

Mechanisms for a No-Regret Agent: Beyond the Common Prior



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For more details, see full paper (arxiv.org/abs/2009.05518).

A High-Level Agenda in Game Theory

Can we replace **prior knowledge with **models of learning**?**

Yes? No-regret assumptions can discipline agents' behavior.

- ▶ E.g. Foster and Vohra (1997)
- ▶ E.g. Nekipelov, Syrgkanis, and Tardos (2015)

No? No-regret algorithms can behave in bizarre ways.

- ▶ E.g. Braverman, Mao, Schneider, and Weinberg (2018).

Can models of learning be adapted to strategic interactions?

This Paper (1/2)

We focus on **Stackelberg games of incomplete information**.

- ▶ Includes contract design, Bayesian persuasion, delegation, etc.

1. Principal decides on a policy, e.g.



or



2. Agent responds to that policy, e.g.



or



3. Payoffs depend on hidden state, e.g.



or



These models usually require **common prior belief** about the state.

- ▶ E.g. 40% chance policeman is at donut shop.

This Paper (2/2)

We replace **common prior** with **adversarial online learning**.

- ▶ Adversarial = no assumptions on the sequence of states.

Principal							
Agent							
State							

We design **low-regret mechanisms** for the principal.

- ▶ Under permissive assumptions on the agent's behavior.
- ▶ We refine no-regret to **counterfactual calibration**.
- ▶ Agent must fully & consistently exploit her **information**.

Agent's Regret

No-regret:

- ▶ In hindsight, agent prefers her algorithm to any fixed action.

Calibration (no-internal-regret):

- ▶ No-regret with past behavior as context.

These restrictions do not rule out pathological behavior.

- ▶ The **adversary** can correlate agent's actions with sequence of states to make it appear as if agent has additional **information**.
- ▶ Informally, can think of an agent that has access to additional data or notices patterns that we missed.

Tortoise travels 1km in 1h : uninformed agent satisfies no-regret.



Hare travels 1km in 1h : informed agent satisfies no-regret.



Hare travels 1km in 2min : informed agent satisfies no-regret
conditioned on her **information**.



Counterfactual Calibration

Information is **revealed** by the agent's **on- and off-path behavior**.

- ▶ **On-path**: agent's behavior under the principal's mechanism.
- ▶ **Off-path**: agent's behavior under **counterfactual** mechanisms.

Counterfactual calibration:

- ▶ No-regret with on- and off-path behavior as context.

Agent must fully & consistently exploit her **revealed information**.

Online Mechanism Design

Principal's regret:

- ▶ How much he prefers the best-in-hindsight fixed policy to his mechanism.
- ▶ Takes into account how changes to mechanism affect agent's behavior.

Goal: design a mechanism that guarantees low **principal's regret**.

- ▶ For any sequence of states.
- ▶ For any **counterfactually-calibrated** behavior by the agent.

Ideally, we seek empirical analogs to the **common prior** policies.

Main Results (1/2)

Reduce **online problem** to robust version of **common prior** problem.

- ▶ **Local robustness**: agent nearly maximizes expected utility.

Theorem (Informal)

Assume: agent's behavior is **counterfactually calibrated**.

Assume: agent isn't better informed than us (**non-negative regret**).

Mechanism: use the **locally-robust policy**, replacing the **common prior** with a **calibrated forecast**.

Result: principal's regret vanishes.

Main Results (2/2)

Reduce **online problem** to robust version of **common prior** problem.

- ▶ **Local robustness**: agent nearly maximizes expected utility.
- ▶ **Informational robustness**: agent receives a private signal, but we do not know its quality.

Theorem (Informal)

Assume: agent's behavior is **counterfactually calibrated**.

Mechanism: use the **locally-** and **informationally-robust policy**, replacing the **common prior** with a **calibrated forecast**.

Result: principal's regret \leq **cost of informational robustness**.

Conclusion

We replaced the common prior with online learning.

- ▶ For rich class of single-agent mechanism design problems.
- ▶ Counterfactual calibration \approx non-Bayesian rationality.
- ▶ If the agent reveals useful information on one path, she must also exploit it on other paths.

Many open problems, e.g.

- ▶ Extension to bandit feedback – conceptually non-trivial!
- ▶ Mechanisms that learn about the agent's information.
- ▶ Computational tractability.

Thank you!

For more details, see full paper (arxiv.org/abs/2009.05518).