t_5 \\ s_1 & s_3 & s_4 & s_5 & s_2 \end{pmatrix}
$$

Now, assume that teacher $t_2$ reports the following preference relation $\succ'_{t_2}$: $s_1, s_5, s_2$, while others report according to $\succ$. Under this profile, starting from the initial assignment, the graph associated with 1S-BE is
Now, there are two possible choices of cycles.

Case A.1: The cycle chosen is \((t_2, s_2) \rightleftharpoons (t_5, s_5)\). Once carried out, the graph associated with 1S-BE starting from the new matching is

Clearly, there is a unique cycle \((t_4, s_4) \rightleftharpoons (t_3, s_3)\). Consider the new matching once this cycle is implemented. Teacher \(t_3\) obtains his most favorite school. Hence, in the graph associated with 1S-BE starting from the new matching, node \((t_1, s_1)\) will now point to node \((t_2, s_5)\). In this graph, the only cycle is \((t_2, s_5) \rightleftharpoons (t_1, s_1)\); therefore, \(t_2\) is eventually matched to school \(s_1\). Hence, \(t_2\) obtains his most preferred school under \(\succ_{t_2}\) and we exhibited a profitable misreport.

Case A.2: The cycle chosen is \((t_4, s_4) \rightleftharpoons (t_3, s_3)\). Once carried out, the graph associated with 1S-BE starting from the new matching is
In this graph, there are three possible choices of cycles:

1. \((t_2, s_2) \rightarrow (t_1, s_1) \rightarrow (t_5, s_5) \rightarrow (t_2, s_2)\): in that case, \(t_2\) is matched to \(s_1\) and so, again, we identified a profitable misreport.

2. \((t_2, s_2) \iff (t_5, s_5)\): Once cleared, the only cycle that is left is \((t_1, s_1) \iff (t_2, s_5)\); therefore, \(t_2\) will be matched to \(s_1\), leading to a successful manipulation.

3. \((t_1, s_1) \iff (t_5, s_5)\): Once cleared, since \(t_5\) prefers \(s_2\) to \(s_1\), there is a unique cycle left: \((t_5, s_1) \iff (t_2, s_2)\). Once again, the manipulation of \(t_2\) is successful.

Thus, we have shown that, when cycle \(\overline{C}\) is selected under the profile \(\succ\), teacher \(t_2\) has a profitable misreport irrespective of the possible selections of cycles performed after \(t_2\)'s deviation. Let us now move to the other case.

**Case B: Under \(\succ\), \(C\) is selected:**

Once this cycle is carried out, the graph associated with 1S-BE starting from the new matching is
There are two possible choices of cycles.

**Case B.1:** \((t_3, s_5) \leftrightarrow (t_4, s_4)\) is chosen. Then, the matching obtained is the same as the one obtained when we selected cycle \(\overline{C}\). Therefore, we can come back to **Case A**, and we know that \(t_2\) has a successful misreport.

**Case B.2:** \((t_1, s_1) \to (t_3, s_5) \to (t_4, s_4) \to (t_2, s_3) \to (t_1, s_1)\) is chosen. In that case, each teacher but teacher \(t_4\) gets his most preferred school. Hence, there are no more cycles in the new graph associated with 1S-BE. In particular, teacher \(t_4\) is matched to school \(s_3\). Now, assume that \(t_4\) submits the following preferences: \(\succ'_t s_5, s_4\). The graph associated with 1S-BE starting from the initial assignment is the same as the one under truthful reports (note that, although these are not the arrows of the graph of 1S-BE, the dashed arrow from \((t_4, s_4)\) disappears). Therefore, again, we are left with a choice between cycle \(\overline{C}\) and \(C\).

1. If we carry out \(C\), the graph starting from the new matching will be given by the graph just above, except that \((t_4, s_4)\) no longer points to \((t_2, s_3)\). Hence, we can pick only cycle \((t_3, s_5) \leftrightarrow (t_4, s_4)\); therefore, \(t_4\) obtains his best school and we identified a profitable misreport for teacher \(t_4\).

2. If we select \(\overline{C}\), we already know that we end up with matching \(\overline{\mu}\), as defined above. Therefore, here again, \(t_4\) obtains his best school \(s_5\) and the manipulation is also a success.

To sum up, we have shown that, for each possible selection of cycles under 1S-BE, there is a teacher who has a profitable misreport. Thus, no selection of the 1S-BE algorithm is strategy-proof, as was to be shown.

**F Proof of Theorem 7 and 8**

**F.1 Preliminaries in random graph**

In the sequel, we will exploit two standard results in random graph theory that are stated in this section. It is thus worth introducing the relevant model of random graph. A **graph** \(G(n)\) consists of \(n\) vertices, \(V\), and edges \(E \subseteq V \times V\) across \(V\). A **bipartite graph** \(G_b(n)\) consists of \(2n\) vertices \(V_1 \cup V_2\) (each of equal size) and edges \(E \subset V_1 \times V_2\) across \(V_1\) and \(V_2\) (with no possible edges within vertices in each side). Random (bipartite) graphs can be seen as random variables over the space of (bipartite) graphs. We will see two asymptotic properties of random graphs: one based on the notion of perfect matchings, the other on that of independent sets.

A **perfect matching** of \(G_b(n)\) is a subset \(E'\) of \(E\) such that each node in \(V_1 \cup V_2\) is contained in a single edge of \(E'\).
Lemma 10 (Erdős-Rényi) Fix \( p \in (0, 1) \). Consider a random graph which selects a graph \( G_0(n) \) with the following procedure. Each pair \((v_1, v_2) \in V_1 \times V_2\) is linked by an edge with probability \( p \) independently (of edges created for all other pairs). The probability that there is a perfect matching in a realization of this random graph tends to 1 as \( n \to \infty \).

The second important technical result is about so-called independent sets. An independent set of \( G(n) \) is \( \bar{V} \subseteq V \) such that for any \((v_1, v_2) \in V \times V\), \((v_1, v_2)\) is not in \( E \).

Lemma 11 (Grimmett and McDiarmid (1975)) Fix \( p \in (0, 1) \). Consider a random graph that selects a graph \( G(n) \) with the following procedure. Each pair \((v_1, v_2) \in V \times V\) is linked by an edge with probability \( p \) independently (of edges created for all other pairs). Then,

\[
\Pr \left\{ \exists \text{ an independent set } \bar{V} \text{ such that } |\bar{V}| \geq \frac{2 \log n}{\log \frac{1}{1-p}} \right\} \to 0 \text{ as } n \to \infty.
\]

### F.2 Proof of Theorem 7

In the sequel, we fix \( \mu_0 \) and let \( T_k = \mu_0(S_k) \), where \( \mu_0 \) is the initial allocation. We will prove the following result, which implies the first part of Theorem 7.

Proposition 9 Consider any selection \( \varphi \) of the BE-algorithm. Fix any \( k \). Let \( T_k := \{ t \in T_k | \varphi(t) \neq \mu_0(t) \} \). We have

\[
\frac{|T_k|}{|T_k|} \to 1.
\]

**Proof of Proposition 9.** Fix an arbitrary \( k \) and fix \( \varepsilon > 0 \). We define a random graph with \( \{(t, \mu_0(t))\}_{t \in T_k} \) as the set of vertices. An edge between \((t, \mu_0(t))\) and \((t', \mu_0(t'))\) is added if and only if \( \xi_{t\mu_0(t)}(\varepsilon) > 1 - \varepsilon \) and \( \xi_{t'\mu_0(t)}(\varepsilon) > 1 - \varepsilon \) and \( \eta_{t\mu_0(t)}(\varepsilon') > 1 - \varepsilon \) and \( \eta_{t'\mu_0(t)}(\varepsilon') > 1 - \varepsilon \). Then, in the random graph, each edge between \((t, \mu_0(t))\) and \((t', \mu_0(t'))\) is added independently with probability \( \varepsilon^4 \in (0, 1) \). Then, let \( \tilde{T}_k := \{ t \in T_k | \varphi(t) = \mu_0(t) \text{ and } U_t(\mu_0(t)) \leq u_k + 1 - \varepsilon \text{ and } V_{\mu_0(t)}(t) \leq 1 - \varepsilon \} \). It must be that \( \{(t, \mu_0(t))\}_{t \in \tilde{T}_k} \) is an independent set, or else if there is an edge \((t, \mu_0(t)), (t', \mu_0(t'))\) where \( t, t' \in \tilde{T}_k \) for some realization of the random graph, then

\[
U_t(\mu_0(t')) > u_k + 1 - \varepsilon \geq U_t(\mu_0(t)) = U_t(\varphi(t)) \text{ and } V_{\mu_0(t')}(t') > 1 - \varepsilon \geq V_{\mu_0(t)}(t') = V_{\mu_0(t')}(\varphi(\mu_0(t')))
\]

and similarly,

\[
U_t'(\mu_0(t)) > u_k + 1 - \varepsilon \geq U_t'(\mu_0(t')) = U_t'(\varphi(t')) \text{ and } V_{\mu_0(t)}(t') > 1 - \varepsilon \geq V_{\mu_0(t)}(t) = V_{\mu_0(t)}(\varphi(\mu_0(t))).
\]

Put another way, both \((t, \mu_0(t'))\) and \((t', \mu_0(t))\) block \( \varphi \). Since, by definition, under \( \varphi \), \( t \) is assigned \( \mu_0(t) \) and \( t' \) is assigned \( \mu_0(t') \), there are still cycles in the graph associated with BE.
when starting from the assignment given by $\varphi$, which contradicts the fact that $\varphi$ is a selection of BE.

Now, we can use Lemma 11 to obtain that $\Pr\left\{ |\tilde{T}_k| \geq \frac{2\log(|T_k|)}{\log \frac{1}{1-p}} \right\} \rightarrow 0$ as $n \rightarrow \infty$ and thus, $\frac{|\tilde{T}_k|}{|T_k|} \rightarrow 0$ as $n \rightarrow \infty$. Setting $\tilde{T}_k := \{ t \in T_k \mid U_t(\mu_0(t)) \leq u_k + 1 - \varepsilon \}$ and $V_{\mu_0(t)}(t) \leq 1 - \varepsilon \}$, we have

$$\frac{|\tilde{T}_k|}{|T_k|} = \frac{|\tilde{T}_k \cap \tilde{T}_k|}{|T_k|} = \frac{|\tilde{T}_k \setminus \tilde{T}_k|}{|T_k|} \geq \frac{|\tilde{T}_k|}{|T_k|} - \frac{|\tilde{T}_k|}{|T_k|}.$$ 

We know that, for the left hand-side above, $\frac{|\tilde{T}_k|}{|T_k|} \rightarrow 0$ as $n \rightarrow \infty$. By the law of large numbers, $\frac{|\tilde{T}_k|}{|T_k|} \rightarrow 1 - (1 - \varepsilon)^2$, which can be made arbitrarily close to 0, given that $\varepsilon > 0$ is arbitrary. Hence, we obtain that $\frac{|\tilde{T}_k|}{|T_k|} \rightarrow 0$ as $n \rightarrow \infty$, as was to be proved.

Let us now move to the other part of Theorem 7. We aim to show that there exists a selection of BE that is asymptotically teacher-efficient, asymptotically school-efficient and asymptotically stable. Note that, in our environment, asymptotic school-efficiency implies asymptotic stability. Hence, the following proposition is sufficient for this purpose.

**Proposition 10** There is a mechanism $\varphi$ that is a selection of the BE algorithm such that, for any $k$ and any $\varepsilon > 0$, we have

$$\frac{|\tilde{T}_k|}{|T_k|} \rightarrow 1 \quad \text{and} \quad \frac{|\tilde{S}_k|}{|S_k|} \rightarrow 1$$

where $\tilde{T}_k := \{ t \in T_k \mid U_t(\varphi(t)) \geq u_k + 1 - \varepsilon \}$ and $\tilde{S}_k := \{ s \in S_k \mid V_s(\varphi(s)) \geq 1 - \varepsilon \}$.

**Proof of Proposition 10.** Fix $\varepsilon > 0$. We show that there exists a 2-IR mechanism $\psi$ s.t. for each $k = 1, \ldots, K$, it matches each teacher $t \in T_k$ to a school in $S_k$ and for each $\delta > 0$:

$$\Pr\left\{ \frac{|\{ t \in T_k \mid \xi_{t\psi(t)}(t) \geq 1 - \varepsilon \}|}{|T_k|} > 1 - \delta \right\} \rightarrow 1$$

and

$$\Pr\left\{ \frac{|\{ s \in S_k \mid \eta_{\psi(s),s} \geq 1 - \varepsilon \}|}{|S_k|} > 1 - \delta \right\} \rightarrow 1$$

as $n \rightarrow \infty$ where we recall that $T_k := \mu_0(S_k)$. This turns out to be enough for our purposes. Indeed, consider the matching mechanism given by $\varphi := BE \circ \psi$ (i.e., the mechanism that runs BE on top of the assignment found by mechanism $\psi$). Since $\psi$ is 2-IR, so is $\varphi$. Hence, by construction, this must be a selection of BE that satisfies

$$\frac{|\tilde{T}_k|}{|T_k|} \rightarrow 1 \quad \text{and} \quad \frac{|\tilde{S}_k|}{|S_k|} \rightarrow 1$$
as $n \to \infty$.

Fix $k = 1, \ldots, K$. Fix $\varepsilon_0 \in (0, \varepsilon)$. Further assume that $\varepsilon_0$ is small enough so that $(1 - \varepsilon_0)^2 > 1 - \delta$. Consider the set of pairs $(t, s) \in T_k \times S_k$ such that $s = \mu_0(t)$ and either $t$ ranks $s$ within his $\varepsilon_0|S_k|$ most favorite schools in $S_k$ or $s$ ranks $t$ within his $\varepsilon_0|T_k|$ most favorite teachers in $T_k$. We eliminate these pairs from $T_k \times S_k$. Observing that the remaining set is a product set, we denote it by $T_k^0 \times S_k^0$. Note that, for each pair $(t, s) \in T_k \times S_k$ such that $s = \mu_0(t)$, there is a probability $(1 - \varepsilon_0)^2$ that both $t$ ranks $s$ outside his $\varepsilon_0|S_k|$ most favorite schools in $S_k$ and $s$ ranks $t$ outside his $\varepsilon_0|T_k|$ most favorite teachers in $T_k$. Let us call this event $E_{ts}$. For each such $(t, s)$ where $s = \mu_0(t)$, we denote $1_{ts}$ for the indicator function, which takes a value 1 if the event $E_{ts}$ is true and 0 otherwise. Hence, $|T_k^0| = \sum_{(t, s) \in T_k \times S_k: s = \mu_0(t)} 1_{ts}$. Thus, $|T_k^0|(= |S_k^0|)$ follows a Binomial distribution $\text{Bin}(|T_k|, (1 - \varepsilon_0)^2)$. By the law of large numbers, $\frac{|T_k^0|}{|T_k|} \to (1 - \varepsilon_0)^2$, which, by assumption, is strictly greater than $1 - \delta$. This proves that

$$\Pr \left\{ \frac{|T_k^0|}{|T_k|} \geq 1 - \delta \right\} \to 1$$

and

$$\Pr \left\{ \frac{|S_k^0|}{|S_k|} \geq 1 - \delta \right\} \to 1.$$

In the sequel, we condition w.r.t. a realization of the random set $T_k^0 \times S_k^0$ assuming that both $\frac{|T_k^0|}{|T_k|}$ and $\frac{|S_k^0|}{|S_k|}$ are greater than $1 - \delta$. Now, fix $\varepsilon'_0 > 0$ and note that, conditional on this, each teacher $t \in T_k^0$ draws randomly in $S_k^0$ his $\varepsilon'_0|S_k^0|$ most favorite schools in $S_k^0$. Similarly, each school $s \in S_k^0$ draws randomly in $T_k^0$ its $\varepsilon'_0|T_k^0|$ most favorite teachers in $T_k^0$. We build a random bipartite graph on $T_k^0 \cup S_k^0$ where the edge $(t, s) \in T_k^0 \times S_k^0$ is added if and only if $t$ ranks $s$ within his $\varepsilon'_0|S_k^0|$ most favorite schools in $S_k^0$ and, similarly, $s$ ranks $t$ within its $\varepsilon'_0|T_k^0|$ most favorite teachers in $T_k^0$. This random bipartite graph can be seen as a mapping from the set of ordinal preferences into the set of bipartite graph $G_b(|T_k^0|)$. We denote this random graph by $\tilde{G}_b$. While Lemma 10 does not apply directly to this type of random graph, we will claim below that this random graph has a perfect matching with probability approaching one as the market grows. Before stating and proving this result, we must define the following lemma.

**Lemma 12** With probability approaching one, for any teacher $t \in T_k^0$, any school $s \in S_k^0$ with which $\xi_{ts} \geq 1 - \frac{\varepsilon'_0}{2}$ must be within his $\varepsilon'_0|S_k^0|$ most favorite schools in $S_k^0$. Similarly, with probability approaching one, for any school $s \in S_k^0$, any teacher $t \in T_k^0$, with whom $\eta_{ts} \geq 1 - \frac{\varepsilon'_0}{2}$ must be within his $\varepsilon'_0|T_k^0|$ most favorite teachers in $T_k^0$.

**Proof.** We prove the first part of the statement, and the other part follows the same argument. Fix $t \in T_k^0$ and let $E_t$ be the event that any school $s \in S_k^0$ with which $\xi_{ts} \geq 1 - \frac{\varepsilon'_0}{2}$
must be within his $\varepsilon'_0|S^0_k|$ most favorite schools in $S^0_k$. Let $X_t := \sum_{s \in S^0_k} 1_{\{\xi_{ts} \geq 1 - \frac{\varepsilon'_0}{2}\}}$ be the number of schools in $S^0_k$ with which teacher $t$ enjoys an idiosyncratic payoff greater than $1 - \frac{\varepsilon'_0}{2}$. Observe that $X_t$ follows a Binomial distribution $B(|S^0_k|, \frac{\varepsilon'_0}{2})$ (recall that $\xi_{ts}$ follows a uniform distribution with support $[0, 1]$) and that $X_t \leq \varepsilon'_0|S^0_k|$ implies that $E_t$ is true. Hence, we have to prove that $\Pr\{\exists t \in T^0_k: X_t > \varepsilon'_0|S^0_k|\} \to 0$ as $n \to \infty$. In the sequel, we let $Y_t$ be a Binomial distribution $B(|S^0_k|, 1 - \frac{\varepsilon'_0}{2})$, we have

$$
\Pr\{\exists t \in T^0_k: X_t > \varepsilon'_0|S^0_k|\} \leq |T^0_k| \Pr\{X_t > \varepsilon'_0|S^0_k|\} = |T^0_k| \Pr\{Y_t \leq (1 - \varepsilon'_0)|S^0_k|\} \leq |T^0_k| \exp\left\{-2|S^0_k|(\frac{\varepsilon'_0}{2})^2\right\} \to 0
$$

as $n \to \infty$, where the first inequality is by the union bound and the last one uses Hoeffding inequality. The limit result uses the fact that under our conditioning event, $|T^0_k| = |S^0_k| \geq (1 - \delta)|S_k| \to \infty$. 

We now move to our statement on the existence of perfect matching in $\tilde{G}_b$.

**Lemma 13** With probability going to 1 as $n \to \infty$, the realization of $\tilde{G}_b$ has a perfect matching.

**Proof.** In our random environment, the state space, $\Omega$, can be considered as the set of all possible profiles of idiosyncratic shocks for teachers and schools, i.e., the space of all $\{(\xi_{ts})_{ts}, (\eta_{ts})_{ts}\}$. We denote by $\omega$ a typical element of that set. Let $E$ be the event under which, for each $(t, s) \in T^0_k \times S^0_k: \xi_{ts} \geq 1 - \frac{\varepsilon'_0}{2}$ and $\eta_{ts} \geq 1 - \frac{\varepsilon'_0}{2}$ imply that both $t$ ranks $s$ within his $\varepsilon'_0|S^0_k|$ most favorite schools in $S^0_k$ and $s$ ranks $t$ within his $\varepsilon'_0|T^0_k|$ most favorite teachers in $T^0_k$. By Lemma 12, $\Pr(E) \to 1$. Now, let us build the following random graph on $T^0_k \cup S^0_k$ where, this time, the edge $(t, s) \in T^0_k \times S^0_k$ is added if and only if $\xi_{ts} \geq 1 - \frac{\varepsilon'_0}{2}$ and $\eta_{ts} \geq 1 - \frac{\varepsilon'_0}{2}$. Let us call this graph $\tilde{G}'_b$. Therefore, this time, $\tilde{G}'_b$ can be viewed as a mapping from the set of cardinal preferences to the set of bipartite graph $G_b(|T^0_k|)$. Let $F$ be the event that the realization of $\tilde{G}'_b$ has perfect matching. By Lemma 10, $\Pr(F) \to 1$. By definition, $E \cap F \subset \Omega$. Let us consider the set of all possible profiles of teachers and schools’ ordinal preferences $\succ$ induced by states $E \cap F$, and let us denote this set by $\mathcal{P}$. Clearly, $\Pr(\mathcal{P}) \geq \Pr(E \cap F) \to 1$. Now, for each profile of preferences $\succ$ in $\mathcal{P}$, let $\tilde{G}_b(\succ)$ be the graph corresponding to $\tilde{G}'_b$ when $\succ$ is the profile of realized preferences. We claim that, for any $\succ \in \mathcal{P}$, $\tilde{G}_b(\succ)$ has a perfect matching. Indeed, let $\omega \in E \cap F$ be one state that induces $\succ$ (this is well defined by the construction of $\mathcal{P}$). Because $\omega \in F$, the realization of $\tilde{G}'_b$ at profile $\omega$ has a perfect matching. In addition, because $\omega \in E$, the realization of $\tilde{G}'_b$ at profile $\omega$ is a subgraph of $\tilde{G}_b(\succ)$. We conclude that $\tilde{G}_b(\succ)$ has a perfect matching. Combining this result with the observation that $\Pr(\mathcal{P}) \to 1$, we get

$$
\Pr\{\exists \text{ a perfect matching in } \tilde{G}_b\} \to 1
$$
as \( n \to \infty \), as claimed. 

Now, we build the mechanism \( \psi \) as follows. For each realization of ordinal preferences (for each \( k \in \{1, \ldots, K\} \)), we build a graph on \( T_k^0 \cup S_k^0 \) as defined above, i.e., where the edge \((t, s) \in T_k^0 \times S_k^0 \) is added if and only if \( t \) ranks \( s \) within his \( \varepsilon_0' |S_k^0| \) most favorite schools in \( S_k^0 \) and, similarly, \( s \) ranks \( t \) within its \( \varepsilon_0' |T_k^0| \) most favorite teachers in \( T_k^0 \). If there is perfect matching, then under \( \psi \), teachers in \( T_k^0 \) are matched according to this perfect matching, while teachers in \( T_k^0 \) remain at their initial assignments. If there is no perfect matching, then under \( \psi \), all teachers in \( T_k \) remain at their initial assignments. Assuming that \( \varepsilon_0' + \delta < \varepsilon_0 \), we obtain that the mechanism built in that way is 2-IR.\(^{55}\) To see this, consider a teacher \( t \) who is not matched to his initial school. This means that \( t \) is matched to a school \( s \) given by a perfect matching of the random bipartite graph. By construction, this means that \( t \) ranks \( s \) within his \( \varepsilon_0' |S_k^0| \) most favorite schools in \( S_k^0 \). Hence, \( s \) is within his \( \varepsilon_0' |S_k^0| + \delta |S_k| \) most favorite schools in \( S_k \). Since \( \varepsilon_0' |S_k^0| + \delta |S_k| \leq (\varepsilon_0' + \delta) |S_k| < \varepsilon_0 |S_k| \) and because \( t \in T_k^0 \) implies that \( \mu_0(t) \) is not within \( t \)'s \( \varepsilon_0 |S_k| \) most favorite schools in \( S_k \), we obtain that \( s \) is preferred by \( t \) to his initial assignment. Since a similar reasoning holds for schools, we obtain that \( \psi \) is 2-IR.

As we have shown, with probability approaching one, our bipartite graph actually has a perfect matching. Obviously, this perfect matching ensures that all teachers in \( T_k^0 \) and all schools in \( S_k^0 \) are matched to a partner within their \( \varepsilon_0' |S_k^0| \) favorite. This holds for any realization of the random set \( T_k^0 \times S_k^0 \) such that \( \frac{|T_k^0|}{|T_k|} \) and \( \frac{|S_k^0|}{|S_k|} \) being greater than \( 1 - \delta \). Thus, it holds conditional on the random sets \( \frac{|T_k^0|}{|T_k|} \) and \( \frac{|S_k^0|}{|S_k|} \) being greater than \( 1 - \delta \). Hence, this perfect matching ensures that all teachers in \( T_k^0 \) and all schools in \( S_k^0 \) are matched to a partner within their \( (\varepsilon_0' + \delta) |S_k| \) favorite in \( S_k \) and \( T_k \), respectively. Hence, under our conditioning event that the random sets \( \frac{|T_k^0|}{|T_k|} \) and \( \frac{|S_k^0|}{|S_k|} \) are greater than \( 1 - \delta \),

\[
\Pr \left\{ \frac{|\{ t \in T_k | \psi(t) \text{ is within the } (\varepsilon_0' + \delta) |S_k| \text{ most favorite school in } S_k \}|}{|T_k|} > 1 - \delta \right\} \to 1
\]

and

\[
\Pr \left\{ \frac{|\{ s \in S_k | \psi(s) \text{ is within the } (\varepsilon_0' + \delta) |S_k| \text{ most favorite teacher in } T_k \}|}{|S_k|} > 1 - \delta \right\} \to 1
\]

Given that the conditioning event has a probability approaching 1 as \( n \to \infty \), this is even true without conditioning.

Now, without loss of generality, let us assume that \( \delta \) is small enough so that \( \varepsilon_0' + \delta < \varepsilon \). It remains to show that these \( (\varepsilon_0' + \delta) |S_k| \) favorite partners in \( S_k \) (resp. \( T_k \)) yield an idiosyncratic payoff greater than \( 1 - \varepsilon \). The following lemma completes the argument.

\(^{55}\)This is without loss of generality because, if \( \Pr \left\{ \frac{|\{ t \in T_k | \mathbb{1}_{T \cap T_k} \geq 1 - \varepsilon \}|}{|T_k|} > 1 - \delta \right\} \to 1 \) then,

\( \Pr \left\{ \frac{|\{ t \in T_k | \mathbb{1}_{T \cap T_k} \geq 1 - \varepsilon \}|}{|T_k|} > 1 - \delta' \right\} \to 1 \) for any \( \delta' > \delta \).
Lemma 14 With probability approaching 1 as \( n \to \infty \), the \((\varepsilon_0' + \delta) |S_k|\) most favorite schools of each teacher in \( T_k \) yield an idiosyncratic payoff higher than \( 1 - \varepsilon \) and the \((\varepsilon_0' + \delta) |T_k|\) most favorite teachers of each school in \( S_k \) yield an idiosyncratic payoff higher than \( 1 - \varepsilon \).

Proof. We show that with probability going to 1 as \( n \to \infty \), the \((\varepsilon_0' + \delta) |S_k|\) most favorite schools of each teacher in \( T_k \) yield an idiosyncratic payoff higher than \( 1 - \varepsilon \). The other part of the statement is proved in the same way. For each \( t \in T_k \), let \( Z_t \) be the number of schools \( s \) in \( S_k \) for which \( \xi_{ts} \geq 1 - \varepsilon \). Note that if \( Z_t > (\varepsilon_0' + \delta) |S_k| \) then \( t \)'s \((\varepsilon_0' + \delta) |S_k|\) first schools in \( S_k \) must yield an idiosyncratic payoff higher than \( 1 - \varepsilon \). Thus, it is enough to show that

\[
\Pr\{ \exists t \in T_k \text{ with } Z_t \leq (\varepsilon_0' + \delta) |S_k| \} \to 0
\]
as \( n \to \infty \). Observe that \( Z_t \) follows a binomial distribution \( B(|S_k|, \varepsilon) \) (recall that \( \xi_{ts} \) follows a uniform distribution with support \([0, 1]\)). Hence,

\[
\Pr\{ \exists t \in T_k \text{ with } Z_t \leq (\varepsilon_0' + \delta) |S_k| \} \leq \sum_{t \in T_k} \Pr\{ Z_t \leq (\varepsilon_0' + \delta) |S_k| \} = |T_k| \Pr\{ Z_t \leq (\varepsilon_0' + \delta) |S_k| \} \leq |T_k| \frac{1}{2} \exp \left( -2 \frac{|S_k| |\varepsilon - (\varepsilon_0' + \delta) |S_k| |^2}{|S_k|} \right) = \frac{|T_k|}{2} \exp \left( 2 (\varepsilon - (\varepsilon_0' + \delta))^2 |S_k| \right) \to 0
\]
where the first inequality is by the union bound, while the second equality is by Hoeffding’s inequality. \( \blacksquare \)

F.3 Proof of Theorem 8

Recall that \( T_k \) stands for \( \mu_0(S_k) \), where \( \mu_0 \) is the initial allocation. We will prove the following result.

Proposition 11 Fix any \( k \) and any \( \varepsilon > 0 \). Let \( \bar{T}_k := \{ t \in T_k | U_t(\text{TO-BE}(t)) \geq u_k + 1 - \varepsilon \} \). We have

\[
\frac{|\bar{T}_k|}{|T_k|} \overset{p}{\to} 1.
\]

Proof of Proposition 11. Recall that TO-BE is in the two-sided core. In particular, this implies that there is no pair of teachers \( t \) and \( t' \) so that \( \mu_0(t') \succeq_t \text{TO-BE}(t) \), \( \mu_0(t) \succeq \text{TO-BE}(t') \) (with a strict preference for either \( t \) or \( t' \)), \( t' \succeq_{\mu_0(t)} t \) and \( t \succeq_{\mu_0(t')} t' \). Fix an arbitrary \( k \) and let \( E \) be the event that the fraction of schools \( s \in S_k \) s.t. \( \eta_{\mu_0(s)} \leq 1 - \delta \) is greater than \( 1 - 2\delta \) where \( \delta \in (0, 1) \). By the law of large numbers, we have

\[
\frac{1}{|S_k|} \sum_{s \in S_k} 1_{\{ \eta_{\mu_0(s)} \leq 1 - \delta \}} \overset{p}{\to} 1 - \delta.
\]
Thus, \( \Pr(E) \rightarrow 1 \). Let \( T^0_k := \{ t \in T_k \mid \eta_{t\mu_0(t)} \leq 1 - \delta \} \).

In the sequel, we condition on event \( E \) and we fix a realization of \( \{ \eta_{\mu_0(s)} \}_{s \in S} \) compatible with \( E \). Observe that \( T^0_k \) is non-random once this has been fixed and that, conditional on these, individuals’ preferences are still drawn according to the same distribution (as in the unconditional case) and for \( t \neq \mu_0(s) \), \( \eta_{t\epsilon_s} \) is also still drawn according to the same distribution. We further observe that, because that event \( E \) holds, \( |T^0_k| \geq 1 - 2\delta \) and hence \( |T^0_k| \) approaches infinity as \( n \rightarrow \infty \). We define a random graph with \( \{(t, \mu_0(t))\}_{t \in T^0_k} \) as the set of vertices. An edge between \((t, \mu_0(t))\) and \((t', \mu_0(t'))\) is added if and only if \( \xi_{t\mu_0(t')} > 1 - \varepsilon \) and \( \xi_{t'\mu_0(t)} > 1 - \varepsilon \) and \( \eta', \mu_0(t) \geq \eta_{t\mu_0(t)} \) and \( \eta_{t'\mu_0(t')} \geq \eta_{t'\mu_0(t')} \).

Then, in the random graph, each edge between \((t, \mu_0(t))\) and \((t', \mu_0(t'))\) is added independently with a probability of at least \( \varepsilon^2 \delta^2 \in (0, 1) \).

Now, let \( T^0_k := \{ t \in T^0_k \mid U_t(\text{TO-BE}(t)) \leq u_k + 1 - \varepsilon \} \). It must be that \( T^0_k \) is an independent set, or else, if there is an edge \((t, t') \in T^0_k \times T^0_k \) for some realization of the random graph, then

\[
U_t(\mu_0(t')) > u_k + 1 - \varepsilon \geq U_t(\text{TO-BE}(t)) \quad \text{and} \quad U_{t'}(\mu_0(t)) > u_k + 1 - \varepsilon \geq U_{t'}(\text{TO-BE}(t')).
\]

In addition, \( V_{\mu_0(t')}(t') = \eta_{t'\mu_0(t)} \geq \eta_{t\mu_0(t)} = V_{\mu_0(t)}(t) \) and \( V_{\mu_0(t)}(t') = \eta_{t\mu_0(t')} \geq \eta_{t'\mu_0(t')} = V_{\mu_0(t')}(t') \) and therefore TO-BE is blocked by a coalition of size two, a contradiction. Now, we can use Lemma 11 to obtain that \( \Pr\left\{ \left| T^0_k \right| \geq \frac{2 \log(|T^0_k|)}{\log \frac{1}{\varepsilon^2 \delta^2}} \right\} \rightarrow 0 \) as \( n \rightarrow \infty \) and thus \( \frac{\left| T^0_k \right|}{\left| T^0_k \right|} \rightarrow 0 \) as \( n \rightarrow \infty \).

Now, since \( T^0_k = T^0_k \cup \{ t \in T_k \setminus T^0_k \mid U_t(\text{TO-BE}(t)) \leq u_k + 1 - \varepsilon \} \), we must have

\[
\frac{\left| T^0_k \right|}{\left| T_k \right|} \leq \frac{\left| T^0_k \right| + \left| T_k \setminus T^0_k \right|}{\left| T_k \right|} \leq \frac{\left| T^0_k \right|}{\left| T_k \right|} + 2\delta
\]

Hence, given that \( \frac{\left| T^0_k \right|}{\left| T^0_k \right|} \rightarrow 0 \), we must have that, with probability approaching 1 as \( n \) approaches infinity, \( \frac{\left| T^0_k \right|}{\left| T_k \right|} \leq 3\delta \) and so \( \frac{\left| T^0_k \right|}{\left| T_k \right|} \geq 1 - 3\delta \).

To recap, given event \( E \) and any realization of \( \{ \eta_{\mu_0(s)} \}_{s \in S} \), we have \( \frac{\left| T^0_k \right|}{\left| T^0_k \right|} \geq 1 - 3\delta \) with probability approaching 1 as \( n \rightarrow \infty \). Since the realization of \( \{ \eta_{\mu_0(s)} \}_{s \in S} \) is arbitrary, we obtain that, given event \( E \), \( \frac{\left| T^0_k \right|}{\left| T^0_k \right|} \geq 1 - 3\delta \) with probability approaching 1 as \( n \rightarrow \infty \). Since \( \Pr(E) \rightarrow 1 \) as \( n \rightarrow \infty \), we obtain that \( \frac{\left| T^0_k \right|}{\left| T^0_k \right|} \geq 1 - 3\delta \) with probability approaching 1 as \( n \rightarrow \infty \). Since \( \delta > 0 \) is arbitrarily small, we obtain \( \frac{\left| T^0_k \right|}{\left| T^0_k \right|} \rightarrow 1 \) as \( n \rightarrow \infty \), as claimed.

Remark 2 The statement is related to that of Che and Tercieux (2015b) in Theorem 1. However, since TO-BE is not Pareto-efficient, their proof/argument does not apply.

Remark 3 The argument relies on the fact that TO-BE is not blocked by any coalition of size 2. Hence, the result applies beyond the TO-BE mechanism and applies to any mechanism that cannot be blocked by any coalition of size 2.
G Many-to-one Extensions

We provide below the extensions of BE and 1S-BE to the many-to-one framework. Now, each school may have multiple seats. As before, we assume that all the teachers are initially matched to a school and that all seats are initially occupied by a teacher. As before, let $\mu_0$ be the initial matching.

The Block Exchange Algorithm

The main difference is that, now, blocking with a school does not necessarily mean that a teacher is preferred to a given matched teacher in this school. To maintain the principle of not hurting any school, we must allow a node to point to another one only if the teacher of the former is preferred to the teacher of the latter by the corresponding school.

- **Step 0**: set $\mu(0) := \mu_0$.
- **Step $k \geq 1$**: Given $\mu(k - 1)$, let the teachers and their assignments stand for the vertices of a directed graph where, for each pair of nodes $(t, s)$ and $(t', s')$, there is an edge $(t, s) \rightarrow (t', s')$ if and only if teacher $t$ has a justified envy against teacher $t'$ at school $s'$, i.e., he prefers $s'$ to its match $s$ and is preferred by $s'$ to $t'$. If there is no cycle, then set $\mu(k - 1)$ as the outcome of the algorithm. Otherwise, select a cycle in this directed graph. For each edge $(t, s) \rightarrow (t', s')$ in the cycle, assign teacher $t$ to school $s'$. Let $\mu(k)$ be the matching so obtained. Go to step $k + 1$.

The Teacher-Optimal Block Exchange Algorithm

In the following lines, we define a class of mechanisms that are all selections of the BE algorithm and are strategy-proof. They all reduce to the TO-BE mechanism (as defined in the main text) in the one-to-one environment.

Given a matching $\mu$ and a set of school $S' \subseteq S$, we let $\text{Opp}(t, \mu, S') := \{ s \in S' | t \succeq_s t' \text{ for some } t' \in \mu(s) \}$ be the opportunity set of teacher $t$ within schools in $S'$. Note that for each teacher $t$, if $\mu_0(t) \in S'$, then $\text{Opp}(t, \mu_0, S') \neq \emptyset$ since $\mu_0(t) \in \text{Opp}(t, \mu_0, S')$.

Now, fix an ordering over teachers $f : \{1, \ldots, |T|\} \rightarrow T$, which will be the index for our class of mechanisms.

- **Step 0**: Set $\mu(0) = \mu_0$, $T(0) := T$ and $S(0) := S$.
- **Step $k \geq 1$**: Given $T(k - 1)$ and $S(k - 1)$, let the teachers in $T(k - 1)$ and their assignments stand for the vertices of a directed graph where, for each pair of nodes $(t, s)$ and $(t', s')$, there is an edge $(t, s) \rightarrow (t', s')$ if and only if teacher $t$ ranks school $s'$ first in his opportunity set $\text{Opp}(t, \mu(k - 1), S(k - 1)) = \text{Opp}(t, \mu_0, S(k - 1))$, teacher $t'$ has a lower priority than teacher $t$ at school $s'$ and teacher $t'$ has the lowest ordering according
to \( f \) among all teachers forming a pair with school \( s' \) and having a lower priority than \( t \) at \( s \) (i.e., \( f(t') \leq f(t'') \) for all \( t'' \) such that \( \mu(k-1)(t'') = s' \) and \( t \unlhd_s t'' \)). The directed graph so obtained is a directed graph with out-degree one and, as such, has at least one cycle; cycles are pairwise disjoint. For each edge \((t, s) \rightarrow (t', s')\) in a cycle, assign teacher \( t \) to school \( s' \). Let \( \mu(k) \) be the assignment obtained and \( T(k) \) be the set of teachers who are not part of any cycle at the current step. If \( T(k) \) is empty, then set \( \mu(k) \) as the outcome of the algorithm. Otherwise, go to step \( k + 1 \).

Remark 4 This class of mechanisms is still tightly connected to the top trading cycle mechanism. To see this, fix an ordering \( f \) and assume first that each teacher ranks schools outside his opportunity set below his initial assignment. Now, for each teacher, define preferences over pairs \( \{(t, \mu_0(t))\}_{t \in T} \) in the following way: for \( s \neq s' \), \((t, s)\) is strictly preferred to \((t', s')\) if and only if \( s \) is strictly preferred to \( s' \); in addition, \((t, s)\) is strictly preferred to \((t', s)\) if and only if \( f(t) < f(t') \). We can consider this modified environment as a one-to-one environment where agents’ preferences are strict. Top trading cycles is well-defined in this environment and coincides with the outcome of TO-BE (with the ordering \( f \)) defined in the previous paragraph.

The 1-Sided Block Exchange Algorithm

In order to keep the property that the graph associated with 1S-BE is a supergraph of that of BE, we build on the previous generalization of BE to define the extension of 1S-BE.

- **Step 0**: set \( \mu(0) := \mu_0 \).

- **Step \( k \geq 1 \)**: Given \( \mu(k-1) \), let the teachers and their assignments stand for the vertices of a directed graph where, for each pair of nodes \((t, s)\) and \((t', s')\), there is an edge \((t, s) \rightarrow (t', s')\) if and only if either (1) teacher \( t \) has a justified envy toward \( t' \) at \( s' \); or (2) \( t \) desires \( s' \) and \( t \) is ranked higher by \( s' \) than each teacher who both desires \( s' \) and does not block with \( s' \). If there is no cycle, then set \( \mu(k-1) \) as the outcome of the algorithm. Otherwise, select a cycle in this directed graph. For each edge \((t, s) \rightarrow (t', s')\) in the cycle, assign teacher \( t \) to school \( s' \). Let \( \mu(k) \) be the matching so obtained. Go to step \( k + 1 \).

H Assignment Process and Sample Restrictions

For the empirical part of the analysis, we decided not to focus on the second phase of the assignment because reported preferences seem to be less reliable. First, teachers are restricted to ranking up to 20 schools, and it is well known in the literature (Haeringer and Klijn (2009)).

\[^{56}\text{Note that, here, teacher } t \text{ may block with } s' \text{ under condition (2). Thus, it is easy to see that, if (1) is satisfied, then (2) is also satisfied. Hence, one could simplify the definition and suppress condition (1). We keep this definition just to have a parallel with the definition provided in the one-to-one environment.}\]
that this constraint gives rise to strategic reports. Second, and perhaps more importantly, teachers can report “wide wishes” instead of reporting a precise school. A wide wish can be a geographic area such as a city, a group of cities, a department or an entire region. For instance, instead of ranking a school within city $x$, a teacher can report the city $x$ in his ranking. Then, when a city is ranked, the designer is free to assign the teacher to any school within that city. This is a way for teachers to signal their strong preference to be in a city $x$ (irrespective of where they eventually end up in that city). While this may make sense from a design point of view, it makes it more difficult for us to interpret the reported preferences.

In the first phase of assignment, 25,067 teachers participate. We restrict the sample to the 49 subjects containing more than 10 teachers asking for a transfer: this restricts the sample to 20,808 teachers. We also remove from the sample all couples (1,579 teachers) because of the specific treatment they receive in the assignment procedure. Finally, only teachers who have an initial assignment are kept in the sample. The final sample contains 10,579 teachers.

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57 Teachers can rank up to 20 or 30 schools, depending on the region. In regions where they can rank a maximum of 20 schools, 10.79% of the teachers rank 20 schools. In regions where teachers can rank up to 30 schools, the constraint is binding for less than 1% of the teachers.

58 Couples can jointly apply, in which case they have to submit two identical lists of regions to the central administration. A specific treatment is applied to the couple: one of the spouses will not be assigned a region if the other one is not assigned to the same region. To achieve this, the central administration runs the algorithm once and checks the region obtained by each spouse. If they do not obtain the same region, one must have obtained a region that is ranked lower in their common ranking (for instance, rank 5). In that case, the ministry would delete all regions ranked higher than rank 5 from their common list of preferences and run the algorithm again on the modified list. This process is repeated until both spouses obtain the same region. If this does not happen, both spouses stay in their initial region.